

Overview

- Ken Price and Rainer Storn
- 1994 1996
- to solve the Chebychev polynomial fitting problem
- population based
- stochastic
- function minimization





Initialization

- usually random
- parameters have upper and lower bounds

Mutation

• all undergo mutation

for each vector $x_{i,g}$ randomly select 3 distinct vectors - $x_{r1,g}$, $x_{r2,g}$, $x_{r3,g}$ $v_{i,g+1}$ = $x_{r1,g}$ + F($x_{r2,g}$ - $x_{r3,g}$) //method DE/rand/1

$v_{\text{i,G+1}}~$ is called the $\underline{\text{donor vector}}$

Mutation Schemes - 1

- DE/rand/1
 - $v_{i,G+1} = x_{r1,G} + F(x_{r2,G} x_{r3,G})$



- DE/best/1
- $\mathbf{v}_{\text{i,G+1}}\text{=} \mathbf{x}_{\text{best,G}} + \text{F}(\mathbf{x}_{\text{rl,G}} \mathbf{x}_{\text{r2,G}})$

Mutation Schemes - 3

- DE/best/2
- $v_{i,G+1} = x_{best,G} + F(x_{r1,G} + x_{r2,G} x_{r3,G} x_{r4,G})$





Selection

• $u_{i,G+1}$ is compared to $x_{i,G}$ and the one with the lower objective function value is taken to be member of the next generation G+1

Rules for usage of DE - 1

- at initialization, the population should be well spread out over objective function surface
- usually $CR \in [0,1]$ should be low (e.g. CR = 0.3)

– if no convergence occurs, $\mathsf{CR}{\in}\left[0.8,1\right]$ helps

- usually NP=10*D
- usually $F \in [0.5,1]$
- for higher NP values, F should be chosen lower

Rules for usage of DE - 2

- if parameters of the best population members change a lot from generation to generation (even though change in objective function may be slow) ⇒ good sign of convergence
- if objective function value of best exhibits plateaus:
 - minimization may take long
 - larger NP may be useful for convergence

Rules for usage of DE - 3

- objective function values of best should not drop too fast or optimization may get stuck at local optima
- choice and design of objective function is crucial