

Nature-Inspired Computing

Evolutionary Strategies

Dr. Şima Uyar
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Overview

- developed in Germany in the 1970's
- typically applied to numerical optimization problems
- features:
 - fast
 - good optimizer for real-valued optimisation
 - relatively much theory behind it
 - self-adaptation of (mutation) parameters is standard

Overview

Representation	Real-valued vectors
Recombination	Discrete or intermediary
Mutation	Gaussian mutation
Parent selection	Uniform random
Survivor selection	(μ, λ) or $(\mu + \lambda)$
Specialty	Self-adaptation of mutation step sizes

Introductory Example

- Task: minimise $f : \mathbb{R}^n \rightarrow \mathbb{R}$
- Algorithm: "two-membered ES" using
 - vectors from \mathbb{R}^n as chromosomes
 - population size 1
 - only mutation creating one child
 - greedy selection

Introductory Example: Pseudocode

```
set t = 0
create initial point  $x^t = \langle x_1^t, \dots, x_n^t \rangle$ 
repeat until (termin criteria)
do
  draw  $z_i$  from a normal distr. for all  $i = 1, \dots, n$ 
   $y_i^t = x_i^t + z_i$ 
  if  $f(x^t) < f(y^t)$  then
     $x^{t+1} = x^t$ 
  else
     $x^{t+1} = y^t$ 
  fi
  set t = t+1
od
```

Introductory Example: Mutation Mechanism

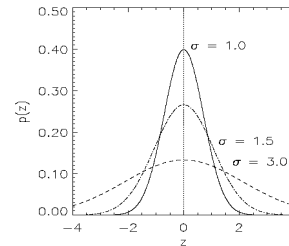
- z values drawn from normal distribution $N(\xi, \sigma)$
 - mean ξ is set to 0
 - variation σ is called mutation step size
- σ is varied on the fly by the "1/5 success rule"

Introductory Example: Mutation Mechanism

- this rule resets σ after every k iterations by
 - $\sigma = \sigma / c$ if $p_s > 1/5$
 - $\sigma = \sigma \cdot c$ if $p_s < 1/5$
 - $\sigma = \sigma$ if $p_s = 1/5$

where p_s is the % of successful mutations,
 $0.8 \leq c \leq 1$

Illustration of Normal Distribution



Representation

- chromosomes consist of three parts:
 - object variables: x_1, \dots, x_n
 - strategy parameters:
 - mutation step sizes: $\sigma_1, \dots, \sigma_n$
 - rotation angles: $\alpha_1, \dots, \alpha_n$

Representation

- not every component is always present
- full size: $\langle x_1, \dots, x_n, \sigma_1, \dots, \sigma_n, \alpha_1, \dots, \alpha_k \rangle$
 where $k = n(n-1)/2$ (no. of i, j pairs)

Mutation

- main mechanism: changing value by adding random noise drawn from normal distribution

$$x'_i = x_i + N(0, \sigma)$$

Mutation

- key idea:
 - σ is part of the chromosome $\langle x_1, \dots, x_n, \sigma \rangle$
 - σ is also mutated into σ' (see later how)
- thus: mutation step size σ is co-evolving with the solution x

Mutation

- net mutation effect:

$$\langle x, \sigma \rangle \rightarrow \langle x', \sigma' \rangle$$

- order is important:
 - first $\sigma \rightarrow \sigma'$ (see later how)
 - then $x \rightarrow x' = x + N(0, \sigma')$

Mutation

- rationale: new $\langle x', \sigma' \rangle$ is evaluated twice
 - primary: x' is good if $f(x')$ is good
 - secondary: σ' is good if the x' created from it is good
- not holds if mutation order is reversed

Mutation Case 1: Uncorrelated Mutation with One σ

- chromosomes: $\langle x_1, \dots, x_n, \sigma \rangle$
 - $\sigma' = \sigma \cdot \exp(\tau \cdot N(0,1))$
 - $x'_i = x_i + \sigma' \cdot N(0,1)$
- typically the "learning rate" $\tau \propto 1/n^{1/2}$

Mutation Case 2: Uncorrelated Mutation with n σ 's

- chromosomes: $\langle x_1, \dots, x_n, \sigma_1, \dots, \sigma_n \rangle$
 - $\sigma'_i = \sigma_i \cdot \exp(\tau' \cdot N(0,1) + \tau \cdot N_i(0,1))$
 - $x'_i = x_i + \sigma'_i \cdot N_i(0,1)$
- two learning rate parameters:
 - τ' overall learning rate
 - τ coordinate-wise learning rate
 - $\tau \propto 1/(2n)^{1/2}$ and $\tau' \propto 1/(2n^{1/2})^{1/2}$

Recombination

- creates one child
- acts per variable / position by either
 - averaging parental values, or
 - selecting one of the parental values
- from two or more parents by either:
 - using two parents to make a child
 - selecting two parents for each position anew

Names of Recombinations

	Two fixed parents	Two parents selected for each i
$z_i = (x_i + y_i)/2$	Local intermediary	Global intermediary
z_i is x_i or y_i chosen randomly	Local discrete	Global discrete

Parent Selection

- selected by uniform random distribution whenever an operator needs one/some
- ES parent selection is unbiased - every individual has the same probability to be selected

Parent Selection

- in ES "parent" means a population member
- in GA's: a population member selected to undergo variation

Survivor Selection

- applied after creating λ children from the μ parents by mutation and recombination
- deterministically chops off the "bad stuff"
- basis of selection is either:
 - set of children only: (μ, λ) -selection
 - set of parents and children: $(\mu + \lambda)$ -selection

Survivor Selection cont'd

- $(\mu + \lambda)$ -selection is an elitist strategy
- (μ, λ) -selection can "forget"
- selective pressure in ES is very high ($\lambda \approx 7 \cdot \mu$ is the common setting)