TENTATIVE SCHEDULE

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## INTRODUCTION TO SCIENTIFIC \& ENGINEERING COMPUTING BIL 108E, CRN24023

Dr. S. Gökhan Karaman

Technical University of Istanbul

```
\begin{tabular}{c|c|c}
\hline Week & Date & Topics \\
\hline 1 & Feb. 10 & Introduction to Scientific and Engineering Computing \\
2 & Feb. 17 & Introduction to Program Computing Environment \\
3 & Feb. 24 & Variables. Operations and Simple Plot \\
4 & Mar. 03 & Algorithms and Logic Operators \\
5 & Mar. 10 & Flow Control, Errors and Source of Errors \\
6 & Mar. 17 & Functions \\
6 & Mar. 20 & Exam 1 \\
7 & Mar. 24 & Arrays \\
8 & Mar. 31 & Solving of Simple Equations \\
9 & Apr. 07 & Polynomials Examples \\
10 & Apr. 14 & Applications of Curve Fitting \\
11 & Apr. 21 & Applications of Interpolation \\
11 & Apr. 24 & Exam 2 \\
12 & Apr. 28 & Applications of Numerical Integration \\
13 & May 05 & Symbolic Mathematics \\
14 & May 12 & Ordinary Differential Equation (ODE) Solutions with Built-in Functions
\end{tabular}
```

March 01, 2010

## LECTURE \# 4

## BITS, BYTES AND WORDS

1 NUMERICAL DATA TYPES IN MATLAB
2 ERRORS
3 LOOPS
4 ALGORITHMS
5 DATA ANALYSIS

BIT = elemental circuit, ON (1) / OFF (0)

- BYTE = string of 8 BITS

VARIABLES ARE REPRESENTED BY WORDS, COMPOSED OF BYTES, COMPOSED OF BITS

- WORD = string of N BYTES
(partially controllable by the programmer)


## BITS, BYTES AND WORDS

## NUMERICAL DATA TYPES IN MATLAB

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| base 10 | conversion | base 2 |
| :---: | :---: | :---: |
| 1 | $1=2^{0}$ | 00000001 |
| 2 | $2=2^{1}$ | 00000010 |
| 4 | $4=2^{2}$ | 00000100 |
| 8 | $8=2^{3}$ | 00001000 |
| 9 | $8+1=2^{3}+2^{0}$ | 00001001 |
| 10 | $8+2=2^{3}+2^{1}$ | 00001010 |
| 27 | $16+8+2+1=2^{4}+2^{3}+2^{1}+2^{0}$ | 00011011 |

one byte $=8$ bits

## NUMERICAL DATA TYPES IN MATLAB

## NUMERICAL DATA TYPES IN MATLAB

## REAL NUMBERS,

FLOATING-POINT NUMBERS

- Real numbers, $\mathbb{R}$.
- Floating-point numbers, $\mathbb{F}$.

Only a subset $\mathbb{F}$ of finite dimension $\mathbb{R}$ can be represented.
NUMERICAL DATA TYPES IN MATLAB

- int8(-128,127), int16(-32768, 32767), int32(- 2147483 648, 2147483 647), int64(-9 223372036854775 808, 9223372036854775807 ), uint8(0, 255), uint16(0, 65535), uint32(0, 4294967 295), uint64(0, 18446744073709551615$)$
- single $\left(2^{-126}, 3.4 \times 10^{38}\right)$
- double $\left(2.2251 \times 10^{-308}, 1.7977 \times 10^{308}\right)$

Any real number $x$ is truncated by the machine as $f(x)$.

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## FLOATING-POINT NUMBERS

- Numeric values with non-zero fractional parts are stored as floating point numbers.
- All floating point values are represented with a normalized scientific notation.


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## FLOATING-POINT NUMBERS

Floating-point number representation of a real number
$x=(-1)^{s} \times\left(0 . a_{1} a_{2} a_{3} \ldots a_{t}\right) \times \beta^{e}$
$a_{1} \neq 0$


## DIGITAL STORAGE OF INTEGERS

## DIGITAL STORAGE OF INTEGERS

- Integers can be exactly represented by base 2
- Typical size is 16 bits
- 32 bit and larger integers are available

Note: All standard mathematical calculations in Matlab use floating point numbers.

## DIGITAL STORAGE OF NON-INTEGER NUMBERS

## EXAMPLES;

$12.7887=0.127887 \times 10^{2}$ (base 10)
$-0.099=-0.99 \times 10^{-1}$ (base 10)

- Floating point values have fixed number of bits allocated for storage of the mantissa and fixed number of bits allocated for storage of the exponent.
- Two common precisions are provided in numerical computing: single precision and double precision.
- Fixed number of bits are allocated to each number: single precision uses 32 bits per floating point number and double precision uses 64 bits per floating point number


## IEEE STANDARD

## DIGITAL STORAGE OF NUMBERS

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Total number of bits are split into separate storage for both the mantissa and the exponent.

■ single precision: 1 sign bit, 8 bit exponent, 23 bit mantissa


- double precision: 1 sign bit, 11 bit exponent, 52 bit mantissa


64 bits


## ERRORS

■ Limiting the number of bits allocated for storage of the exponent means that there are upper and lower limits on the magnitude of floating point numbers
■ Limiting the number of bits allocated for storage of the mantissa means that there is a limit to the precision (number of significant digits) for any floating point number.

## ERRORS

1 PP Physical Problem
2 MP Mathematical Problem
3 NP Numerical Problem
Each of these steps involve errors.

## ERRORS

## ERRORS

## EXAMPLE:

Computational Errors
$f(x)=(x-1)^{7}$
$f(x)=x^{7}-7 x^{6}+21 x^{5}-35 x^{4}+35 x^{3}-21 x^{2}+7 x-1$

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## EXAMPLE:



## ERRORS

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## EXAMPLE:



EXAMPLE:
Calculation of $p i$
$z_{2}=2, z_{n+1}=2^{n-1 / 2} \sqrt{1-\sqrt{1-4^{1-n} z_{n}^{2}}}$
$n=2,3, \ldots$

## ERRORS

## ERRORS

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## EXAMPLE:



## ERRORS

$\mathbf{e}_{\mathbf{c}}$ : computational Error
ERRORS RESULTING FROM PROBLEMS

- SYNTAX ERRORS
- LOGIC ERRORS
- ROUNDOFF ERRORS


## ERRORS

## ERRORS

## SYNTAX ERRORS

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## LOGIC ERRORS

- Try to run the program for some special cases where you know the answer.
- If you don't know any exact answer, use your insight to check whether the answer seems to be of the right order of magnitude.
- Try working through the program by hand to see if you can spot where things start going wrong.


## ERRORS

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## ROUNDING ERRORS

- Finite-precision leads round-off in individual calculations
- Effects of round-off accumulate slowly
- The round-off errors are inevitable, solution is to create better algorithms
- Subtracting nearly equal may lead to severe loss of precision


## MACHINE PRECISION

The magnitude of roundoff errors is quantified by machine precision $\epsilon_{M}$
There is a number, $\epsilon_{M}$ such that

$$
1+\delta=1
$$

whenever $\delta<\epsilon_{M}$
In exact arithmetics, $\epsilon_{M}$ is identically 0 .
eps $=2.2204 \times 10^{-16}$ in Matlab

## NUMERICAL DATA TYPES IN MATLAB

## NUMERICAL DATA TYPES IN MATLAB

## FLOATING-POINT NUMBERS

Roundoff-Error
FLOATING-POINT NUMBERS
realmin, and realmax
If $x$ is less than $x_{\text {min }}$ is treated as 0 , UNDERFLOW
If $x$ is greater than $x_{\max }$ Inf OVERFLOW
The elements in $\mathbb{F}$ are more dense near $x_{\text {min }}$, and less dense while approaching $x_{\text {max }}$.
Ref: Standard for Floating Point Arithmetic P754, IEEE. $\epsilon_{M}=\beta^{1-t}$, here $t$ is the distance between 1 and its closest floating-point number greater than 1.
In Matlab $\epsilon_{M}$ is obtained through the command eps.
Number 0 does not belong to $\mathbb{F}$

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$$
\frac{|x-f|(x) \mid}{|x|} \leq \frac{1}{2} \epsilon_{M}
$$

NUMERICAL DATA TYPES IN MATLAB

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## EXAMPLE:

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## TRUNCATION ERROR

Example;
Consider the series for $\sin x$
$\sin (x)=x-\frac{x^{3}}{3!}+\frac{x^{5}}{5!}-\ldots$
For small $x$, only a few terms are needed to get an accurate aproximation to $\sin x$. The higher order terms are truncated.
$f_{\text {true }}=f_{\text {sum }}+$ truncation error
The size of truncation error depends on $x$ and the number of terms included in $f_{\text {sum }}$

## FLOW CONTROL

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Numbers: precision and accuracy


1 FOR statements
[ IF statements
3 SWITCH statements
4 WHILE statements
Numbers. precision and accuracy
-Low precision: $\pi=3.14$

- High precision: $\pi=3.140101011$
- Low accuracy: $\pi=3.10212$
- High accuracy: $\pi=3.14159$
- High accuracy \& precision: $\pi=3.141592653$


## LOOPS

## LOOPS

## REPETITIVE TASKS

$■ j: k$ is a vector with elements $j, j+1, j+2, \ldots, k$.
$\square j: m: k$ is a vector with elements $j, j+m, j+2 m, \ldots$ such that the last element can not exceed $k$.

■ index must be a variable. Each time through the loop it will contain the next element of the vector $j: k$ or $j: m: k$.

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index $=$ first $:$ increment $:$ last

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The number of times that the loop is executed is defined as iteration:
iteration $=\mathrm{floor}\left(\frac{\text { last-first }}{\text { increment }}\right)+1$ Here floor $(x)$ is a function, that rounds $x$ down toward $-\infty$

This value is called iteration or trip count

- On completion of the for loop the index contains the last value used.
■ If the vector $j: k$ or $j: m: k$ is empty, statements are not executed and control passes to the statement following end.
- If the index does appear explicitly in statements, the for can often be vectorized. It runs faster.
■ It is good programming style to indent (tabulate) the statements inside a for loop.


## LOOPS

## LOOPS

## for in a single line

More general form of the for is
for index $=v$
Here $v$ is any vector.
The index moves through each element of the vector.


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## EXAMPLE:



## EXAMPLES:

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Vectorize if possible

Evaluate the expression given below without the formula for the sum.

$$
\sum_{n=1}^{100000} n
$$

- clock function
returns a six element vector.
- etime function
returns the time in seconds between its two arguments.


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## EXAMPLE

 > help cputyme
CPUTIME CPU time in seconds.
CPUTIME returns the CPU time in seconds that has been used
by the MATLAB process since MATLAB started.
For example:
t=cputime; your_operation; cputime-t
returns the cpu time used to run your_operation
The return value may overflow the internal representation
and wrap around.
See al so etime, tic, toc, clock
Reference page in Help browser
dor rnutima
help cputime

- 1 start


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## EXAMPLE:



## LOOPS

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with for loop
t0 = clock;
$\mathrm{s}=0$;
for $n=1: 100000$
$s=s+n ;$
end
etime (clock, t0)

## EXAMPLE:



## LOOPS

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EXAMPLE:



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## EXAMPLES

with vectorization
tic
$\mathrm{n}=1$ : 100000;
$\mathrm{s}=\operatorname{sum}\left(1 \mathrm{I} / \mathrm{n} .{ }^{\wedge} 2\right)$;
toc

## LOOPS

## CONDITIONAL STATEMENTS

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## EXAMPLE:



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## if statements

- Relational Operators

Usage;
if condition statement, end
■ condition is usually a logical expression
■ if condition is true statement is executed but if condition is false, nothing happens.
■ Condition may be a vector or a matrix, in which case it is true only if all of its elements are nonzero. A single zero element in a vector or matrix renders it false.

## CONDITIONAL STATEMENTS

## CONDITIONAL STATEMENTS

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## LOGICAL EXPRESSIONS

Logical operators are used to combine logical expressions (with "and" or "or"), or to change a logical value with "not"
Operators:
\& AND, | OR, ~ NOT.

| INPUT |  | OUTPUT |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | B | $\mathrm{A} \& \mathrm{~B}$ | $\mathrm{~A} \mid \mathrm{B}$ | ${ }^{\sim} \mathrm{A}$ | $\sim \mathrm{B}$ |
| false | false | false | false | true | true |
| false | true | false | true | true | false |
| true | false | false | true | false | true |
| true | true | true | true | false | false |

EXAMPLE
$\mathrm{a}=\mathrm{rand}$
if $a>0.5$ disp('greater 0.5'), end
\% if logical expression is TRUE ---> 1
\% if logical expression is FALSE --> 0

## CONDITIONAL STATEMENTS

## CONDITIONAL STATEMENTS

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## EXAMPLE:

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## IF-ELSE

if condition
blockofstatementsA
else
blockofstatements $B$
end

- blockofstatementsA or blockofstatementsB represents one or more statements.
- If condition is true blockofstatementsA is executed and if false blockofstatements $B$ is executed.
- else is optional.


## CONDITIONAL STATEMENTS

## ERRORS

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## EXAMPLE

$\mathrm{a}=\mathrm{rand}$
if $a>0.5$
disp('a is greater than 0.5')
else
disp('a is less than 0.5')
end

## EXAMPLE:

- Stan


## CONDITIONAL STATEMENTS

## CONDITIONAL STATEMENTS

## if condition 1

statement $A$
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elseif

1 condition 1 is tested. If it is true, statementA are executed MATLAB then moves to the next statement after end.

2 If condition 1 is false, MATLAB checks condition2. If it is true, statement $B$ are executed, followed by the statement after end.

3 In this way, all conditions are tested until a true one is found. As soon as a true condition is found, no further elseifs are examined andMATLAB jumps off the ladder.If none of the conditions is true, statement $E$ after else are executed.

## CONDITIONAL STATEMENTS

## CONDITIONAL STATEMENTS

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elseif cont'd

5 Arrange the logic so that not more than one of the conditions is true.

6 There can be any number of elseifs, but at most one else.
7 elseif must be written as one word.
8 It is good programming style to indent each group of statements as shown.

## CONDITIONAL STATEMENTS

## switch STATEMENT

switch value
case val1
statement1
case val2
statement 2
case [val3 val4 val5]
statement3
otherweise
statementN
end

## NESTED ifs

An if construct can contain further ifs.
This is called NESTING.
else belongs to the most recent ifs.

## CONDITIONAL STATEMENTS

## EXAMPLE:

val = 3;
switch val
case 1
disp('one')
case 2
disp('two')
case 3
disp('three')
otherwise
disp('not a number between 1-3')
end

## CONDITIONAL STATEMENTS

## CONDITIONAL STATEMENTS

EXAMPLE:


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EXAMPLE:


## LOOPS

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## WHILE LOOP

While loops are most often used when an iteration is repeated until some termination criterion is met.

Usage;
while expression

> block of statements
end
The block of statements is executed as long as expression is true.

## WHILE LOOP

To execute a while-end loop properly;
■ The conditional expression in the while command must include at least one variable;
■ The variables in the conditional expression must have been assigned when MATLAB executes the while command for the first time;

■ At least one of the variables in the conditional execution must be assigned a new value in the commands that are between the while and the end. Otherwise once the looping starts it will never stop since the conditional expression will remain true.


## LOOPS

## EXAMPLE:



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INTERRUPTING THE INFINITE LOOP
In case of an Infinite Loop
\% ***
i=100;
while i == 100
disp(i)
end
$\% * * *$
Use CTRL+C or CTRL+BREAK to stop the program.

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## LOOPS

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EXAMPLE:



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## BREAK, CONTINUE AND RETURN

- The break and return statements provide an alternative way to exit from the flow of the program.
- continue passes control to the next iteration of for or while loop and skips any remaining statements in the body of the loop.
- break is used to escape from an enclosing while or for loop. Execution continues at the end of the enclosing loop construct.
- return is used to force an exit from a function. This can have the effect of escaping from a loop. Any statement following the loop that are in the function body are skipped (Next week "Functions").


## LOOPS

## EXAMPLE:

$i=0$
sum $=0$;
while (i <= 100)
if (i == 72)
disp(i);
disp('loop stopped');
break;
end
if(i == 12)
disp(i);
disp('loop continued without ending');
i $=i+1$
end
i $=\mathbf{i}+1$;
sum $=$ sum $+i$.
end

## LOOPS

## LOOPS

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EXAMPLE:
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## PROGRAM DESIGN AND ALGORITHM

## PROGRAM DESIGN

- Design Process
- The program must be readable and hence clearly understandable.
To design a successful program you need to understand a problem thoroughly and break it down into its most fundamental logical stages.
In other words, you have to develop a systematic procedure or an algorithm for solving it.


## DESIGN PROCESS

## DESIGN PROCESS cont'd.

1 Problem analysis.
2 Problem statement. Develop a detailed statement of the mathematical problem to be solved with a computer program.
3 Processing scheme. Define the inputs required and the outputs to be produced by the program.
4 Algorithm. Design the step-by-step procedure in a top-down process that decomposes the overall problem into subordinate problems.

5 Program algorithm. Translate or convert the algorithm into a computer language.Evaluation. Test all of the options and conduct a validation study of the program. For example, compare results with other programs.
7 Application. Solve the problems, the program was designed to solve. If the program is well designed and useful, it can be saved in your working directory

## DESIGN PROCESS

## DESIGN PROCESS

EXAMPLE
TRAJECTORY
A ball is thrown with an initial angle of $\theta$ and initial velocity of $v_{0}$.
Given

- velocity and theta angle


## Find

- Projectile Flight Path
- Projectile speed vs. angle


## DESIGN PROCESS

## DESIGN PROCESS

## EXAMPLE

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$1 v_{0, x}=v_{0} \times \cos \left(\theta_{0}\right)$
2 $v_{0, y}=v_{0} \times \sin \left(\theta_{0}\right)$
3 $x(t)=v_{0, x} \times t$ (horizontal distance from origin as a function of $t$ )
$4 y(t)=v_{0, y} \times t-0.5 \times g t^{2}$ (vertical distance from origin as a function of $t$ )
5. $y(x)=\frac{v_{0, y}}{v_{0, x}} \times x-0.5 \times g \frac{x^{2}}{v_{0, x}^{2}}$ (with using \#3 and \#4 vertical location of the point is a function of $x$ horizontal distance)

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## EXAMPLE

\%
\% The projectile problem with zero air resistance
$\%$ in a gravitational field with constant $g$.
\%
\% Written by \#\#\#\#\#\#\# 01.03.2010
\% Written by D. T. Valentine ........ September 2006
\% Revised by D. T. Valentine ........ November 2008
\% An eight-step structure plan applied in MATLAB:
$\%$

## DESIGN PROCESS

## DESIGN PROCESS

## EXAMPLE cont'd.

\% 1. Definition of the input variables.
\%
\% Gravity in m/s**2
g = 9.81;
disp('*** INPUT DATA FOR PROJECTILE PROBLEM ***');
vo = input('Launch speed in m/s: ');
theta $=$ input('Launch angle in degrees: ');
\% Convert degrees to radians
theta $=$ pi*theta/ 180 ;

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EXAMPLE cont'd.
\% 2. Calculate the range and duration of the flight.
\%
txmax $=(2 * v 0 / g) * \sin ($ theta $) ;$
xmax $=$ txmax $*$ v0 * cos(theta);

## DESIGN PROCESS

## DESIGN PROCESS

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EXAMPLE cont'd.
$\% 3$. Calculate the sequence of time
\% steps to compute trajectory.
\%
dt = txmax/100;
$\mathrm{t}=0: \mathrm{dt}: \mathrm{txmax}$;
\%
\% 4. Compute the trajectory.
\%
$\mathrm{x}=(\mathrm{v} 0 * \cos ($ theta) ) .* t;
$\mathrm{y}=(\mathrm{v} 0$ * $\sin (\mathrm{theta}))$.* $\mathrm{t}-(\mathrm{g} / 2) . * \mathrm{t} . \wedge 2$;

EXAMPLE cont'd.
\% 5. Compute the speed and angular
\% direction of the projectile.
$\%$ Note that $v x=d x / d t, v y=d y / d t$.
\%
$\mathrm{vx}=\mathrm{v} 0 * \cos ($ theta) ;
vy $=\mathrm{v0}$ * $\sin (\mathrm{theta}) ~-\mathrm{g} . * \mathrm{t}$;
v = sqrt(vx.*vx + vy.*vy);
th $=(180 / \mathrm{pi}) . *$ atan2(vy,vx);
\%
\% 6. Compute the time, horizontal
\% distance at maximum altitude.
\%
tymax $=(v 0 / g) * \sin ($ theta) ;
xymax = xmax/2;
ymax $=(v 0 / 2) *$ tymax $* \sin ($ theta $) ;$

## DESIGN PROCESS

## DESIGN PROCESS

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## EXAMPLE cont'd.

## \% 7. Display ouput

\%
disp([' Range in $m=$, num2str(xmax)
, Duration in $\mathrm{s}=$, num2str(txmax)]
disp(' ')
disp([' Maximum altitude in $m=$ ',num2str(ymax), ...
' Arrival in $\mathrm{s}=$ ', num2str(tymax)]
plot ( $\mathrm{x}, \mathrm{y}$, ' k ', xmax, $\mathrm{y}(\operatorname{size}(\mathrm{t})$ ), 'o', $\mathrm{xmax} / 2, \mathrm{ymax}$, 'o')
title([' Projectile flight path, vo $=>$, num2str(vo)
, th $=$ ', num2str ( $180 *$ th/pi)]
xlabel(' x '), ylabel(' y ') \% Plot of Figure 1
figure \% Creates a new figure.
plot(v,th,'r)
title(' Projectile speed vs. angle ,
xlabel(' V'), ylabel(' \theta ') \% Plot of Figure 2
$\%$
$\%$
\%

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EXAMPLE:


## DESIGN PROCESS

## DESIGN PROCESS

EXAMPLE

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## EXAMPLE:



## DATA ANALYSIS FUNCTIONS

## DATA ANALYSIS FUNCTIONS

## EXAMPLE:



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- $\max (\mathrm{x})$ Determines the largest value in x .
- $\min (x)$ Determines the smallest value in $x$.
- sum( $x$ ) Determines the sum of the elements in $x$.
- $\operatorname{prod}(\mathrm{x})$ Determines the product of the elements in x .
- sort( x ) Returns a vector with the values of x in ascending order.


## DATA ANALYSIS FUNCTIONS

## DATA ANALYSIS FUNTIONS

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## MEAN AND MEDIAN

■ mean(x) Computes the mean(average value) of the elements of the vector $x$.
$\bar{x}=\frac{\sum_{k=1}^{N} x_{k}}{N}$
where $\sum_{k=1}^{N} x_{k}=x_{1}+x_{2}+\ldots+x_{N}$

- median ( x ) Determines the median value of the elements in the vector $x$.

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## VARIANCE AND STANDARD DEVIATION

■ $\operatorname{var}(\mathrm{x})$ Computes the variation of the values in $x$.

- std ( $x$ ) Computes the standard deviation of the values in $x$.
■ The standard deviation is defined as the square root of the variance.
$\sigma^{2}=\frac{\sum_{k=1}^{N}\left(x_{k}-\bar{x}\right)^{2}}{(N-1)}$


## References

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