

# ELE6XXE

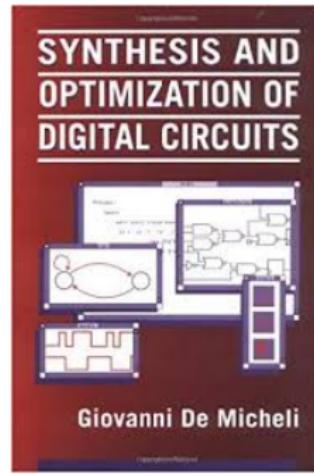
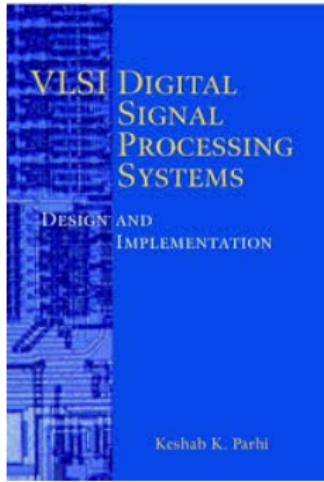
## Lectures

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# Course information



- K. K. Parhi, VLSI Digital Signal Processing Systems Design and Imp.
- Giovanni De Micheli - Synthesis and Optimization of Digital Circuits.

Reading : Keshab K. Parhi, "High-level algorithm and architecture transformations for DSP synthesis," Journal of VLSI signal processing systems for signal, image and video technology, 10.1007/BF02406474, 1995

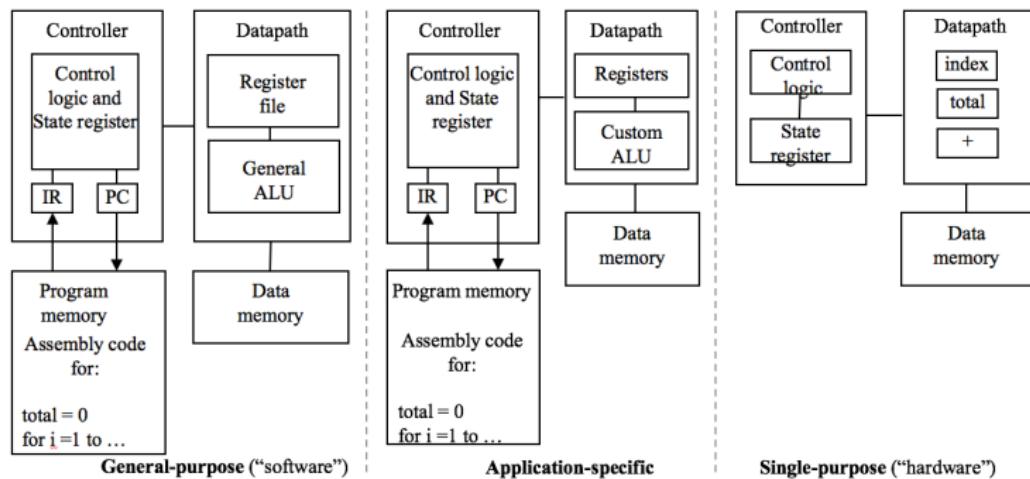
# Scope of the Course

To obtain an efficient implementation of a signal processing algorithm in a structured way.

- Folding
- Unfolding
- Pipelining
- Parallelism
- Strength reduction

# Three key technologies for embedded systems

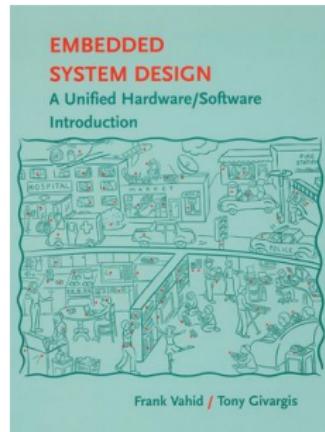
The architecture of the computation engine used to implement a system's desired functionality



Main focus of this Course: FPGA and ASIC

Source: Embedded System Design: A Unified Hardware/Software Introduction  
Frank Vahid and Tony Givargis John Wiley Sons, 2002.

# Introduction to Embedded Systems



Read: Frank Vahid and Tony Givargis- Embedded System Design: A Unified Hardware/Software Introduction, John Wiley Sons, (2002).

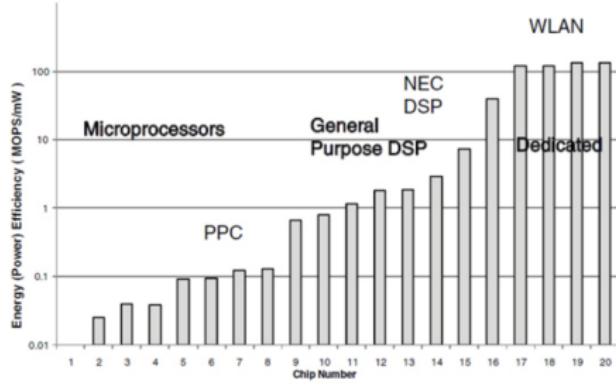
- EHB326E, Introduction to Embedded Systems, Week 1-6

# Design issues

Specialized architectures which will be introduced in this course could be used for either FPGA or ASIC.

► Features and Benefits of Single-purpose/Application-specific

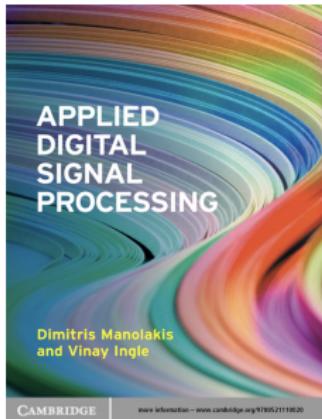
Key design issues: Energy Efficiency



► National Research Council. 2011. The Future of Computing Performance.

The data are somewhat dated, but all chips were designed for similar 0.18- to 0.25-m CMOS technology, and one can see that the ASIC designs are roughly 3 orders of magnitude more energy-efficient than the general-purpose processors.

# Introduction to DSP



Read: Dimitris G. Manolakis, Vinay K. Ingle - Applied Digital Signal Processing Theory and Practice -Cambridge University Press (2011), Chapter 1.

- ► Digital Signal Processing, MIT Open Courseware
- ► Digital signal processor (also DSP), From Wikipedia
- ► EHB433: Sayısal Filtreler ve Sistemler, Week-1 and Week-2

# Recursive and non-recursive systems

- non-recursive system

$$y(k) = \sum_{i=0}^m b_i x(k-i)$$

*Finite impulse response (FIR)*

► EHB433: Sayısal Filtreler ve Sistemler, Week-5 and Week-6

- recursive system

$$y(k) = \sum_{i=1}^n a_i y(k-i) + \sum_{i=0}^m b_i x(k-i)$$

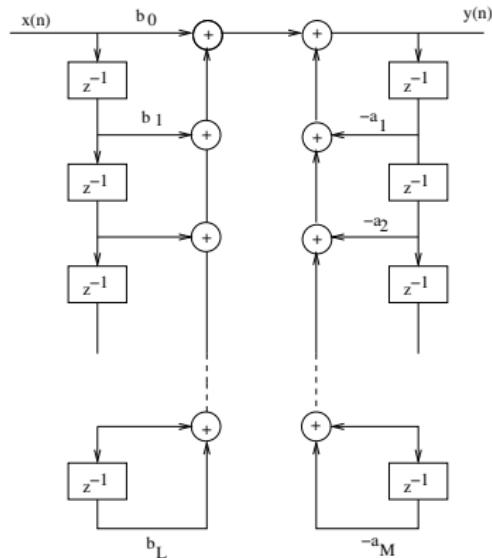
*Infinite impulse response (IIR)*

► EHB433: Sayısal Filtreler ve Sistemler, Week-3 and Week-4

# Filter Design

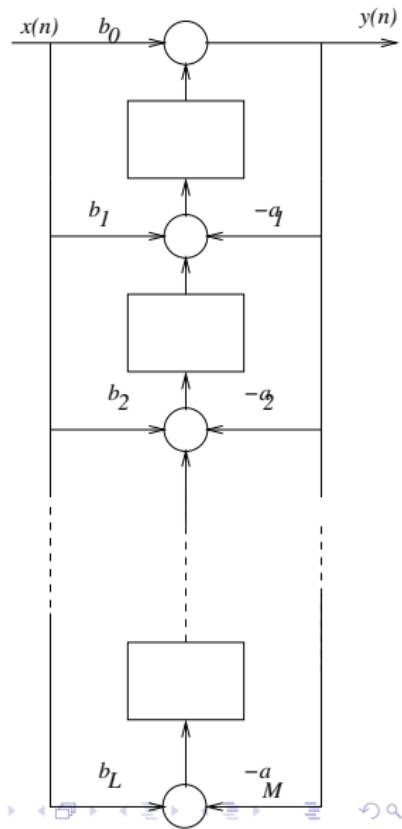
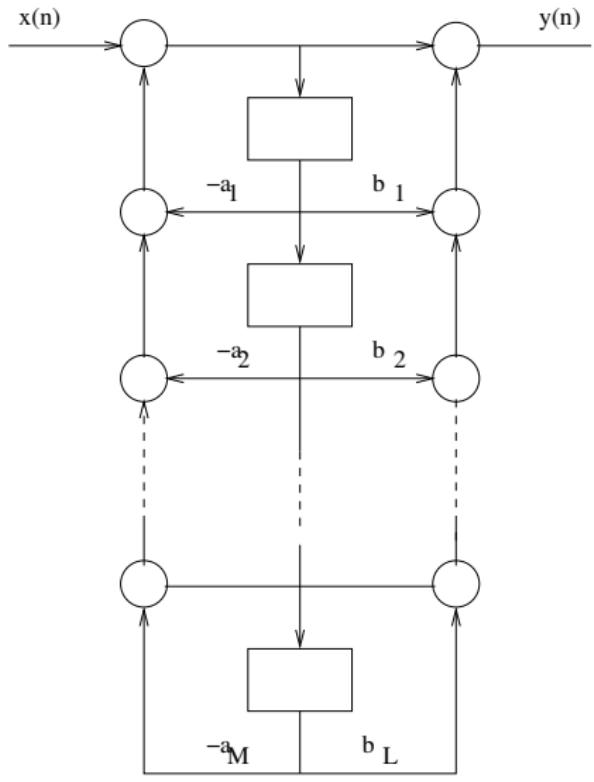
- Infinite impulse response (IIR) Filter Design

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{i=0}^L b_i z^{-i}}{1 + \sum_{i=1}^M a_i z^{-i}}$$



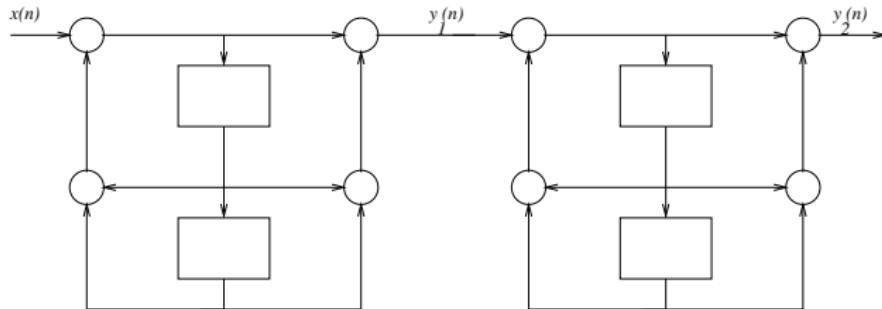
direct form I

# Direct form I and II



# Cascade form

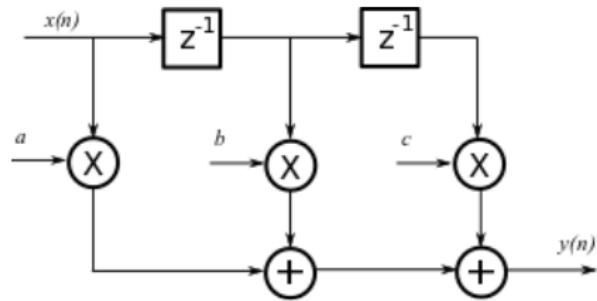
$$H(z) = G \prod_{i=1}^K \frac{b_{k0} + b_{k1}z^{-1} + b_{k2}z^{-2}}{1 + a_{k1}z^{-1} + a_{k2}z^{-2}}$$



$$[sos, G] = tf2sos(b, a)$$

# Finite impulse response (FIR)

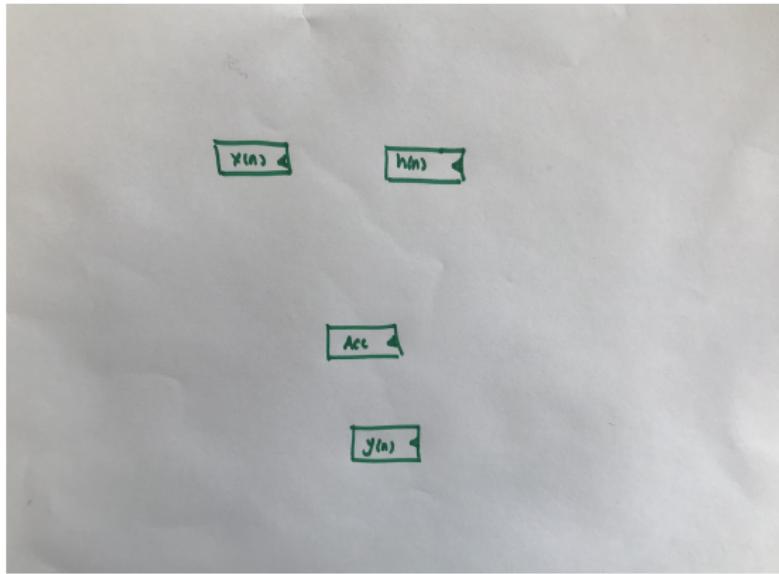
$$y(n) = ax(n) + bx(n - 1) + cx(n - 2)$$



Filter length: 3; Filter order: 2; # filter taps: 3

# Finite impulse response (FIR)

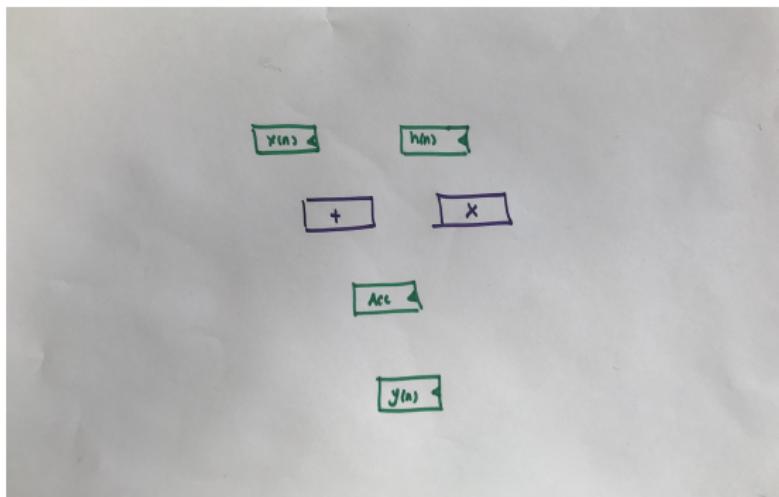
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- ▶ EHB326E Introduction to Embedded Systems, Algorithm to FSDM and then Hardware, Week-5

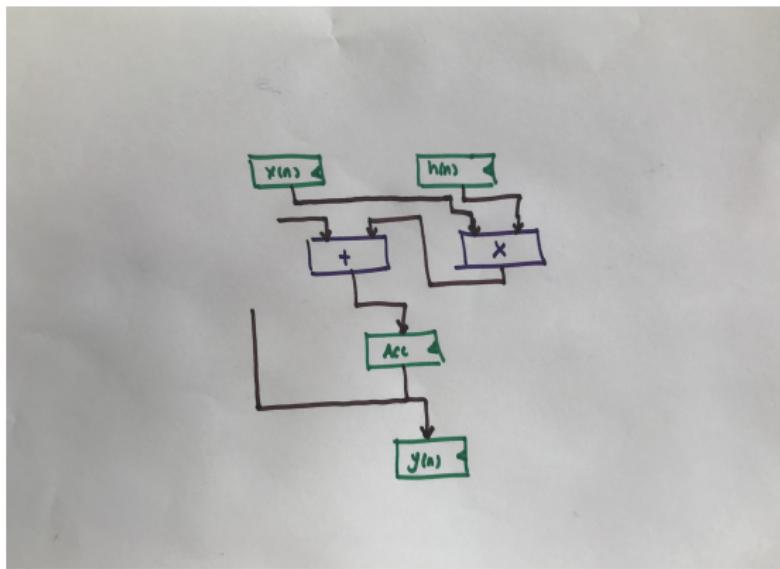
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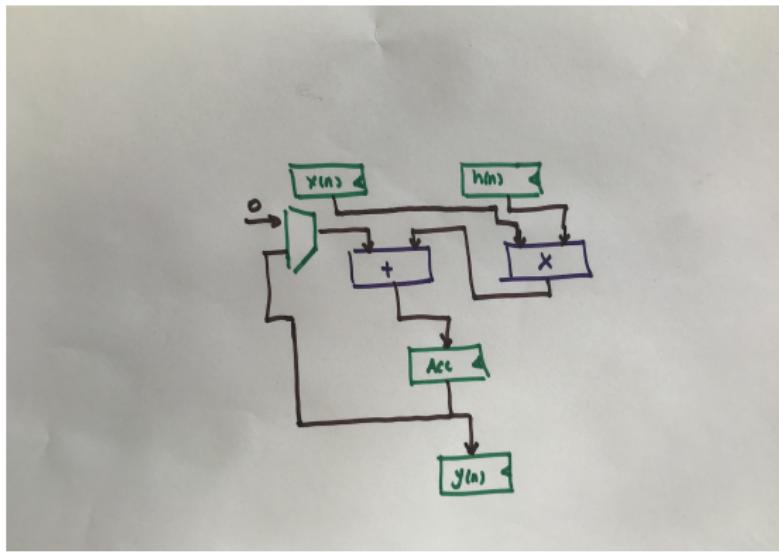
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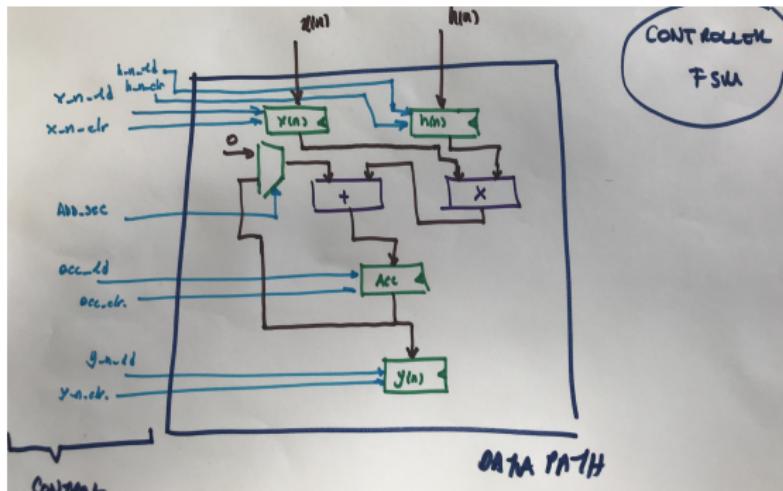
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## Finite impulse response (FIR)

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Solution for  $h(n)$  and  $x(n)$  ?