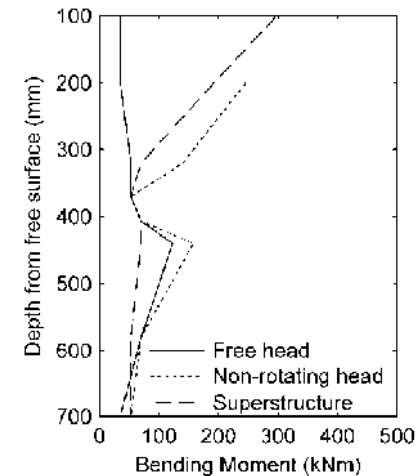
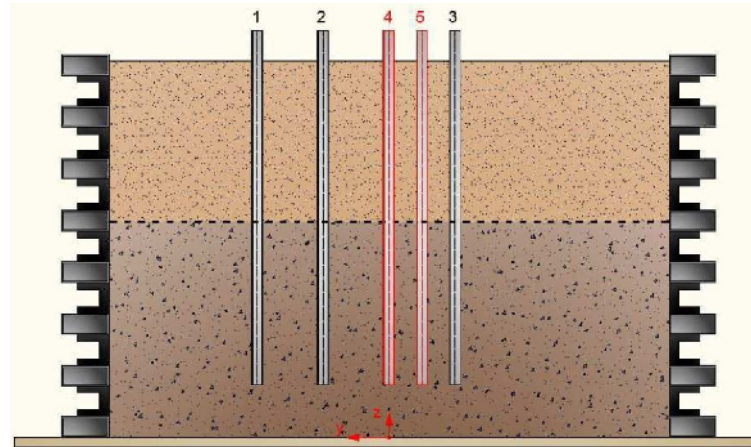
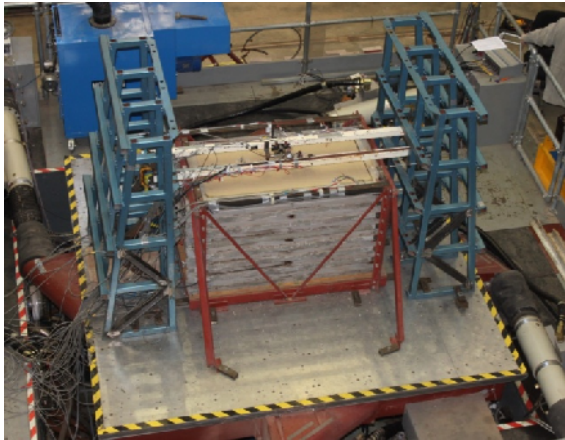


SERIES Workshop**“Role of research infrastructures in seismic rehabilitation”***Istanbul, February 8-9, 2012***Experimental investigation of soil-pile-structure seismic interaction****TA project PILESI @ UnivBris****Assessment of Soil-Pile-Structure Seismic Interaction****A.L. Simonelli***University of Sannio, Italy***L. Di Sarno****M.G. Durante****S. Sica****R. Cairo****A. Chidichimo****G. Dente**University
of Patras**G. Anoyatis****G. Mylonakis****S. Bhattacharya****M. Dietz****L. Dighoru****C.A. Taylor****A. Modaressi****L.A. Todo Bom****A. Kaynia**

PILESI Project (Bristol)

Experimental investigation of soil-pile-structure seismic interaction

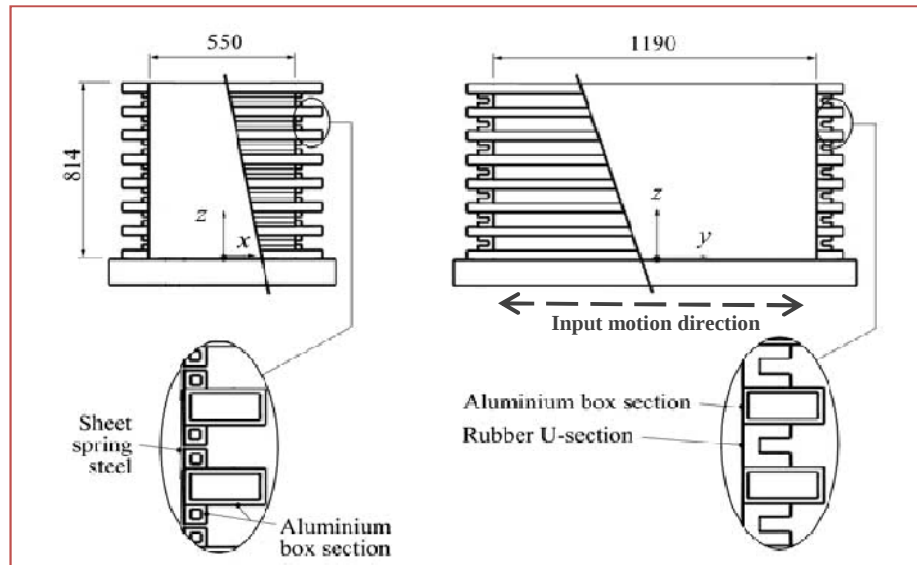


Project leader: Prof. A. L. Simonelli (University of Sannio, Italy)

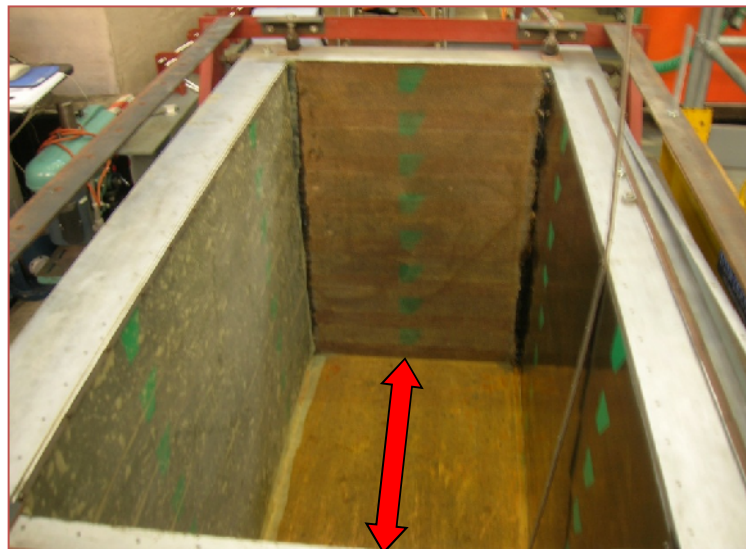
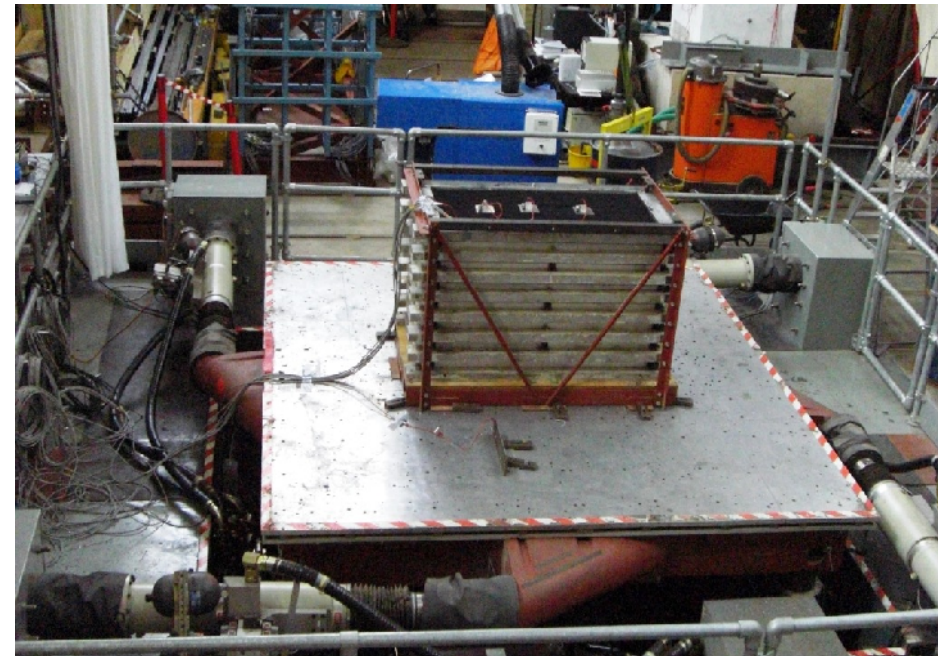
Objectives: To investigate the seismic response of pile groups in layered soils in order to provide a benchmark for numerical-model validation purposes.

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Controlled Sand Deposition is used to impose a stiffness contrast between upper and lower soil layers.

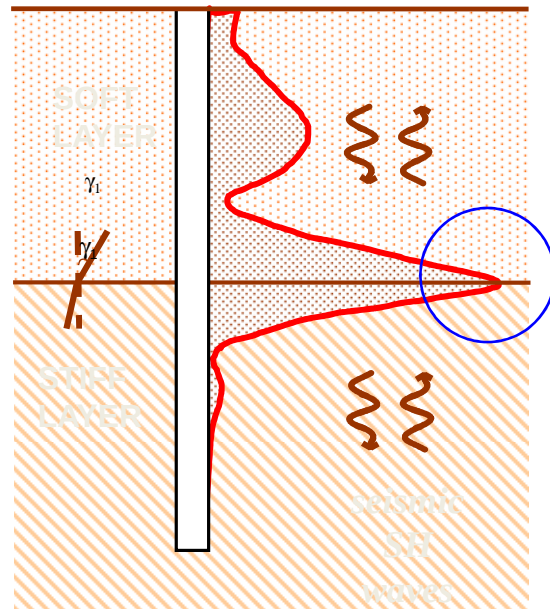


Bristol SHEAR STACK



appropriate boundary conditions

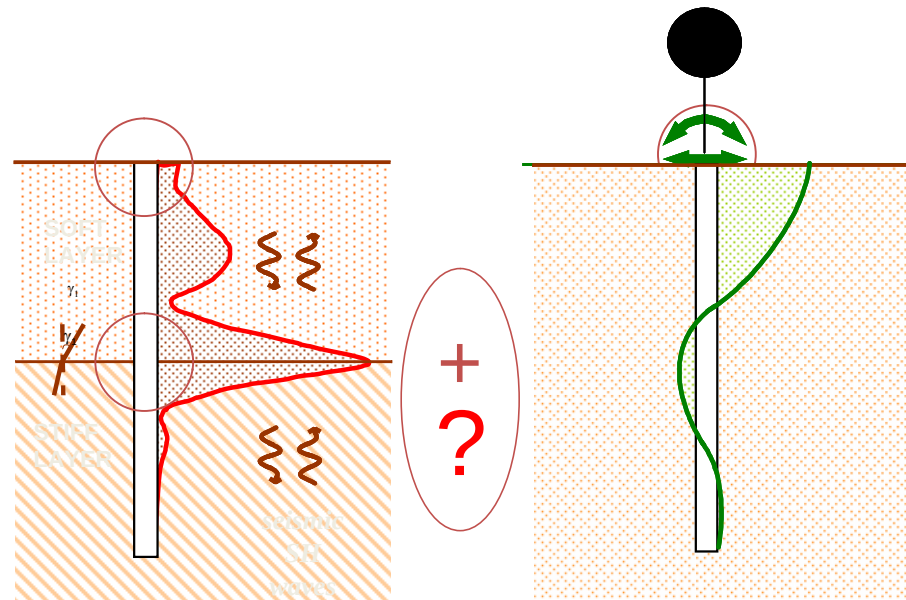
Kinematic pile bending : Theoretical background



Kinematic

Seismic waves through the soil surrounding a pile impose **lateral displacements and curvatures** on the pile, thereby generating 'kinematic' bending moments even in the absence of a superstructure.

These "kinematic" moments can be quite severe at the interfaces between soft and stiff soil layers.



Kinematic

Inertial

Overview

Following the early work by Margason & Halloway [1977], theoretical investigations of the problem began in the 1980's [Flores-Berrones & Whitman 1982, Dobry & O'Rourke 1983, Tazoh 1987, Conte & Dente 1989, etc.] and continued into the 1990's and beyond [Novak 1991, Kavvadas & Gazetas 1993, Pender 1993, Mylonakis 2001, Nikolaou et al. 2001, etc.].

In 2005, a systematic research effort was initiated in Italy under the auspicious of the 1th ReLUIS project 2005-2008, which has lead to a number of publications and brilliant research effort on such an issue [Cairo and Dente 2007; Sica et al., 2007-2009-2011; Castelli & Maugeri 2007; Cairo et al. 2008; Di Laora 2009; Maiorano et al. 2009; Moccia 2009; Dezi et al. 2009-2010; etc.].

Many aspects of kinematic pile bending are now better understood, whilst others require further research and remain unsolved.

Unsolved issues on seismic soil-pile interaction

Less research has been carried out on **short piles** and/or interfaces located close to the pile head.

Lack of simple formulations for assessing kinematic moments at the pile head for **non homogeneous** soils.

Material **nonlinearity** and **plasticity** need to be explored in a more systematic way, despite recent progress.

The effect of the **transient nature** of the input motion on both kinematic and inertial bending moments along the pile requires further investigation.

Proper **summation rule** between kinematic and inertial bending moments should be defined.

Notwithstanding these issues ... Code indications

Soil-Pile Kinematic Interaction

and

EC8

Eurocode 8, prEN 1998-5, December 2003

- (3) Analyses to determine the internal forces along the pile, as well as the deflection and rotation at the pile head, shall be based on discrete or continuum models that can realistically (even if approximately) reproduce
.....
- (6) Bending moments developing due to kinematic interaction shall be computed only when all of the following conditions occur simultaneously:
- i. the ground profile is of type D, S1 or S2, and contains consecutive layers of sharply differing stiffness;
 - ii. the zone is of moderate or high seismicity, i.e. the product $a_g \cdot S$ exceeds 0,10 g ,
 - iii. and the supported structure is of importance class III or IV.
- (7) Piles should in principle be designed to remain elastic, but may under certain conditions be allowed to develop a plastic hinge at their heads.

Soil-Pile Kinematic Interaction

and

the Italian Code

Norme Tecniche per le Costruzioni, February 2008 (Italy)

§ 7.11.5.3.2 È opportuno che i momenti flettenti dovuti alla interazione cinematica siano valutati per

- le costruzioni di classe d'uso III e IV,
- per sottosuoli di tipo D o peggiori,
- in siti a sismicità media o alta ($a_g > 0,25g$)
- e in presenza di elevati contrasti di rigidezza al contatto fra strati contigui di terreno.

What is in progress in other European countries ???

RELUIS project 2005-2008: Deep Foundations

(Research Theme 6.4 - Coordinator: A.L. Simonelli)

The main objective of the project is to individuate elements to be introduced in the technical code, regarding the **seismic design of deep foundations**, with particular attention to the effects of **kinematic interaction**.

Questions (before ReLUIS).... and answers (after ReLUIS)

In which cases kinematic interaction should be taken into account ?
(subsoil category, soil layer stiffness contrast, sismicity level)

Which are the factors affecting pile kinematic bending ?
(soil damping, pile-end conditions, soil nonlinearity, wave-forms, etc.)

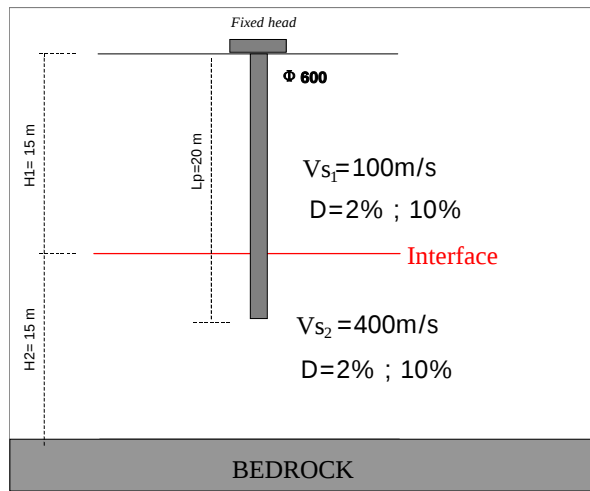
Which are the analytical tools to evaluate kinematic interaction (in the p.b.d. approach) ?
(from complex dynamic analyses ... to simplified ones ?)

Are the closed-form solutions available in literature effective ?
(Dobry&O'Rourke, 1983; Nikolaou et al., 2001; Mylonakis, 2001)

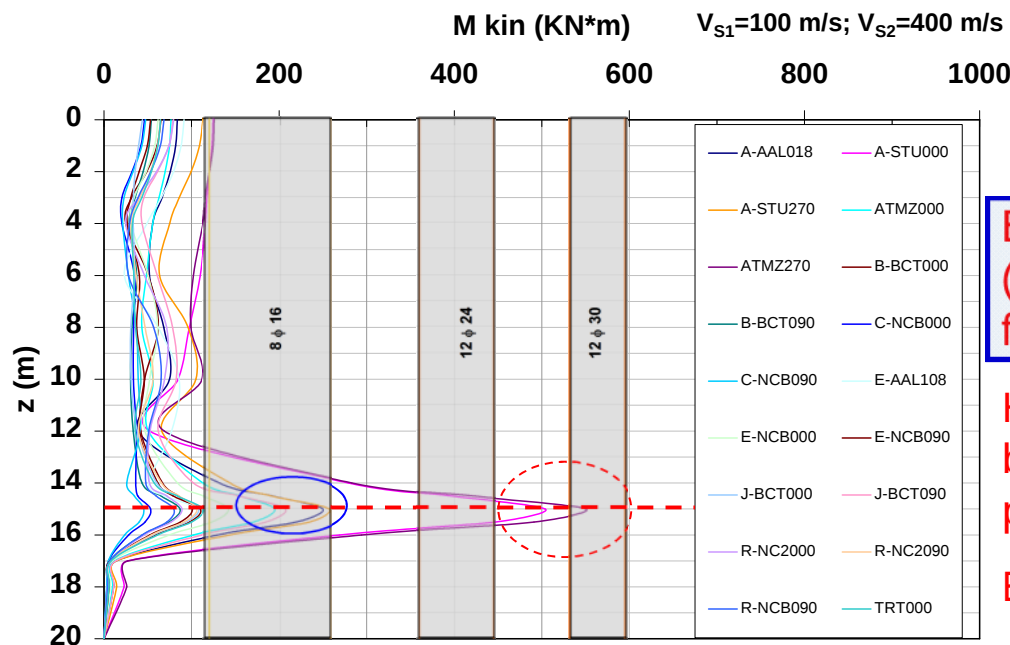
RELUIS project: main numerical results

Subsoil configuration S1

(H1=15m ed H2=15m) $V_{s,30}=160$ m/s - subsoil type D



- BDWF Analysis
- Input motions from SISMA, scaled to the same PGA
- Grey vertical bands represent M_y for typical pile reinforcement configurations



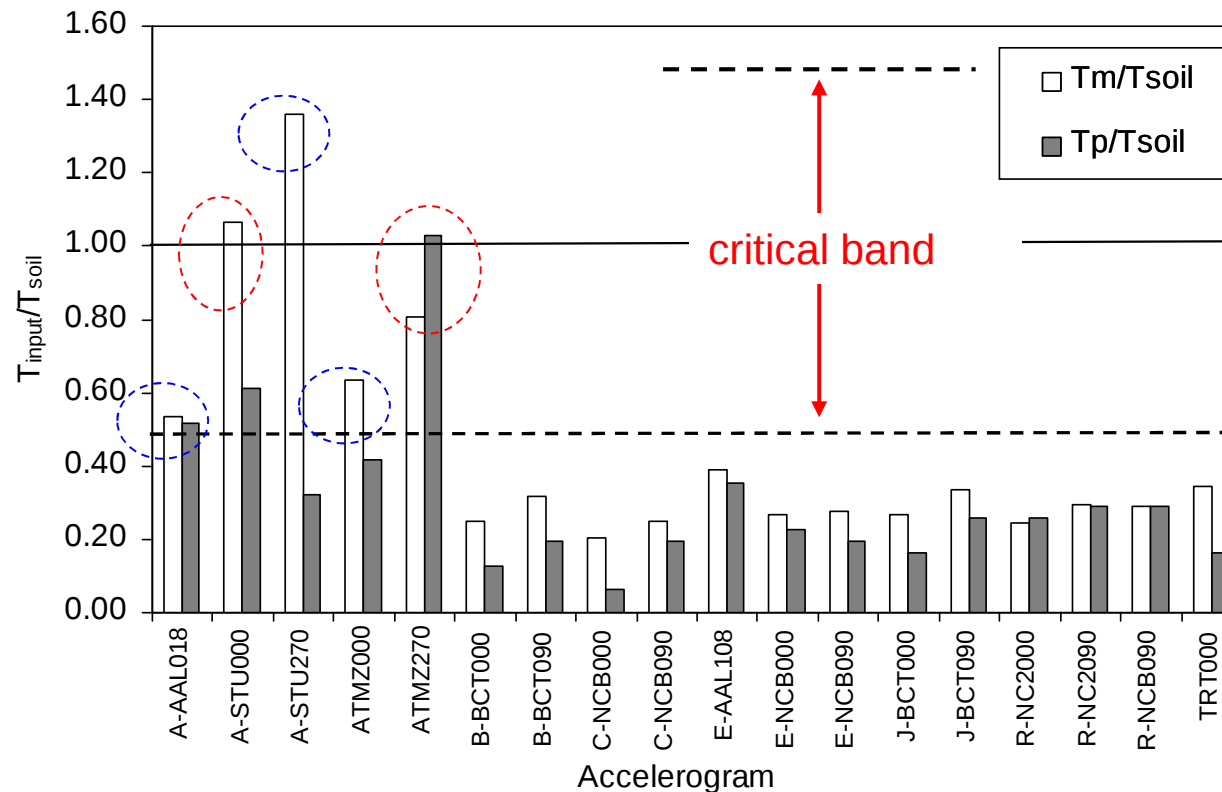
Bending moments are very high for 2 (over 18) accelerograms and still high for other 4 input motions

Huge effects of dynamic interaction between the input waveform and the pile-soil system

Bending moments can not exceed M_y
results on www.reluis.it

A simple criterion to investigate waveform-subsoil “coupling” effects

T_{input} $\begin{cases} T_m = \text{Mean period of an accelerogram by Rathje et al. (1998)} \\ T_p = \text{predominant period from the acceleration response spectrum (@ damping=5\%)} \end{cases}$

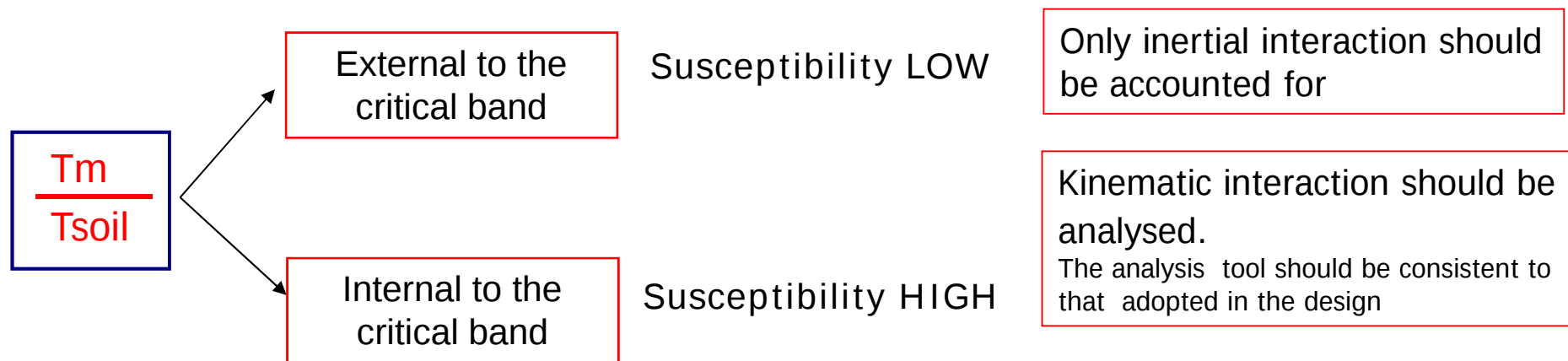
$$T_m = \frac{\sum c_i^2 \cdot \left(\frac{1}{f_i}\right)}{\sum c_i^2}$$


Effect of the
ratio
between
the dominant period
of the input motion
and the
fundamental period of
the subsoil S1

A criterion to select significant time-histories from a database

Site susceptibility to significant kinematic effects

If for a given seismic zone the acceleration time-histories are provided (in addition to the peak ground acceleration a_{gR}) a simple criterion to define the “susceptibility of the site with the associated waveforms” to relevant kinematic bending in piles may be established.



Three alternative “code-oriented” simplified procedures for bending moment evaluation:

- 1) *Static approach based on Φ_1* (derived from *Mylonakis, 2001*)
- 2) *Dynamic approach based on Φ_2* (derived from *Mylonakis, 2001*)
- 3) *Dynamic approach based on η* (derived from *Nikolaou et al., 2001*)

from **Sica S., Mylonakis G., Simonelli A.L. (2011)**
Soil Dynamics and Earthquake Engineering, Vol. 31

Unsolved issues on seismic soil-pile interaction

Less research has been carried out on **short piles** and/or interfaces located close to the pile head.

Lack of simple formulations for assessing kinematic moments at the pile head for **non homogeneous** soils.

Material **nonlinearity** and **plasticity** need to be explored in a more systematic way, despite recent progress.

The effect of the **transient nature** of the input motion on both kinematic and inertial bending moments along the pile requires further investigation.

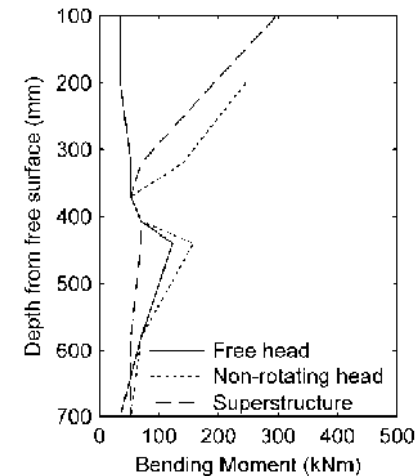
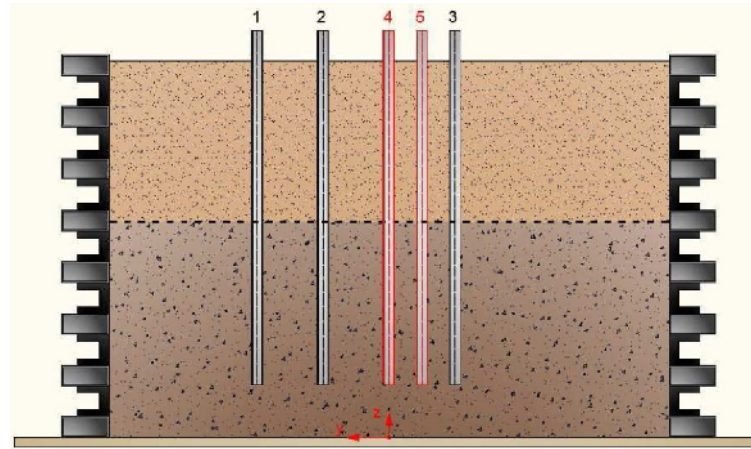
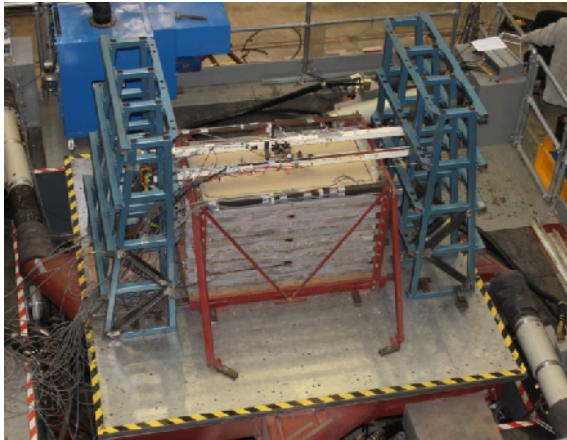
Proper **summation rule** between kinematic and inertial bending moments should be defined.

Need of **experimental data** to validate the huge amount of numerical findings.

The reliability of **existing analytical formulations** to predict the inertial and kinematical bending moment along the pile, as a function of the soil and pile properties and the input ground motion characteristics, **should be assessed**.

PILESI Project (Bristol)

Experimental investigation of soil-pile-structure seismic interaction



Project leader: Prof. A. L. Simonelli (University of Sannio, Italy)

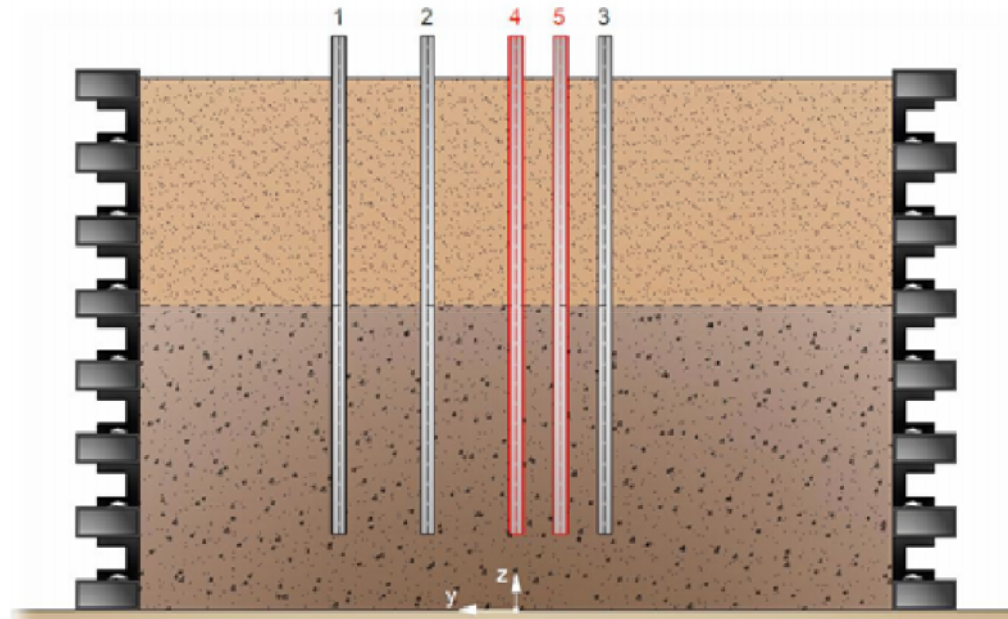
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Experimental variables: Pile head fixity, Pile-structure interaction, input motion

Methodology: **A shear stack is used to apply appropriate boundary conditions**
Controlled Sand Deposition is used to impose a stiffness contrast between upper and lower soil layers.

Model details

SOIL: Granular 2-layer deposit



Upper layer:

340 mm thick

Leighton Buzzard sand (Fraction E)

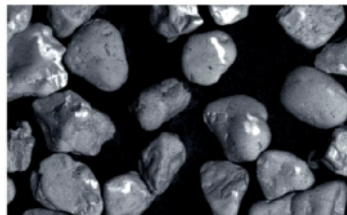
Bottom layer:

460 mm thick

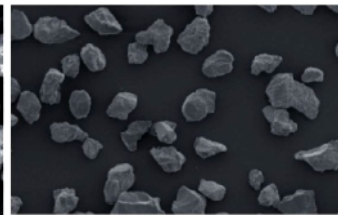
Leighton Buzzard

Fraction E + LB-Fraction B

LB-Fraction B



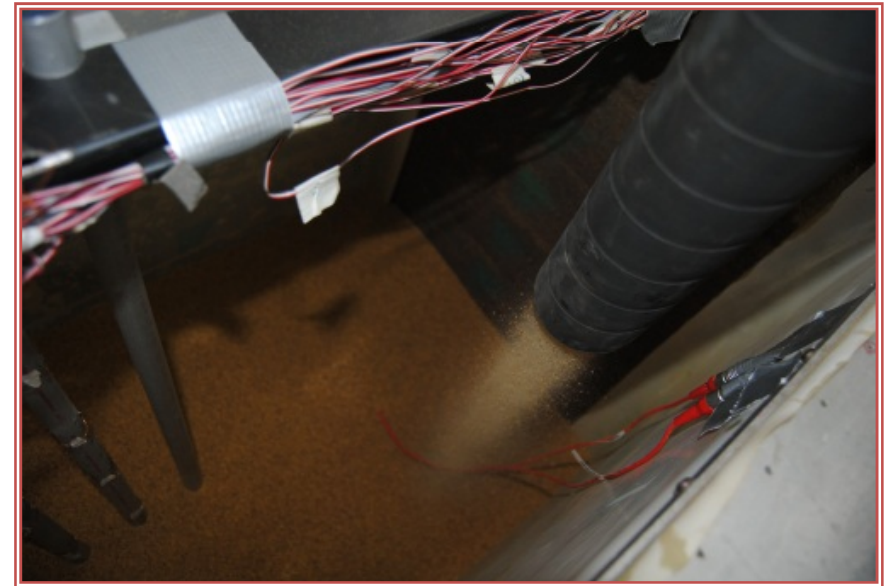
LB-Fraction E



Model details

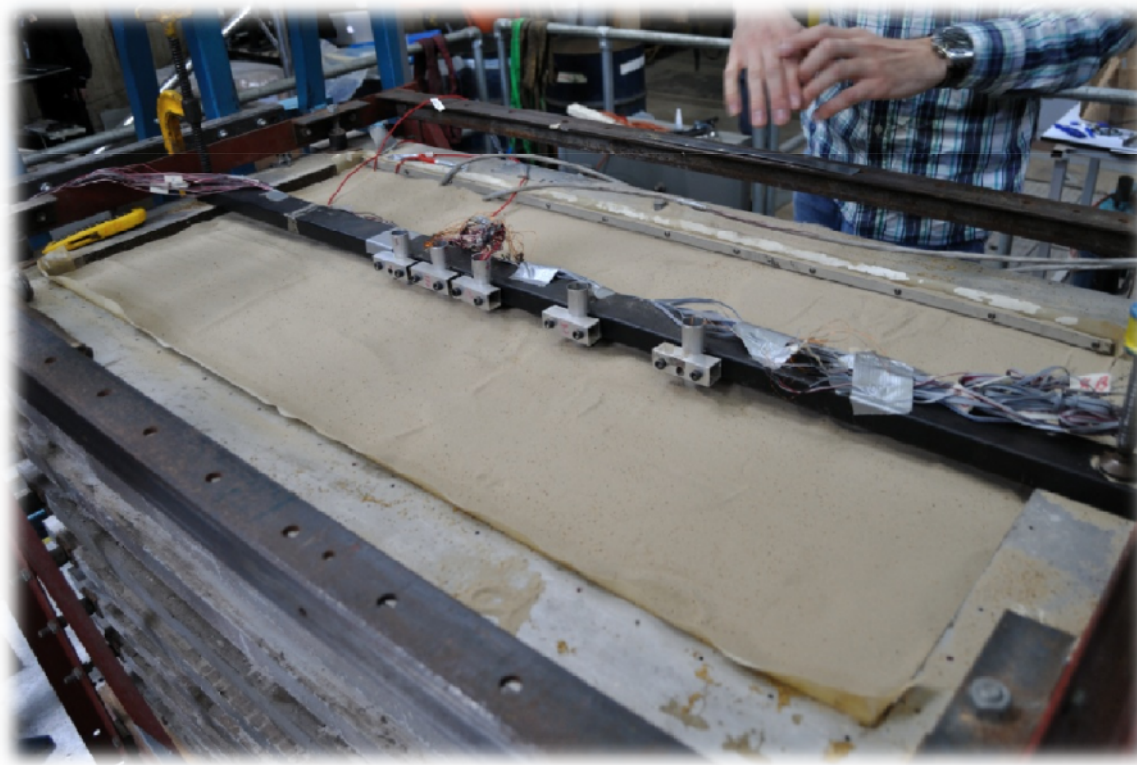


SOIL DEPOSITION



Model details

SOIL DEPOSITION



Model details

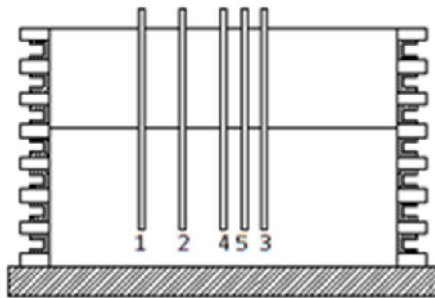


Piles and strain gauges

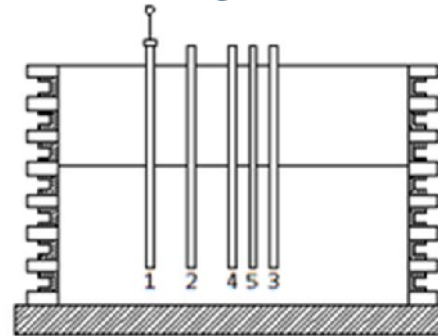


Model configurations

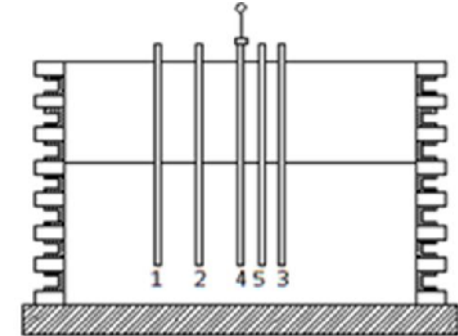
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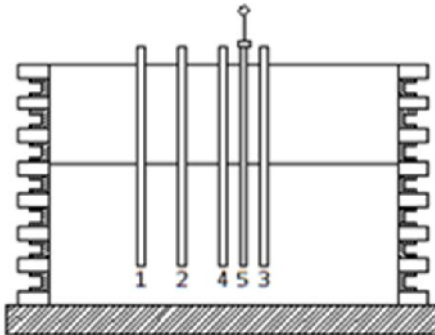
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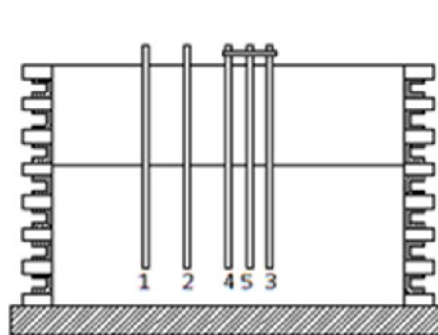
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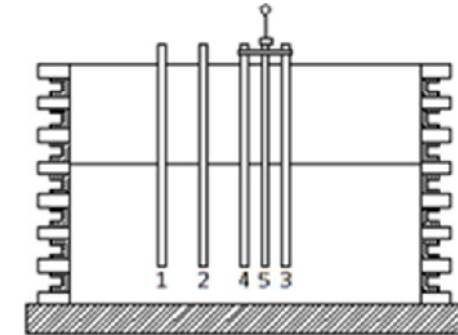
4)



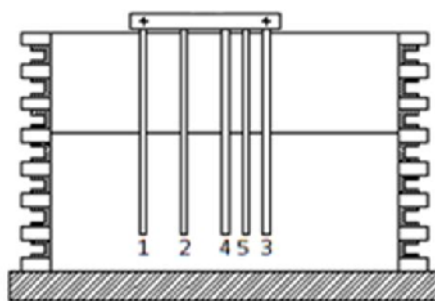
5)



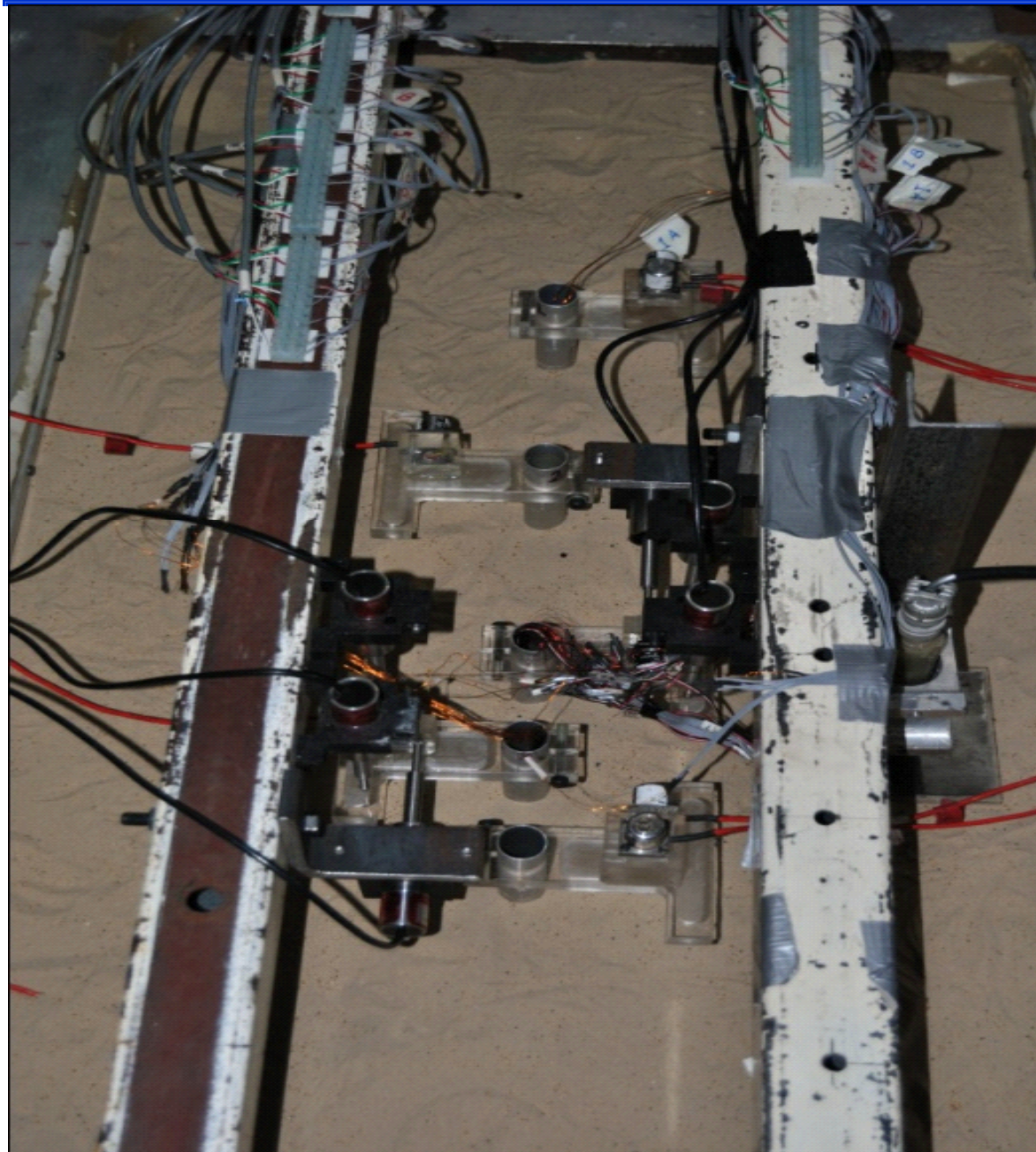
6)



7)

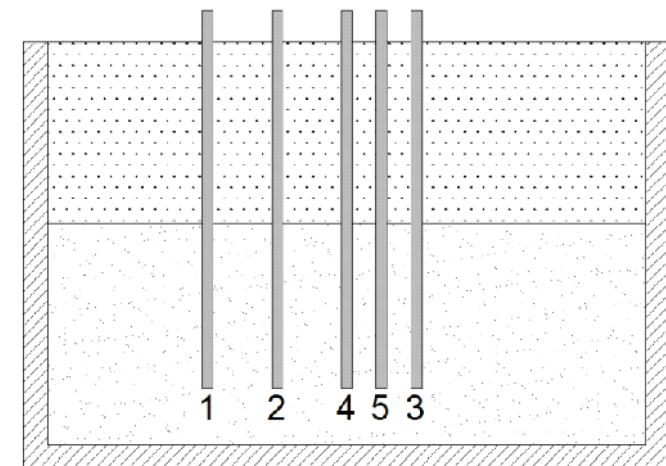


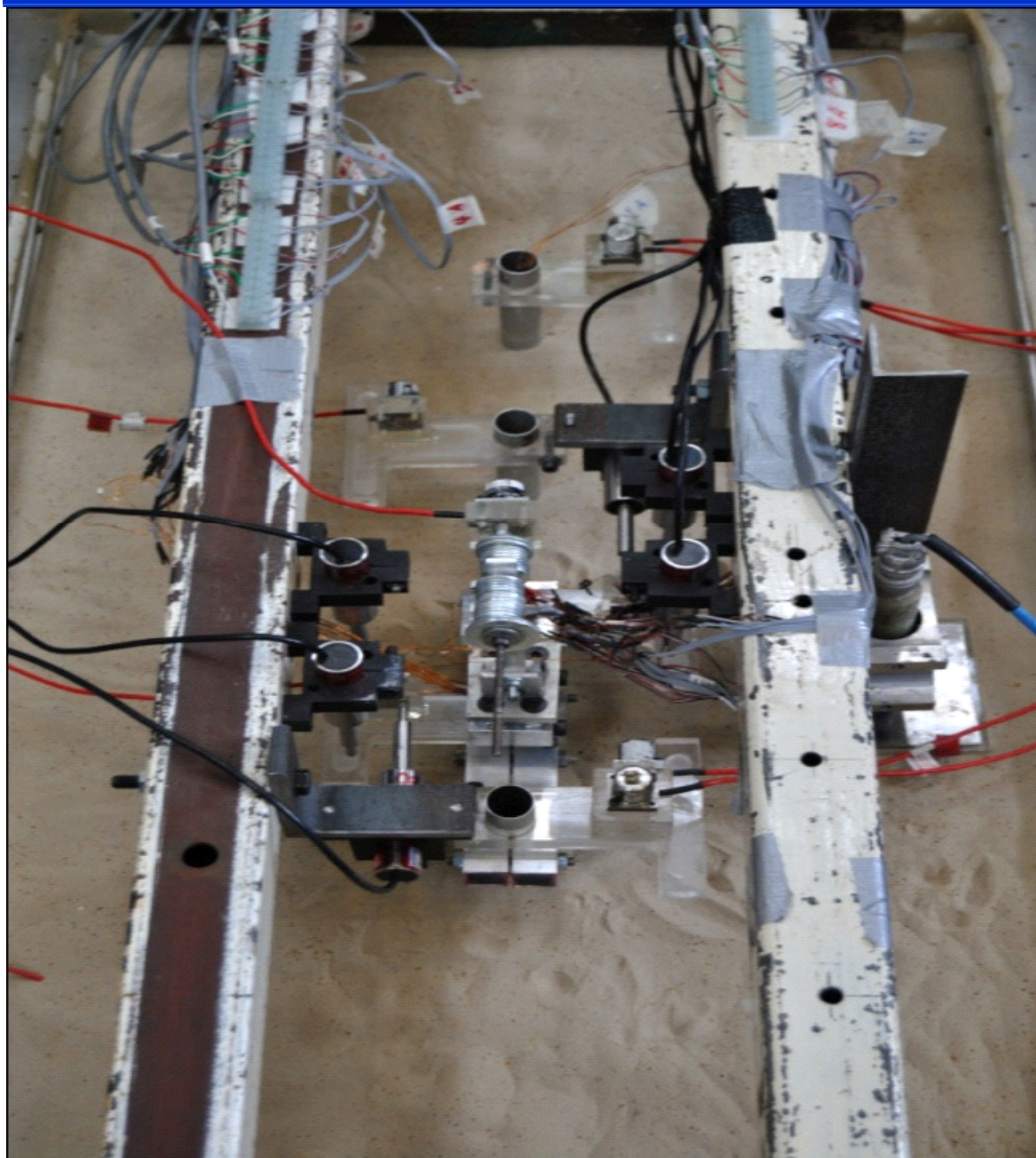
- 1) Free head pile
- 2) SDOF on pile 1
- 3) SDOF on pile 4
- 4) SDOF on pile 5
- 5) Short cap connecting piles 3,4,5
- 6) Short cap with SDOF on pile 5
- 7) Long cap from pile 1 to pile 3



Model configurations

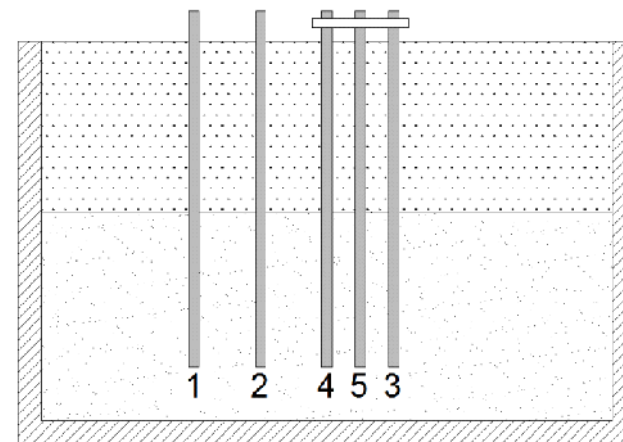
Free Head Pile

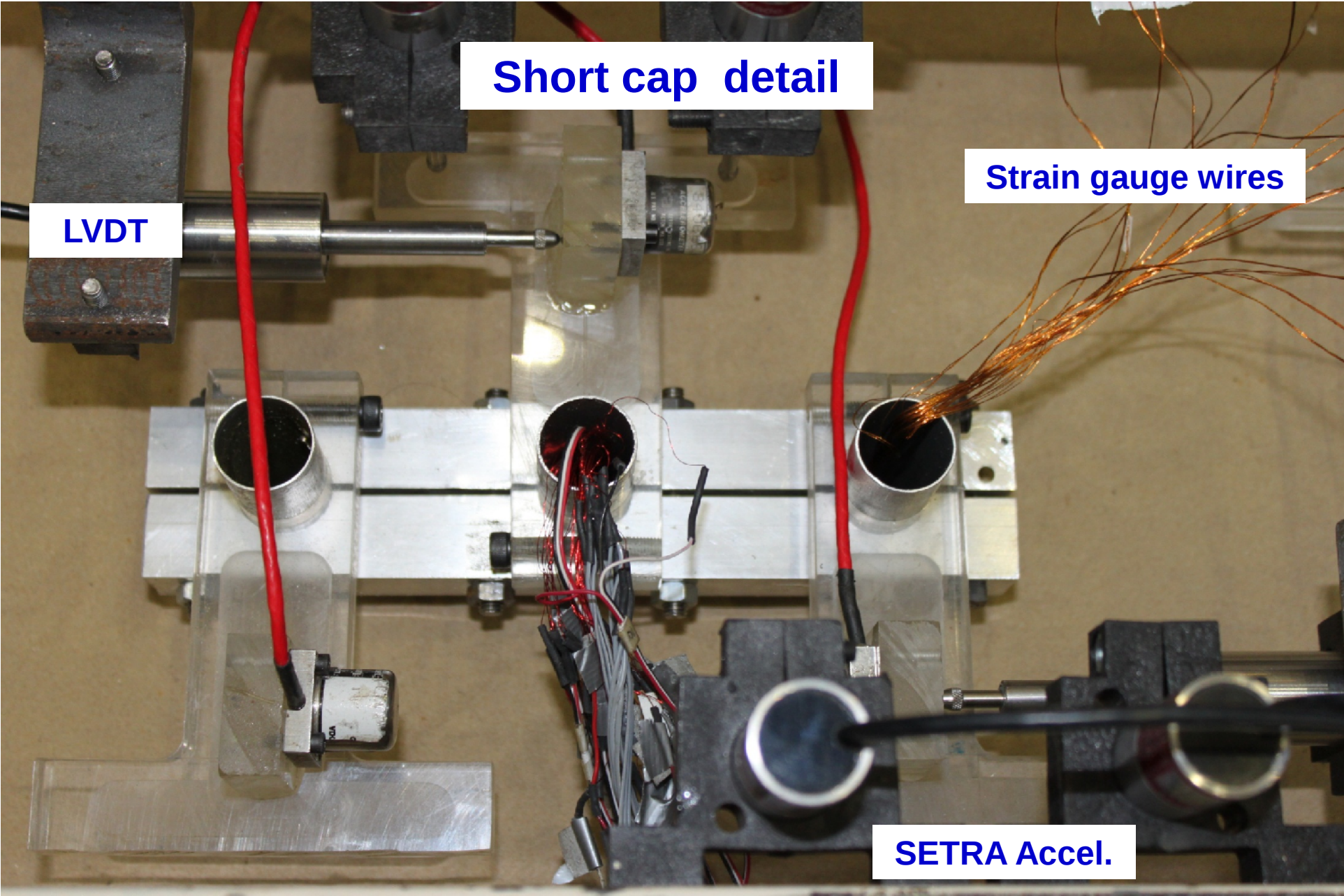




Model configurations

Short cap





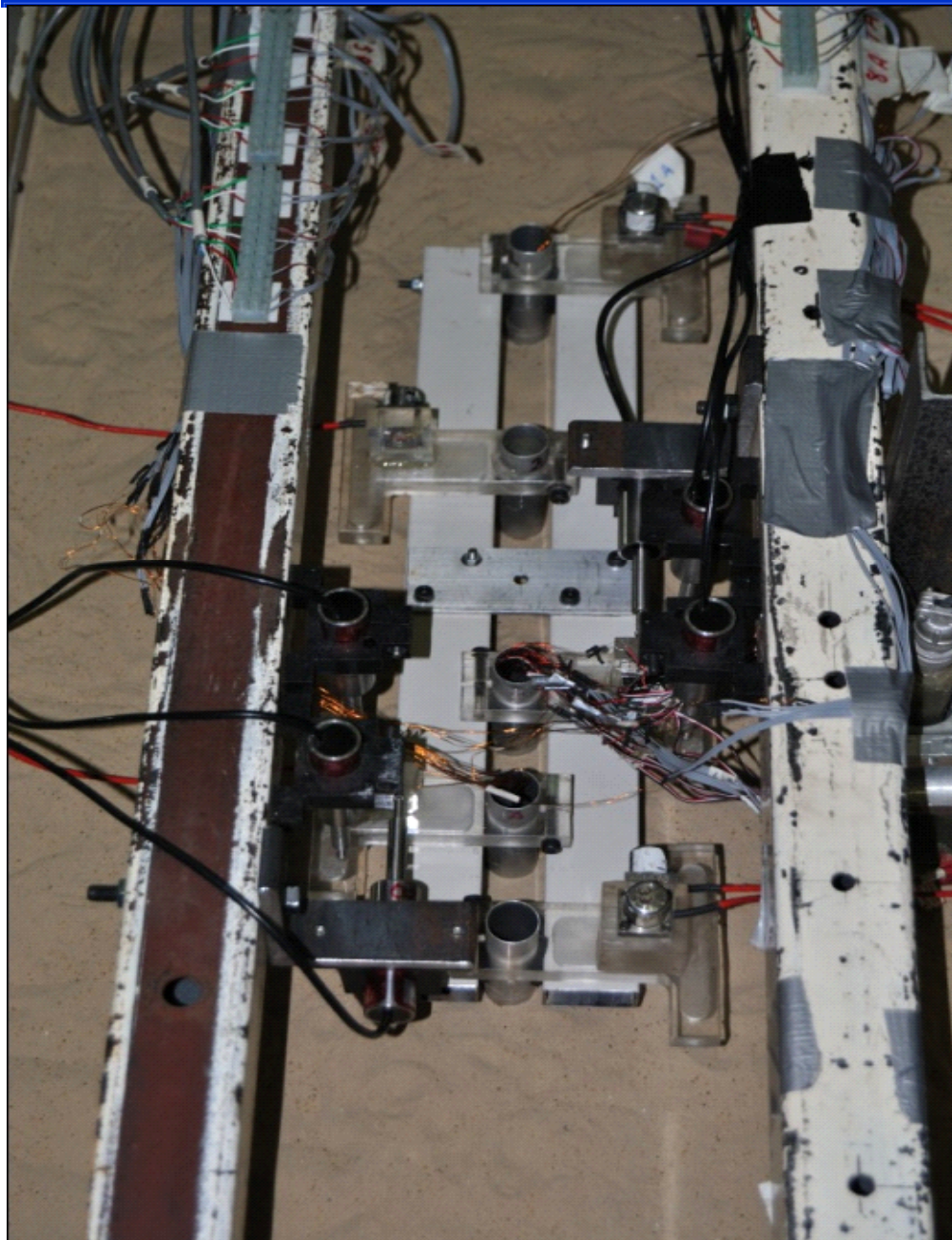
Short cap detail

The image shows a mechanical test setup. A central horizontal aluminum bar is supported by a base. A vertical rod passes through the bar, with a 'Short cap detail' at the top. A 'LVDT' is connected to the rod. 'Strain gauge wires' (copper) are connected to the bar. A 'SETRA Accel.' sensor is mounted on the base. Red and black wires are connected to the setup.

LVDT

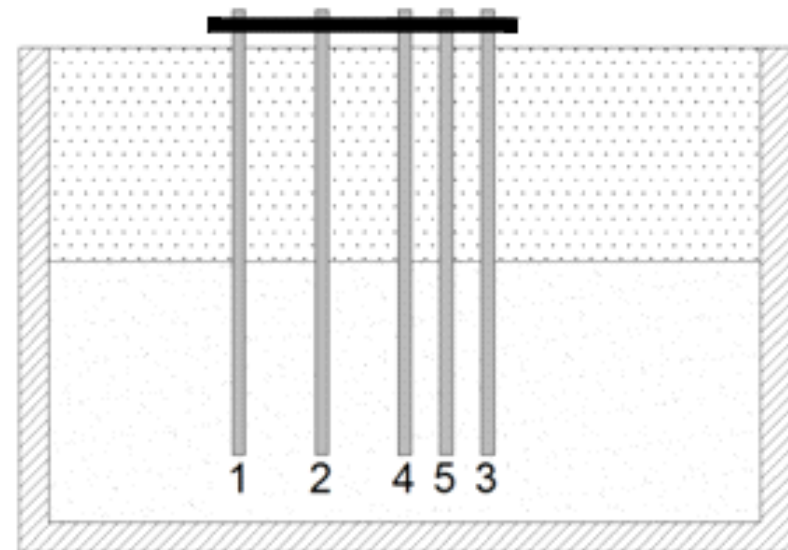
Strain gauge wires

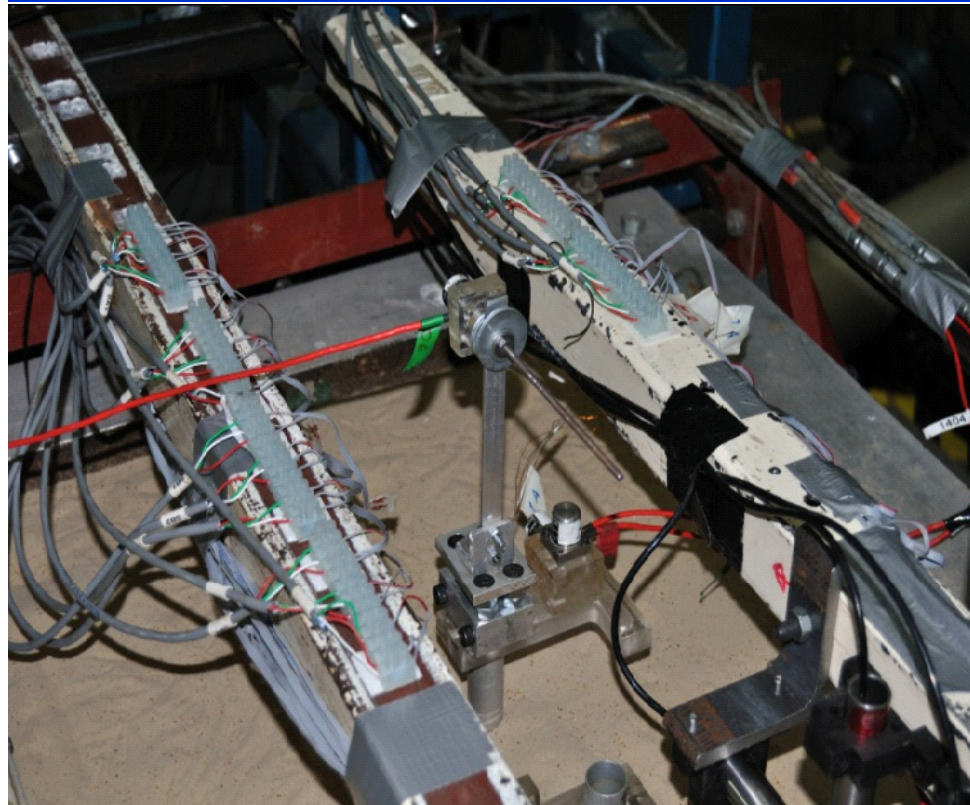
SETRA Accel.



Model configurations

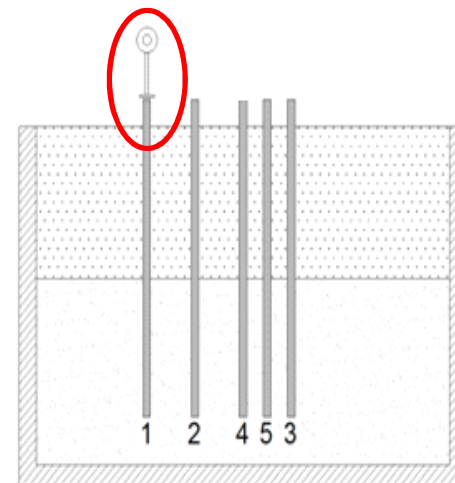
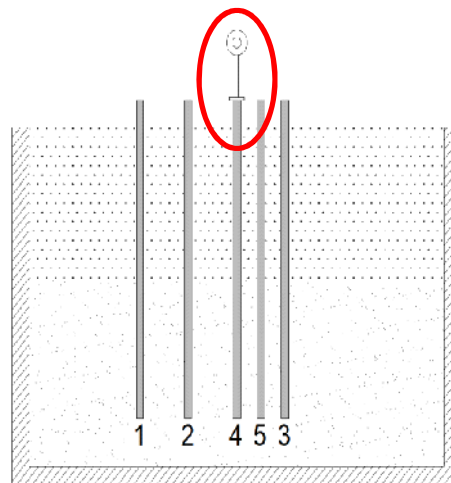
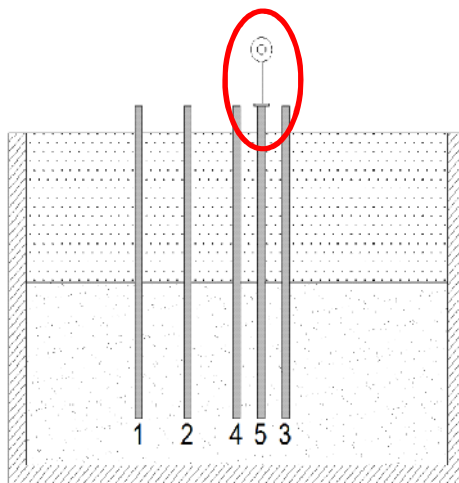
Large cap

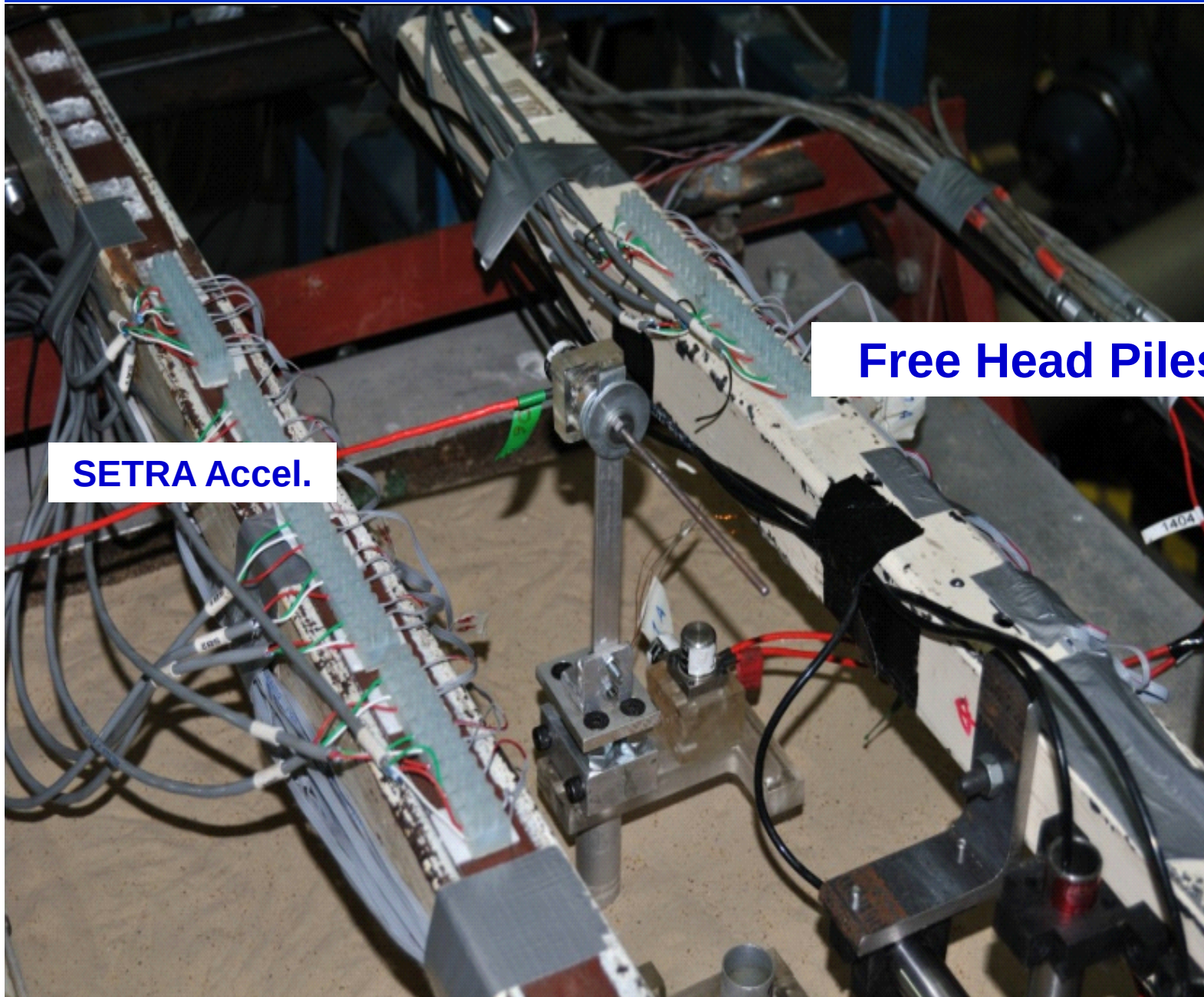




Model configurations With SDOF

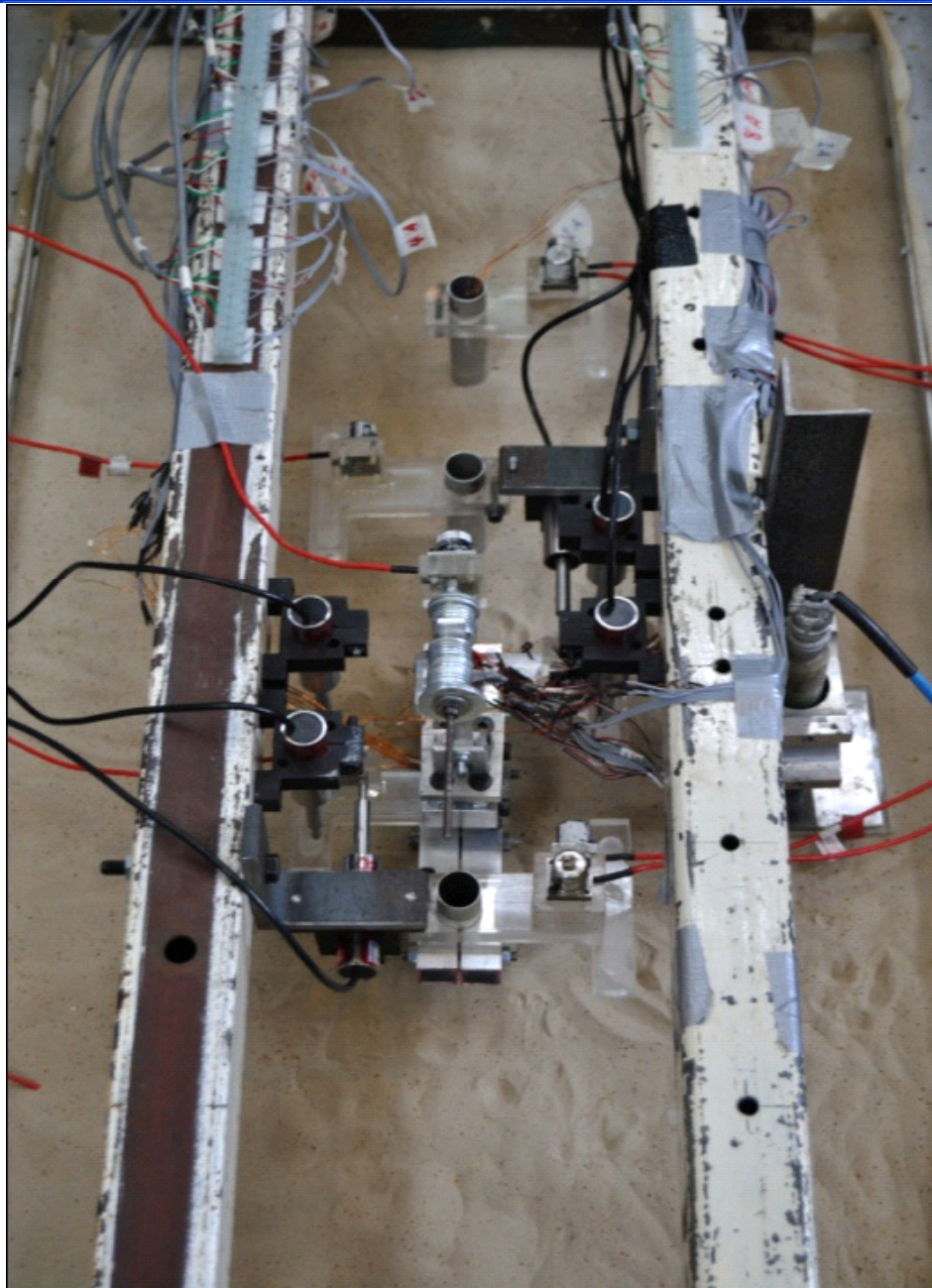
Free Head Piles + SDOF





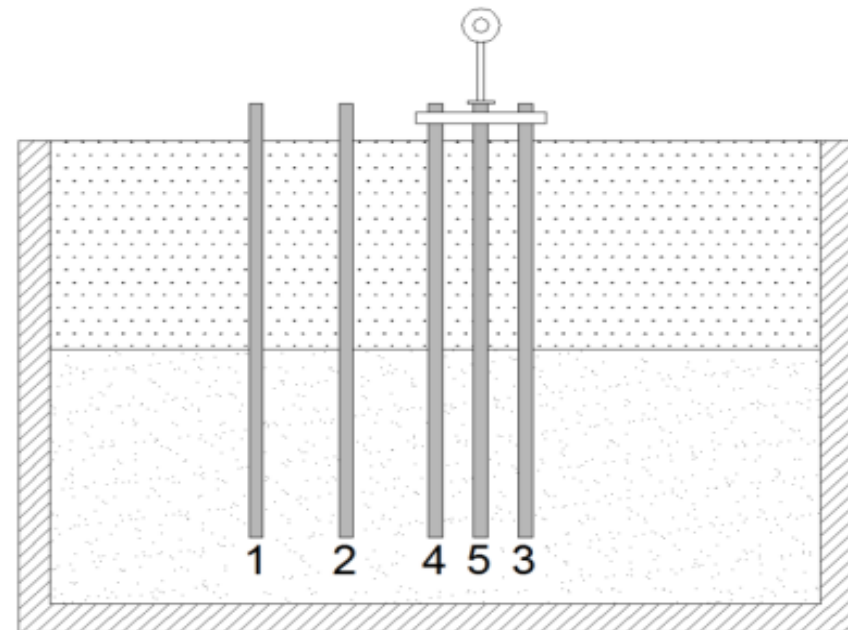
SETRA Accel.

Free Head Piles + SDOF



Model
configurations
With
SDOF

Short cap + SDOF

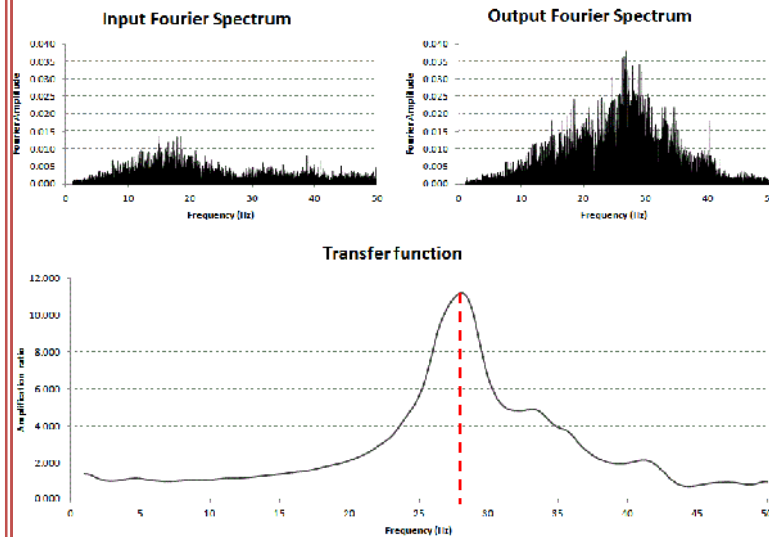


Test objectives

<i>test - input motion</i>		<i>objective</i>
Horizontal white noise test	<i>White noise signals applied on the vibrating table along u direction</i>	Horizontal natural frequency of the system; Shear stack influence on the system motion
Horizontal sinedwell		Dynamic interaction factors
Vertical white noise		Natural frequency of the system
Vertical sinedwell		Dynamic interaction factors
Static impedance test (Pul		Components of stiffness
	<i>measure pile head deflection at two points</i>	Matrix
Dynamic impedance test	<i>Horizontal motion applied to the shaking table. The shear stack is arranged in configuration LC</i>	K _{vv} , K _{rr} , K _{rv} components of stiffness matrix
Snapback test	<i>Traction and quick release applied on pile 5 head</i>	Natural frequency and damping of the embedded pile
Earthquake tests	<i>Frequency scaled seismic motions applied on the shaking table</i>	Observe the behavior under seismic motion

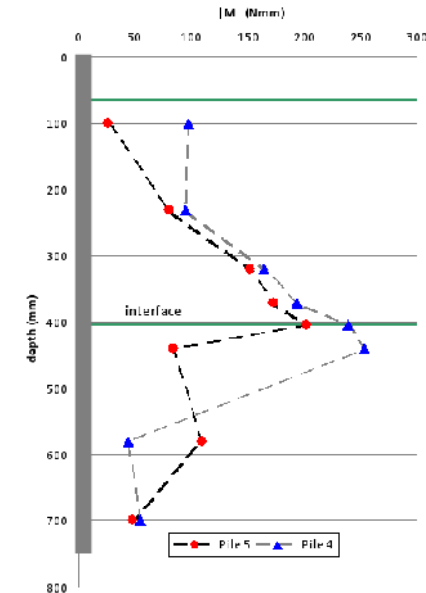
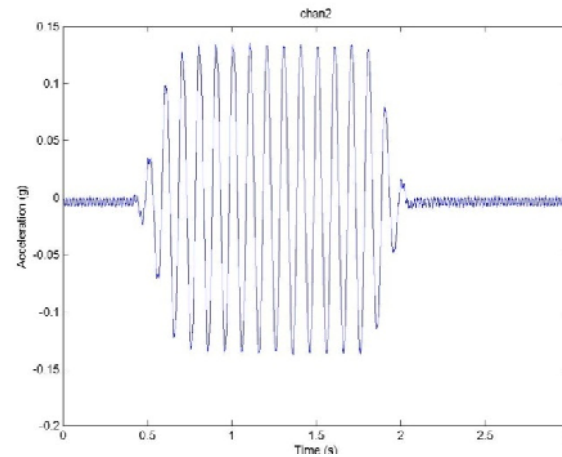
***total no. of tests :
about 600 !***

White noise test

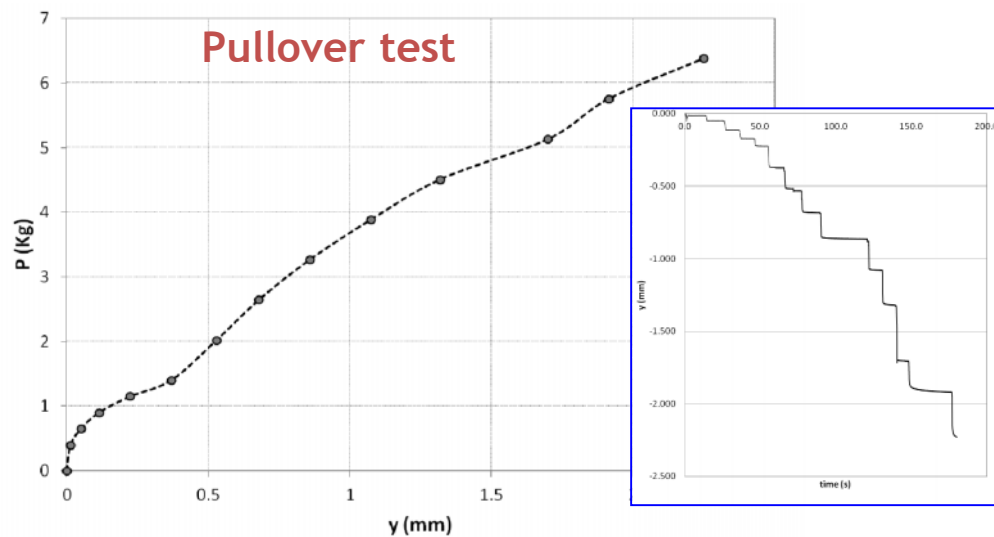


Sinedwell test

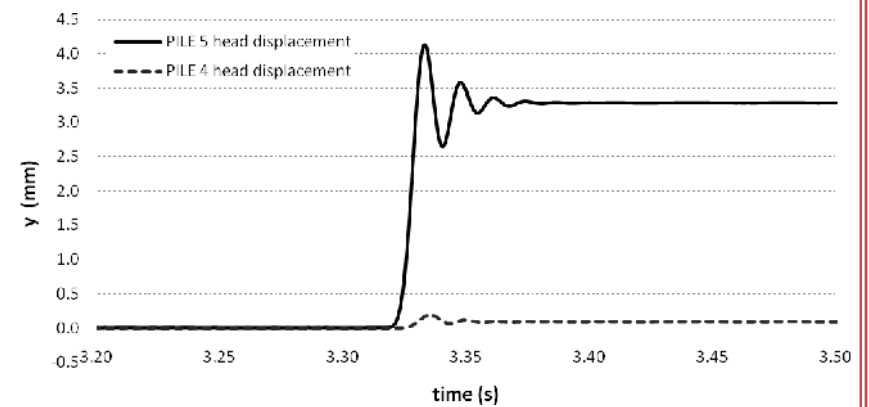
Test 101115-D7R1



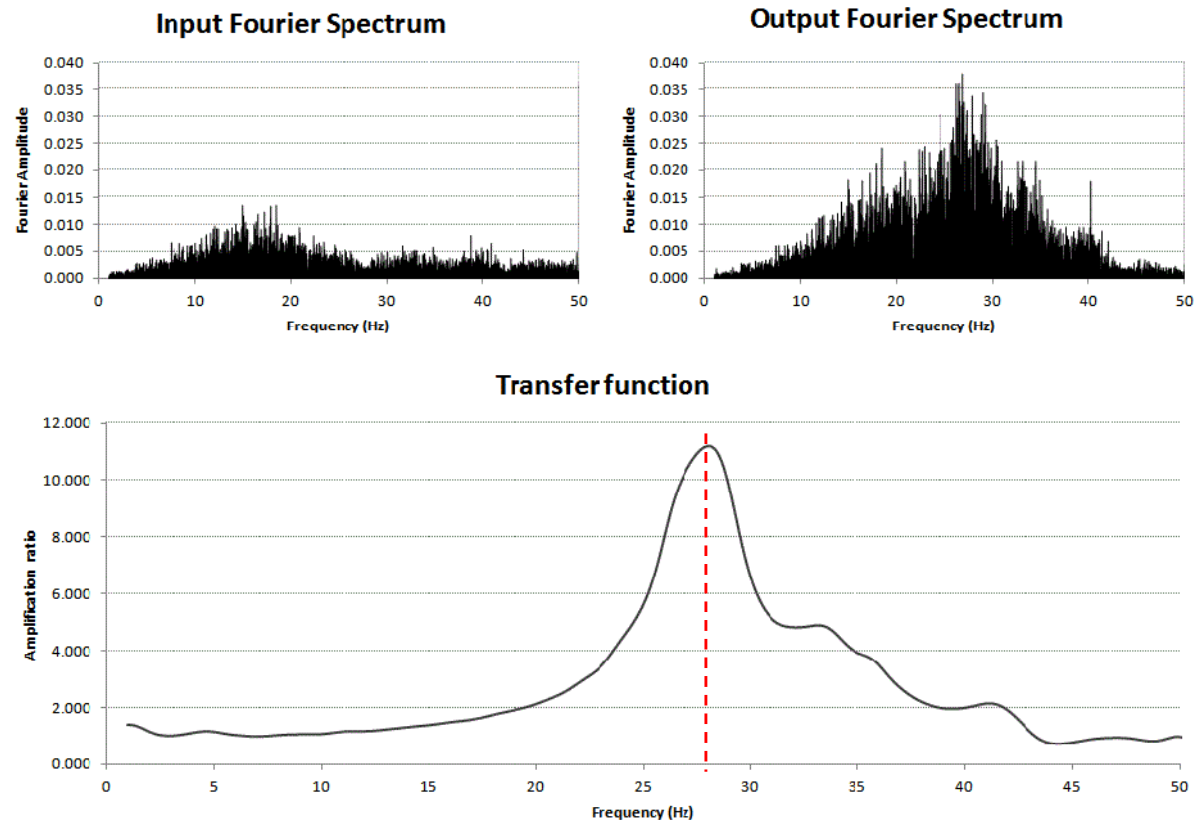
Pullover test



Snapback test



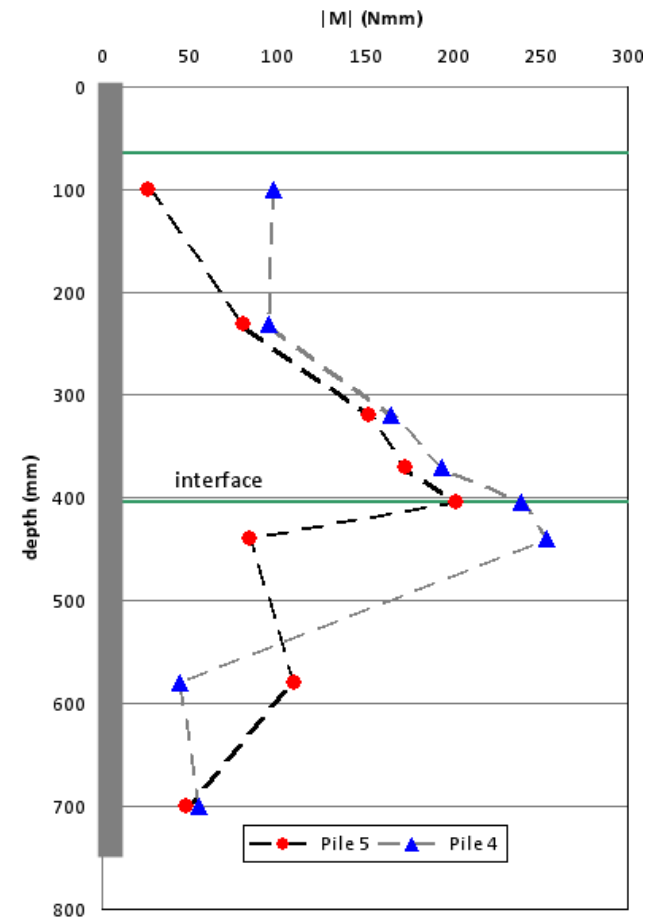
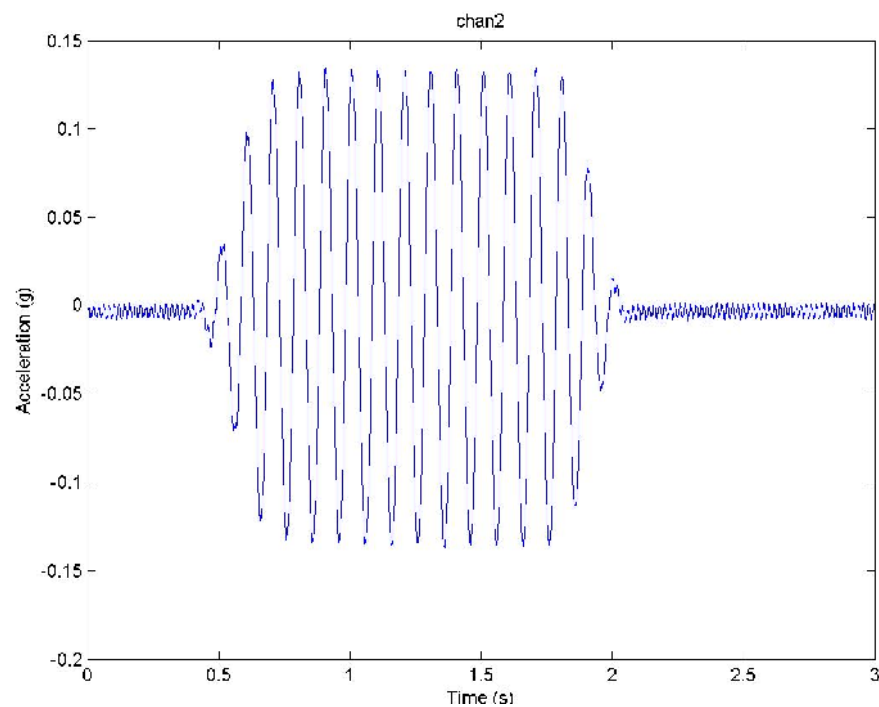
White noise test



*Horizontal natural
frequency of the system*

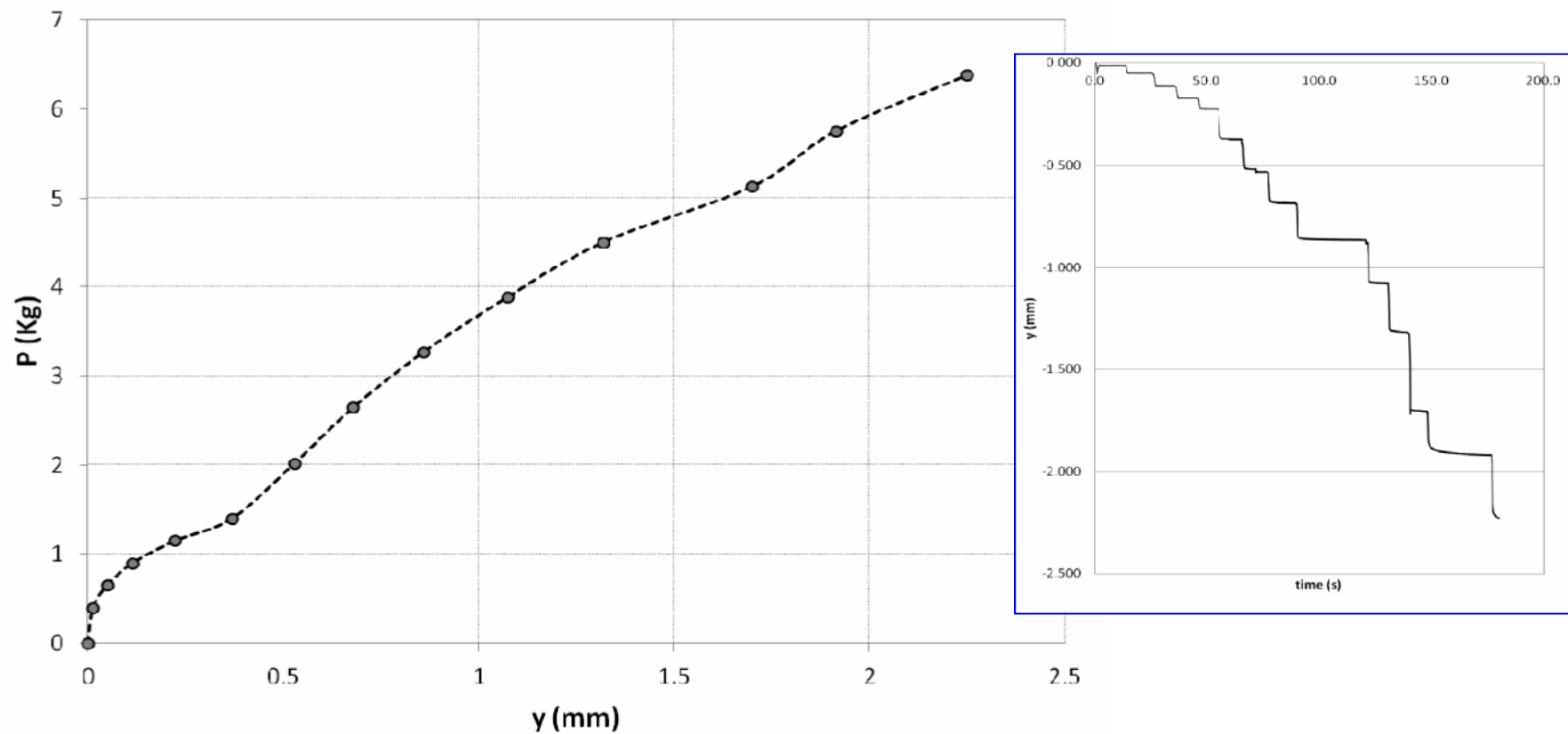
Sinedwell test

Test 101115-D7R1



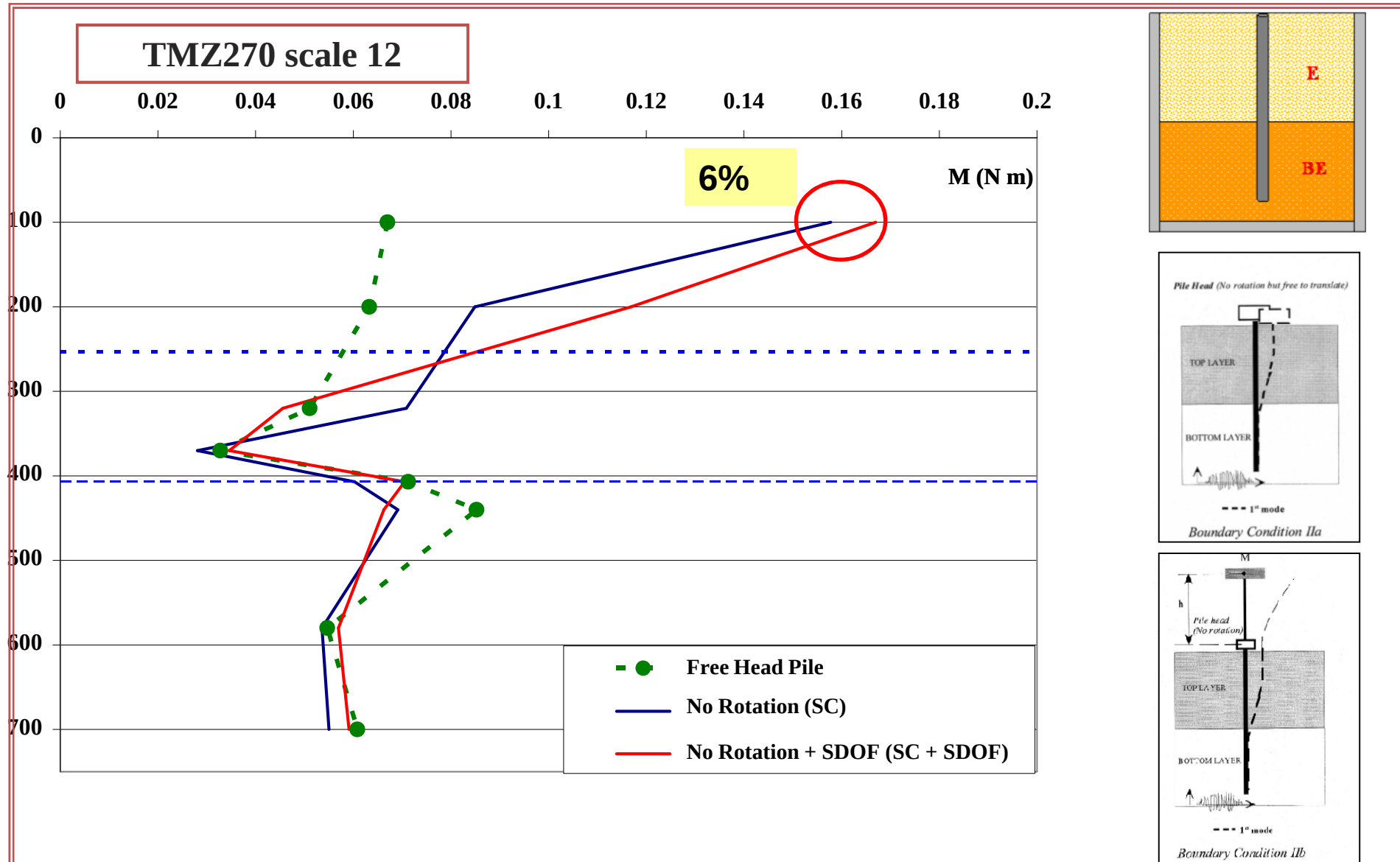
Horizontal kinematic interaction

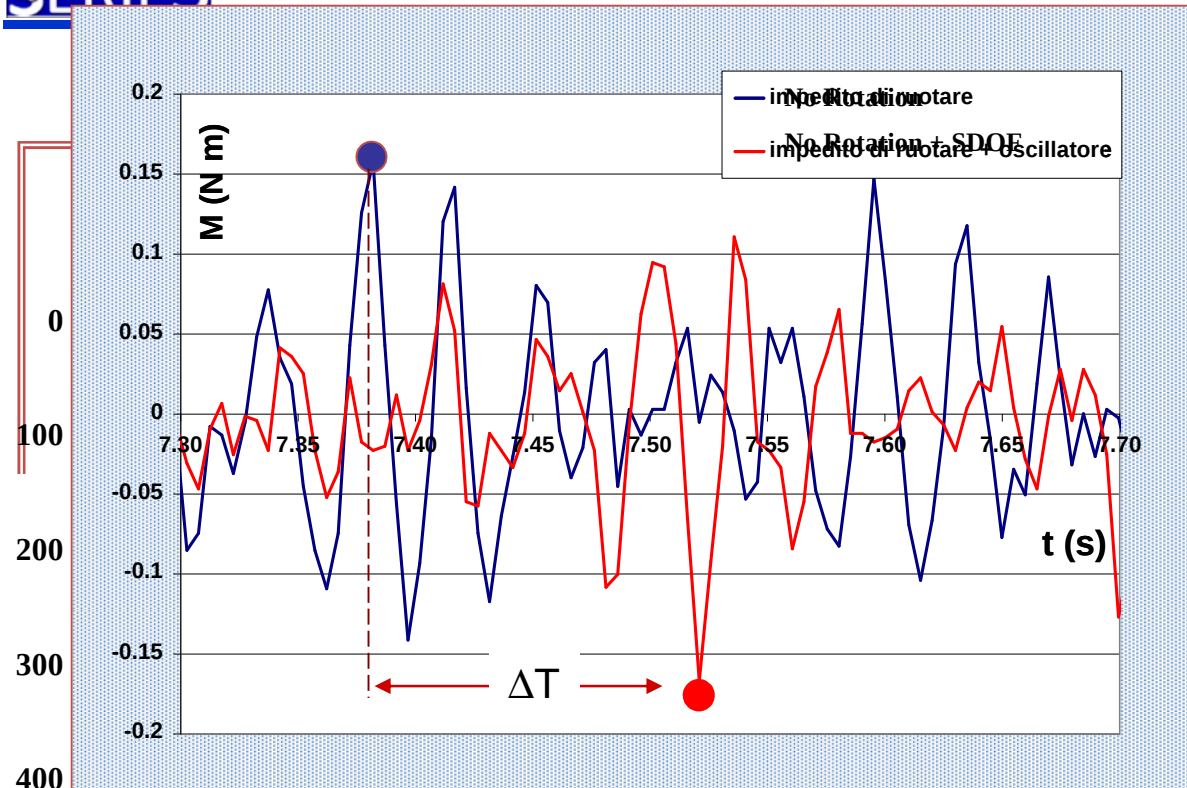
Pullover test



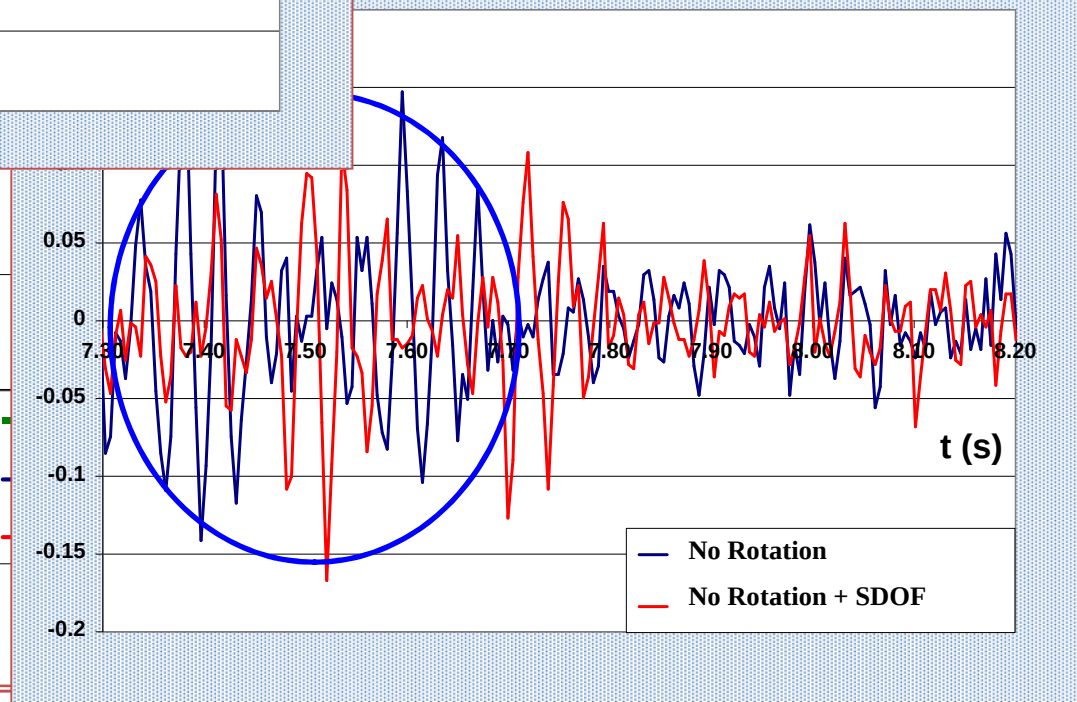
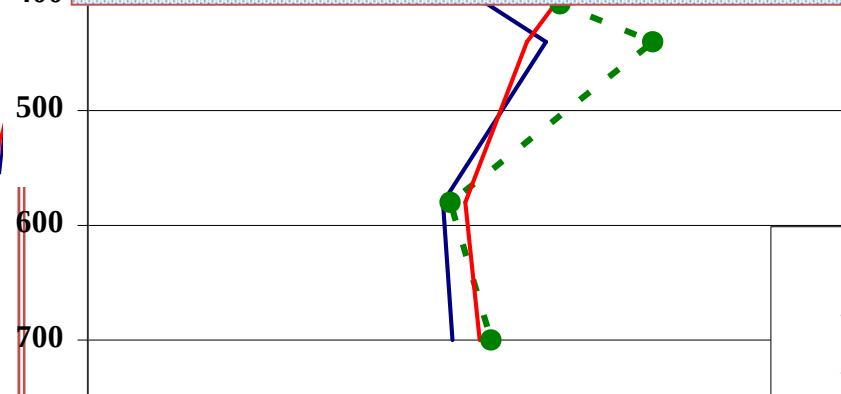
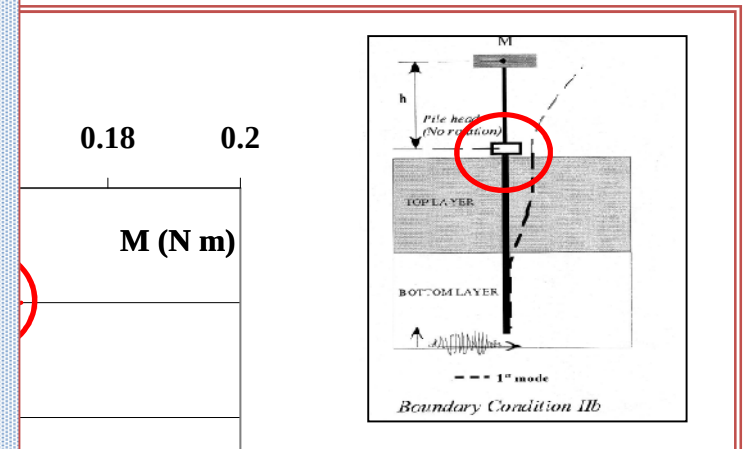
Static impedance test

Kinematic and Inertial bending moments

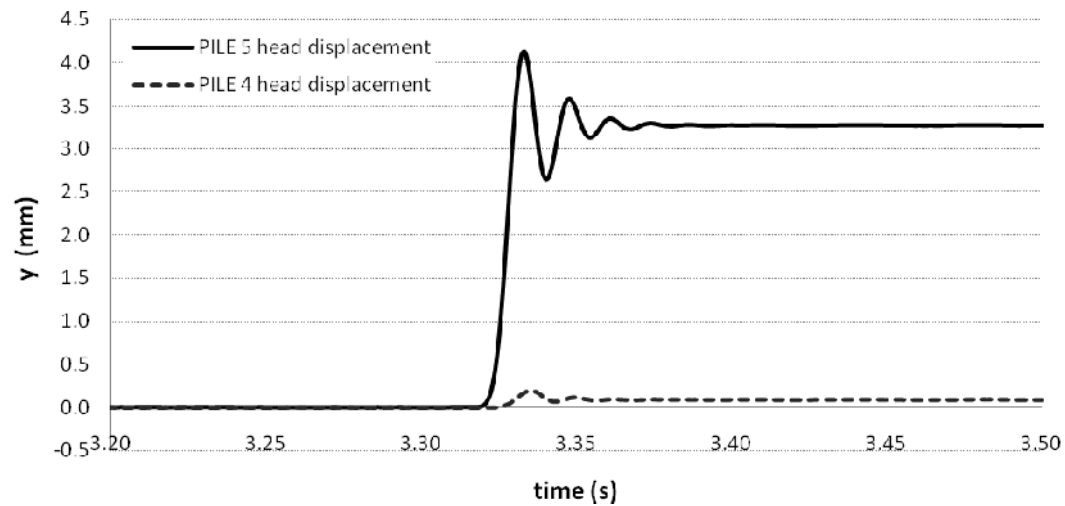




ing moments



Snapback test



Natural frequency and damping of the embedded pile





SERIES

SEISMIC ENGINEERING RESEARCH INFRASTRUCTURES
FOR EUROPEAN SYNERGIES



*Thank you
for
your attention*