

(6.26)

$$R_x[m] = 10 e^{-\lambda_1 |m|} + 5 e^{-\lambda_2 |m|} \quad 0 < \lambda_1, \lambda_2 < \infty$$

$$S_x(\omega) = \sum_{m=-\infty}^{+\infty} R_x[m] e^{-j\omega m}$$

$$= \sum_{m=-\infty}^{+\infty} 10 e^{-\lambda_1 |m|} e^{-j\omega m} + \sum_{m=-\infty}^{+\infty} 5 e^{-\lambda_2 |m|} e^{-j\omega m}$$

$$= 10 \sum_{m=0}^{\infty} e^{-\lambda_1 m} e^{-j\omega m} + 10 \sum_{m=-\infty}^{-1} e^{+\lambda_1 m} e^{-j\omega m}$$

$$+ 5 \sum_{m=0}^{\infty} e^{-\lambda_2 m} e^{-j\omega m} + 5 \sum_{m=-\infty}^{-1} e^{+\lambda_2 m} e^{-j\omega m}$$

$$= 10 \sum_{m=0}^{\infty} e^{-(\lambda_1 + j\omega)m} + 10 \sum_{m=0}^{\infty} e^{-(\lambda_1 - j\omega)m} - 10$$

$$+ 5 \sum_{m=0}^{\infty} e^{-(\lambda_2 + j\omega)m} + 5 \sum_{m=0}^{\infty} e^{-(\lambda_2 - j\omega)m} - 5$$

$$= \frac{10}{1 - e^{-(\lambda_1 + j\omega)}} + \frac{10}{1 - e^{-(\lambda_1 - j\omega)}} + \frac{5}{1 - e^{-(\lambda_2 + j\omega)}} + \frac{5}{1 - e^{-(\lambda_2 - j\omega)}} - 15,$$

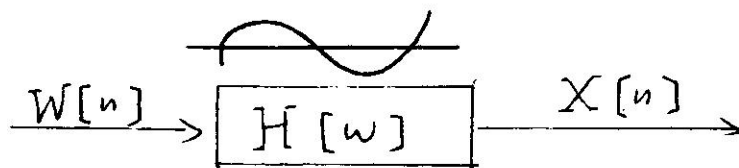
$$= 10 \frac{1 - e^{-2\lambda_1}}{1 - 2\cos\omega e^{-\lambda_1} + e^{-2\lambda_1}} + 5 \frac{1 - e^{-2\lambda_2}}{1 - 2\cos\omega e^{-\lambda_2} + e^{-2\lambda_2}}$$

$$= 10 \left(\frac{1 - f_1^2}{1 + f_1^2 - 2f_1 \cos\omega} \right)$$

with
 $f_i \triangleq e^{-\lambda_i}$
 $i=1,2.$

$$+ 5 \left(\frac{1 - f_2^2}{1 + f_2^2 - 2f_2 \cos\omega} \right)$$

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$\mu_w[n] = 0$, $K_w[m] = \delta[m]$, we know;

$$X[n] = \sum_{K=-\infty}^{+\infty} h[K] W[n-K] = \sum_{K=-\infty}^{+\infty} h[n-K] W[K]$$

$$\text{and } R_{ww}[n] = E\{W^*[m] W[m+n]\}$$

$$\begin{aligned} R_{xw}[n] &= E\{W^*[m] X[m+n]\} \\ &= E\{W^*[m] \sum_{K=-\infty}^{+\infty} h[K] W[m+n-K]\} \end{aligned}$$

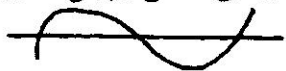
If the Σ converges, then

$$\begin{aligned} R_{xw}[n] &= \sum_{K=-\infty}^{+\infty} h[K] E\{W^*[m] W[m+n-K]\} \\ &= \sum_{K=-\infty}^{+\infty} h[K] R_{ww}[n-K] \end{aligned}$$

OR:

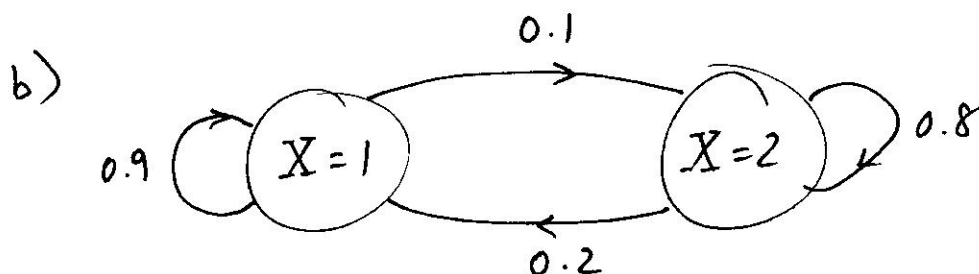
$$\begin{aligned} R_{xw}[n] &= R_{ww}[n] * h[n] \\ &= \delta[n] * h[n] = h[n]. \end{aligned}$$

Therefore similar result holds in the Discrete time case.



6.31 a) Since $\underline{p}[n] = (P[X[n]=1], P[X[n]=2])$

$$\begin{aligned}
 &= (P[X[n-1]=1] P_{11} + P[X[n-1]=2] P_{21}, \\
 &\quad P[X[n-1]=1] P_{12} + P[X[n-1]=2] P_{22}) \\
 &= \underline{p}[n-1] \underline{P} \\
 \Rightarrow \underline{p}[n] &= \underline{p}[0] \underline{P}^n
 \end{aligned}$$



c) Let p be the probability of the first transition to state 2 occurring at time n , given $X[0]=1$.

Then

$$\begin{aligned}
 p &= P_{11}^{n-1} \cdot P_{12} \\
 &= (0.9)^{n-1} (0.1) \\
 &= (0.1) (0.9)^{n-1}
 \end{aligned}$$



7.3


 $B(n)$ is Bernoulli r.s.; Let +1 occur w.p. $\frac{1}{2}$
 $X(t) \triangleq \sqrt{P} \sin(2\pi f_0 t + B[n] \frac{\pi}{2})$ for $nT \leq t < (n+1)T$,
 $\forall n$ and $\sqrt{P}, f_0 \in \mathbb{R}$

$$\begin{aligned}
 (a) \mu_X(t) &\triangleq E[X(t)] = E\left\{\sqrt{P} \sin(2\pi f_0 t + B[n] \frac{\pi}{2})\right\} \\
 &= \sqrt{P} E\left\{\sin(2\pi f_0 t + B[n] \frac{\pi}{2})\right\} \\
 &= \sqrt{P} \left\{ \frac{1}{2} \sin(2\pi f_0 t + \frac{\pi}{2}) + \frac{1}{2} \sin(2\pi f_0 t - \frac{\pi}{2}) \right\} \\
 &= \sqrt{P} \left[\frac{1}{2} (+\cos 2\pi f_0 t) + \frac{1}{2} (-\cos 2\pi f_0 t) \right]
 \end{aligned}$$

$$\mu_X(t) = \sqrt{P} \left(\frac{1}{2} - \frac{1}{2} \right) \cos 2\pi f_0 t = 0.$$

$$(b) K_X(t, s) = E[X(t)X(s)] - E[X(t)]E[X(s)]$$

(i) For $nT \leq t, s < (n+1)T$, i.e., t and s are in the same interval.

$$\begin{aligned} E[X(t)X(s)] &= \frac{1}{2}\sqrt{P}\sin(2\pi f_0 t + \frac{\pi}{2})\sqrt{P}\sin(2\pi f_0 s + \frac{\pi}{2}) \\ &\quad + (1 - \frac{1}{2})P\sin(2\pi f_0 t - \frac{\pi}{2})\sin(2\pi f_0 s - \frac{\pi}{2}) \\ &= \frac{1}{2}P\cos(2\pi f_0 t)\cos(2\pi f_0 s) \\ &\quad + (1 - \frac{1}{2})P\cos(2\pi f_0 t)\cos(2\pi f_0 s) \\ &= P\cos(2\pi f_0 t)\cos(2\pi f_0 s) \end{aligned}$$

$$\Rightarrow K_X(t, s) = P\cos(2\pi f_0 t)\cos(2\pi f_0 s)$$

(ii) For $nT \leq t < (n+1)T, kT \leq s < (k+1)T, k \neq n$, $X(t)$ and $X(s)$ are independent.

$$\begin{aligned} \Rightarrow K_X(t, s) &= E[X(t)X(s)] - E[X(t)]E[X(s)] \\ &= E[X(t)]E[X(s)] - E[X(t)]E[X(s)] \\ &= 0. \end{aligned}$$



7.6

(a) Use property (3) for $t_1 = 0$ and $t_2 = t$
 Then by property (1), $N(0) = 0$. So,

(3) becomes:

$$P[N(t) = n] = \frac{\left[\int_0^t \lambda(\nu) d\nu\right]^n}{n!} e^{-\int_0^t \lambda(\nu) d\nu}; n \geq 0$$

Then, since $N(t)$ is poisson distributed,
 we recognize the mean as

$$\mu_N(t) = \int_0^t \lambda(\nu) d\nu$$

(b) Take $t_2 \geq t_1$ and write

$$E[N(t_2)N(t_1)] = E[(N(t_1) + (N(t_2) - N(t_1)))N(t_1)]$$

Then using the linearity of $E[\]$ and the
 independent increments of property (2),
 we have

$$E[N(t_2)N(t_1)] = E[N^2(t_1)] + E[N(t_2) - N(t_1)] E[N(t_1)]$$

Now, the first term is the second moment
 of a poisson r.v., so

$$E[N^2(t_1)] = \int_0^{t_1} \lambda(\nu) d\nu + \left(\int_0^{t_1} \lambda(\nu) d\nu\right)^2$$

Now

$$E[N(t_2) - N(t_1)] = \int_{t_1}^{t_2} \lambda(\nu) d\nu$$

$$\& \text{ from a) } E[N(t_1)] = \int_0^{t_1} \lambda(\nu) d\nu$$

so

$$\begin{aligned} R_N(t_1, t_2) &= E[N(t_1) N(t_2)] \\ &= \int_0^{t_1} \lambda(\nu) d\nu + \left(\int_0^{t_1} \lambda(\nu) d\nu \right)^2 + \left(\int_{t_1}^{t_2} \lambda(\nu) d\nu \right) \left(\int_0^{t_1} \lambda(\nu) d\nu \right) \\ &= \left(\int_0^{t_1} \lambda(\nu) d\nu \right) \left[1 + \int_0^{t_2} \lambda(\nu) d\nu \right] \quad t_2 > t_1 \end{aligned}$$

$$= \int_0^{\min(t_1, t_2)} \lambda(\nu) d\nu \left[1 + \int_0^{\max(t_1, t_2)} \lambda(\nu) d\nu \right] \quad \text{for all } t_1, t_2.$$

c)

We have to show (1), (2), & (3).

$$(1) \quad N_u(0) \triangleq N(t(0)) = N(0) \triangleq 0 \quad \checkmark$$

(2) Let $\tau_1 \leq \tau_2 \leq \dots \leq \tau_k$, Then since $t(\tau)$ is monotone increasing (since it is integral of positive $\lambda(\nu)$), we have $t_1 \leq t_2 \leq \dots \leq t_k$ where $t_i \triangleq t(\tau_i)$.

Thus $N_u(\tau_i) \triangleq N(t(\tau_i)) = N(t_i)$. So by def.

$N(t_1), N(t_2) - N(t_1), \dots, N(t_k) - N(t_{k-1})$ are jointly indep. But $N_u(\tau_i) - N_u(\tau_{i-1}) = N(t_i) - N(t_{i-1})$, so The $N_u(\tau)$ process has independent increments too!

(3) Since $N_u(\tau_2) - N_u(\tau_1) = N(t_2) - N(t_1)$ with mean value $\int_{t_1}^{t_2} \lambda(\nu) d\nu = \int_0^{t_2} - \int_0^{t_1} = \tau_2 - \tau_1$.

- 7.15 Since W_1 & W_2 are independent Wiener processes, Their difference is still Gaussian. Since the mean of $W_2(t)$ is zero, $-W_2(t)$ still has correlation function $\alpha_2 \min(t_1, t_2)$.
- a) Thus $R_X(t_1, t_2) = (\alpha_1 + \alpha_2) \min(t_1, t_2)$
- b) $f_X(x; t) \sim N(0, (\alpha_1 + \alpha_2)t)$.

7.16 a) $Y(t) = X'(t)$

so $\mu_Y(t) = \frac{d}{dt} \mu_X(t) = \frac{d}{dt} 4 = 0.$

b) Since $\mu_X(t) = 4,$

$$R_Y(t_1, t_2) = \frac{\partial^2}{\partial t_1 \partial t_2} \left[5 \min^2(t_1, t_2) + 4^2 \right]$$

$$= \frac{\partial}{\partial t_1} \left[\frac{\partial}{\partial t_2} (5 \min^2(t_1, t_2)) \right]$$

$$\begin{aligned}
&= \frac{\partial}{\partial t_1} \left[10 \min(t_1, t_2) u(t_1 - t_2) \right] \\
&= 10 \min(t_1, t_2) \delta(t_1 - t_2) \\
&\quad + 10 u(t_2 - t_1) \overset{0}{\delta(t_1 - t_2)}
\end{aligned}$$

$$\begin{aligned}
\text{so } K_Y = R_Y(t_1, t_2) &= 10 \min(t_1, t_2) \delta(t_1 - t_2) \\
&= 10 t_1 \delta(t_1 - t_2) \\
&= 10 t_2 \delta(t_1 - t_2).
\end{aligned}$$

c) (i) $\mu_Y(t) = 0 \quad \checkmark$

$$\begin{aligned}
\text{(i) } R_Y(t+\tau, t) &= (t+\tau) \delta(\tau) \\
&= t \delta(\tau) \quad \text{not WSS!}
\end{aligned}$$

d) One way to get this covariance is to multiply together two independent Wiener processes $W_1(t)$ $W_2(t)$ each with covariance $\min(t_1, t_2)$. Then multiply result by $\sqrt{5}$ and add the value 4.

$$X_c(t) = \sqrt{5} W_1(t) W_2(t)$$

$$\begin{aligned}
\text{Then } K_X(t_1, t_2) &= 5 E[W_1(t_1) W_1(t_2)] E[W_2(t_1) W_2(t_2)] \\
&= 5 \min(t_1, t_2) \cdot \min(t_1, t_2).
\end{aligned}$$

(9)

a) $P[\text{remain in state 2 till time } t \mid X(0)=2], \quad t > 0$

$$= P[\text{no transition to 3}] \cdot P[\text{no trans. to 1}]$$

$$= e^{-\lambda_2 t} e^{-\mu_2 t} = \exp - (\lambda_2 + \mu_2) t$$

$$b) \begin{bmatrix} P_1(t+\Delta t) \\ P_2(t+\Delta t) \\ P_3(t+\Delta t) \end{bmatrix} \approx \begin{bmatrix} 1-\lambda_1 \Delta t & \mu_2 \Delta t & 0 \\ \lambda_1 \Delta t & 1-(\lambda_2+\mu_2) \Delta t & \mu_3 \Delta t \\ 0 & \lambda_2 \Delta t & 1-\mu_3 \Delta t \end{bmatrix} \begin{bmatrix} P_1(t) \\ P_2(t) \\ P_3(t) \end{bmatrix}$$

$$\approx \dot{\underline{P}} = \begin{bmatrix} -\lambda_1 & \mu_2 & 0 \\ \lambda_1 & -(\lambda_2+\mu_2) & \mu_3 \\ 0 & \lambda_2 & -\mu_3 \end{bmatrix} \underline{P}$$

$$c) \text{ In steady state } \dot{\underline{P}} = 0$$

so

$$-\lambda_1 P_1 + \mu_2 P_2 = 0$$

$$\text{and } \lambda_2 P_2 - \mu_3 P_3 = 0.$$

$$\text{Also we know } P_1 + P_2 + P_3 = 1$$

$$\text{so } P_2 = \frac{\lambda_1}{\mu_2} P_1 \quad \& \quad P_3 = \frac{\lambda_2}{\mu_3} P_2$$

$$\text{so } P_1 + P_2 + P_3 = P_1 \left[1 + \frac{\lambda_1}{\mu_2} + \frac{\lambda_2}{\mu_3} \cdot \frac{\lambda_1}{\mu_2} \right] = 1$$

$$\text{so } P_1 = \frac{1}{1 + \frac{\lambda_1}{\mu_2} \left(1 + \frac{\lambda_2}{\mu_3} \right)} =$$

$$P_2 = \frac{\lambda_1 / \mu_2}{1 + \frac{\lambda_1}{\mu_2} \left(1 + \frac{\lambda_2}{\mu_3} \right)}$$

$$\text{and } P_3 = \frac{\frac{\lambda_1}{\mu_2} \cdot \frac{\lambda_2}{\mu_3}}{1 + \frac{\lambda_1}{\mu_2} \left(1 + \frac{\lambda_2}{\mu_3} \right)}$$

(7.29)

$$\begin{aligned}
 \text{'a)} \quad \mu_Y(t) &= E[X(t) + 0.3 X'(t)] \\
 &= \mu_X(t) + 0.3 \mu_X'(t) \\
 &= 5t + 0.3(5) \\
 &= 5t + 1.5 //
 \end{aligned}$$

$$b) \quad K_Y(t_1, t_2) = E[(X_c + .3 X_c')(X_c + .3 X_c')]$$

$$\text{where } X_c \triangleq X - \mu_X$$

so

$$\begin{aligned}
 K_X(t_1, t_2) + 0.3 \frac{\partial K_X(t_1, t_2)}{\partial t_1} + 0.3 \frac{\partial K_X(t_1, t_2)}{\partial t_2} + 0.09 \frac{\partial^2 K_X(t_1, t_2)}{\partial t_1 \partial t_2} \\
 = K_Y(t_1, t_2)
 \end{aligned}$$

$$\text{Now } \frac{\partial K_X(t_1, t_2)}{\partial t_1} = \frac{-\sigma^2 2\alpha (t_1 - t_2)}{(1 + \alpha (t_1 - t_2)^2)^2}$$

$$\begin{aligned}
 \frac{\partial K_X(t_1, t_2)}{\partial t_2} &= \frac{-\sigma^2 2\alpha (t_2 - t_1)}{(1 + \alpha (t_1 - t_2)^2)^2} \\
 &= - \frac{\partial K_X(t_1, t_2)}{\partial t_1}
 \end{aligned}$$

so cross-terms cancel. Thus, with

$$\frac{\partial^2 K_X(t_1, t_2)}{\partial t_1 \partial t_2} = \frac{-6d^2 \sigma^2 (t_1 - t_2)^2 + 2d \sigma^2}{(1 + d(t_1 - t_2)^2)^3}, \text{ we have}$$

$$\text{finally } K_Y(t_1, t_2) = \frac{\sigma^2}{1 + d \tau^2} \left\{ 1 + \frac{-0.54 d^2 \tau^2 + .18 d}{(1 + d \tau^2)^2} \right\} = K_Y(\tau).$$

$\tau = t_1 - t_2.$

7.32 (a) $X(t)$ has constant mean 128.

$$\mu_X(t) = \mu_X H(0) = 128 \times 1 = 128$$

$$(b) K_Y(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |H(\omega)|^2 \cdot S_{X_c}(\omega) e^{j\omega\tau} d\omega$$

$$|H(\omega)|^2 = \frac{1}{1+\omega^2}$$

$$S_{X_c}(\omega) = \int_{-\infty}^{\infty} 1000 e^{-10|\tau|} e^{-j\omega\tau} d\tau$$

$$= 1000 \int_{-\infty}^{\infty} e^{-10|\tau| - j\omega\tau} d\tau$$

(note:
 $X_c \triangleq X - \mu_X$)

$$= 1000 \left[\int_0^{\infty} e^{-10\tau - j\omega\tau} d\tau + \int_{-\infty}^0 e^{10\tau - j\omega\tau} d\tau \right]$$

$$= 1000 \left[\frac{1}{10 + j\omega} + \frac{1}{10 - j\omega} \right]$$

$$= 1000 \frac{20}{100 + \omega^2}$$

$$= \frac{20000}{100 + \omega^2}$$

$$K_Y(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{1+\omega^2} \cdot \frac{20000}{100+\omega^2} e^{j\omega\tau} d\omega$$

$$= \frac{20000}{2\pi \cdot 99} \int_{-\infty}^{\infty} \left[\frac{1}{1+\omega^2} - \frac{1}{100+\omega^2} \right] e^{j\omega\tau} d\omega$$

$$= \frac{20000}{99} \left[\frac{1}{2} e^{-|\tau|} - \frac{1}{20} e^{-10|\tau|} \right]$$

$$= (101.01) e^{-|\tau|} - (10.10) e^{-10|\tau|}$$



7.33 a) $S_Y(\omega) = |H(\omega)|^2 S_X(\omega)$

$$H(\omega) = \frac{1}{4} \int_{-2}^{+2} e^{-j\omega t} dt = \frac{e^{-j\omega 2} - e^{+j\omega 2}}{-j2(2\omega)}$$

$$= \frac{\sin 2\omega}{2\omega}$$

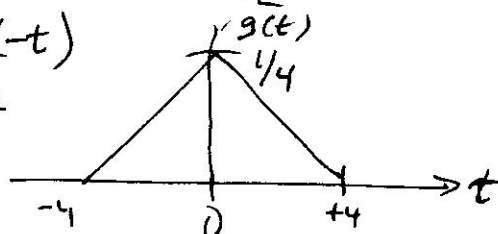
S_X is given as 2.

So $S_Y(\omega) = 2 \left(\frac{\sin 2\omega}{2\omega} \right)^2$.

b) $R_X(\tau) = 2\delta(\tau)$ $h(t) = \frac{1}{4}[u(t+2) - u(t-2)]$

let $g(t) = h(t) * h^*(-t)$
 $= \text{triangle}$

$$g(0) = \frac{1}{4} = \int_{-2}^{+2} h^*(-\tau) h(-\tau) d\tau$$



$Y = h * X$

$$= \frac{1}{4} \cdot \frac{1}{4} \cdot \int_{-2}^{+2} d\tau$$

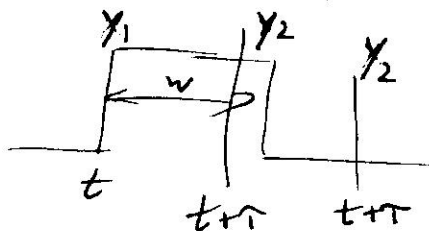
$$= \frac{1}{4} \cdot \frac{1}{4} \cdot 4 \checkmark$$

$$\Rightarrow R_Y(\tau) = \begin{cases} \frac{1}{2} \left(1 - \frac{|\tau|}{4}\right), & |\tau| \leq 4 \\ 0, & |\tau| > 4. \end{cases}$$

7.34

$$R_Y(\tau) = E[Y(t)Y(t+\tau)] = E_W[E[Y(t)Y(t+\tau)|W]]$$

Let $W=w$ & evaluate $E[Y(t)Y(t+\tau)|W=w]$. Since not a function of t , can take t at start of pulse (by WSS on Y)



Now for $\tau < w$ $Y_1 = Y_2$

so $Y_1 Y_2 = Y_1^2$

for $\tau > w$ Y_1, Y_2 with $Y_1 \perp Y_2$

$$E[Y(t)Y(t+\tau)|W=w] = E[Y_1 Y_2] = E[Y_1]E[Y_2] = E^2[Y], \tau > w \\ = E[Y_1^2] = E[Y^2], \tau < w$$

$$\text{so } E[Y(t)Y(t+\tau)|W=w] = \begin{cases} E^2[Y] & \tau > w \\ E[Y^2] & \tau < w \end{cases}$$

so

$$E[E[Y(t)Y(t+\tau)|W]] = E^2[Y] P[W < \tau] + E[Y^2] P[W > \tau]$$

$$\phi \quad E[X] = 0, \quad P[W > \tau] = \int_{\tau}^{\infty} \lambda e^{-\lambda w} dw = e^{-\lambda \tau}$$

$$E[Y^2] = \int_{-\infty}^{+\infty} y^2 f_Y(y) dy = \sigma^2 \quad (E[Y] = 0 \text{ since the process is zero mean})$$

$$\therefore R_Y(\tau) = \sigma^2 e^{-\lambda \tau}, \quad \tau > 0$$

Since $R_Y(\tau)$ must be even in τ , we have

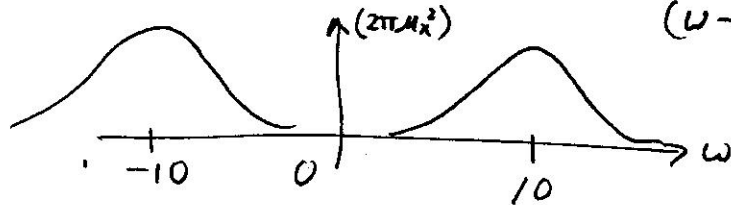
$$R_Y(\tau) = \sigma^2 \exp(-\lambda |\tau|) \quad \text{for } -\infty < \tau < +\infty.$$

$$S_Y(\omega) = \frac{2\lambda\sigma^2}{\omega^2 + \lambda^2} \quad \text{for } -\infty < \omega < +\infty$$

$\tau = 0$, $R_X(0) = \sigma^2$ = mean square value of X , as it should be.

$\tau = \infty$, $R_X(\omega) = 0$ = mean value of the process ^{squared}. Separated elements become uncorrelated.

7.35 a) $S_X(\omega) = 2\pi \mu_X^2 \delta(\omega) + \frac{10}{(\omega-10)^2+4} + \frac{10}{(\omega+10)^2+4}$



$$\left(e^{-a|\omega|} \leftrightarrow \frac{2a}{\omega^2 + a^2} \right)$$

b) $\frac{1}{2\pi} \int_{\omega_1}^{\omega_2} (\cdot) d\omega + \frac{1}{2\pi} \int_{-\omega_2}^{-\omega_1} (\cdot) d\omega$

c) $S_Y(\omega) = S_X(\omega) \cdot |H|^2(\omega)$

with $|H|^2 = \frac{j\omega+4}{(j\omega+6)(j\omega+5)} \cdot \frac{-j\omega+4}{(-j\omega+6)(-j\omega+5)} = \frac{\omega^2+16}{(\omega^2+36)(\omega^2+25)}$

(7.7) Poisson pmf: $P_N(n; t) = \frac{(\int_0^t \lambda(v) dv)^n}{n!} e^{-\int_0^t \lambda(v) dv} u(n)$

a) $\mu_N(t) = E[N(t)] = \int_0^t \lambda(v) dv, \quad t \geq 0.$

$$= \int_0^t (1+2v) dv$$

$$= v + v^2 \Big|_0^t$$

$$= t + t^2, \quad t \geq 0.$$

b) Let $t_2 > t_1 \geq 0$, then

$$N(t_1)N(t_2) = N(t_1) [N(t_1) + (N(t_2) - N(t_1))]$$

so $R_N(t_1, t_2) = E[N^2(t_1)] + \mu_N(t_1) (\mu_N(t_2) - \mu_N(t_1))$

$$E[N^2(t)] = \int_0^t \lambda(v) dv + \left(\int_0^t \lambda(v) dv \right)^2$$

$$= (t + t^2) + (t + t^2)^2$$

so for $t_2 > t_1$,

$$R_N(t_1, t_2) = (t_1 + t_1^2) + (t_1 + t_1^2)^2 + (t_1 + t_1^2) \left(t_2 + t_2^2 - (t_1 + t_1^2) \right)$$

$$= (t_1 + t_1^2) + (t_1 + t_1^2)(t_2 + t_2^2).$$

in general
then

$$R_N(t_1, t_2) = [\min(t_1, t_2) + \min^2(t_1, t_2)] [1 + \max(t_1, t_2) + \max^2(t_1, t_2)]$$

d) Use CLT with $\mu_N = t+t^2$, $\sigma_N^2 = t+t^2$
to yield

$$P \approx \frac{1}{2} + \operatorname{erf}\left(\frac{t^2}{\sqrt{t+t^2}}\right) \sim \frac{1}{2} + \operatorname{erf}(t).$$

