

Nature-Inspired Computing

Handling Multiple Objectives

Dr. Şima Uyar
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Multi-objective Optimization

- MOP: Multi-objective Optimization Problem
- optimization problems with multiple, often conflicting objectives
- two part problem:
 - finding set of good solutions
 - choosing best solution for particular application

Multi-objective Optimization

- MOPs present uncountable set of solutions
- solutions produce vectors representing trade-offs in objective space
- decision maker chooses among these set of possible solutions

Multi-objective Optimization Problem

- a.k.a. multi-criteria optimization, multi-performance or vector optimization problem
- problem of finding a vector of decision variables which satisfies some constraints and optimizes a vector function whose elements represent the (usually conflicting) objective functions
 - acceptable solutions to decision maker

Multi-objective Optimization Problem

Find the vector $\vec{x}^* = [x_1^*, x_2^*, \dots, x_n^*]^T$ satisfying

m inequality constraints: $g_i(\vec{x}) \leq 0 \quad i = 1, 2, \dots, m$

p equality constraints: $h_i(\vec{x}) = 0 \quad i = 1, 2, \dots, p$

optimizing the vector function:

$$\vec{f}(\vec{x}) = [f_1(\vec{x}), f_2(\vec{x}), \dots, f_k(\vec{x})]^T$$

Solution Classification

- a priori preference articulation:
 - (decide \rightarrow search)
 - decision maker combines different objectives into a scalar cost function.
 - makes MOP into single objective prior to optimization
 - to find other solutions, to re-optimize with different w_i

$$f'(x) = \sum_{i=1}^n w_i f_i(x)$$

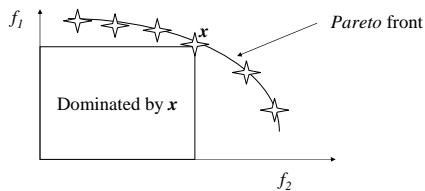
Solution Classification

- progressive preference articulation:
 - (decide \leftrightarrow search)
 - decision making and optimization intertwined
 - partial preference information provides updated set of solutions for decision maker

Solution Classification

- a posteriori preference articulation:
 - (search \rightarrow decide)
 - decision maker presented with set of Pareto optimal candidate solutions
 - decision maker chooses from set

Pareto Optimality



x dominates y if it is at least as good on all criteria and **better** on at least one

Pareto Optimality

A vector of decision variables $\vec{x}^* \in F$ is

Pareto optimal if there does not exist another

$\vec{x} \in F$ such that $f_i(\vec{x}) \leq f_i(\vec{x}^*)$ for all $i = 1, \dots, k$

and $f_j(\vec{x}) < f_j(\vec{x}^*)$ for at least one j .

Pareto Optimality

- definition usually gives a set of solutions called the *Pareto optimal set*
- solutions in the Pareto optimal set are called *nondominated* solutions
- plot of objective functions with nondominated vectors in Pareto optimal set is called *Pareto front*

Advantages of NIC Approaches

- population-based nature of search
 - can *simultaneously* find several Pareto optimal solutions in one run
 - traditional mathematical programming techniques can find Pareto optimum per run
- don't have to make guesses about which combinations of weights might be useful
- makes no assumptions about shape of Pareto front
 - can be convex / discontinuous etc
 - causes problems for most traditional mathematical programming techniques

Requirements of NIC Approach

- way of assigning fitness,
 - usually based on dominance
- preservation of diverse set of points
 - similarities to multi-modal problems
- remembering all the nondominated points encountered
 - usually using elitism or an archive