

Rolling-Contact Bearings

- Rolling-contact bearing, anti friction bearing, and rolling bearing are all used to describe that class of bearing in which the main load is transferred through elements in rolling contact.
- The four essential parts of a bearing are the outer ring, the inner ring, the balls or rolling elements, and the separator. (Figure 11-1)
- Types of bearings (Figure 11-2 and 11-3)
- Bearings are manufactured to take pure radial loads, pure thrust loads, or a combination of the two kinds of loads.

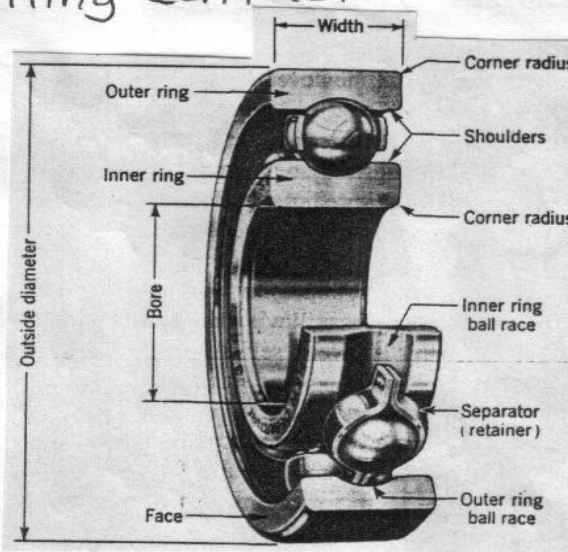


Figure 11-1
Nomenclature of a ball bearing.
(Courtesy of New Departure-Hyatt Division, General Motors Corporation.)

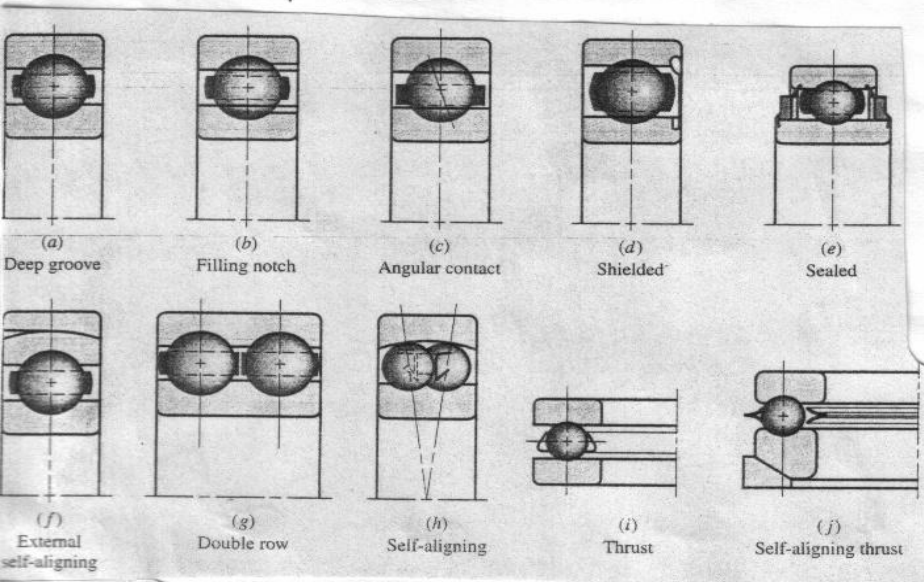


Figure 11-2
Various types of ball bearings.

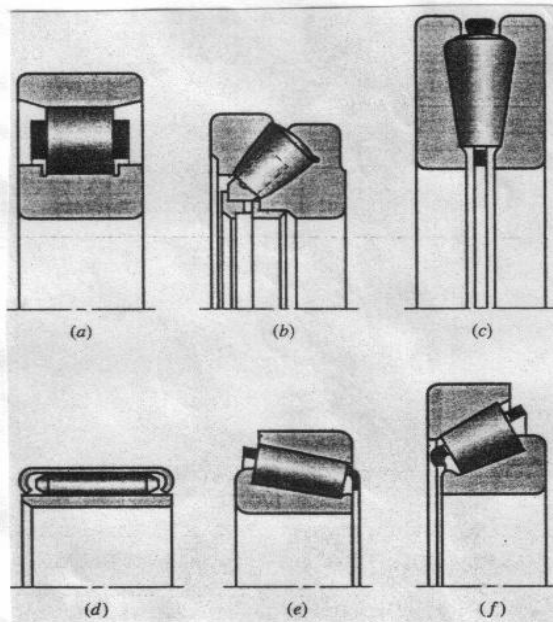


Figure 11-3
Types of roller bearings: (a) straight roller; (b) spherical roller, thrust; (c) tapered roller, thrust; (d) needle; (e) tapered roller; (f) steep-angle tapered roller. (Courtesy of The Timken Company.)

Bearing life

$$F_e \cdot L^{1/a} = C \Rightarrow L = \left(\frac{C}{F_e} \right)^a$$

(million cycles)

$a=3$ for ball bearings

$a=10/3$ for roller bearings (cylindrical and tapered roller)

C : dynamic load factor

$$F_e = X \cdot F_r + Y \cdot F_a$$

↖ radial load
↘ axial load

equivalent load

$$F_e \leq C_0$$

Static load factor

$$\frac{F_a}{V \cdot F_r} \Rightarrow X, Y$$

Table 11-5

$$C_0 = S_0 \cdot F_e$$

$V=1$ (inner ring rotates)
 $V=1.2$ (outer ring rotates)

$$L_h = \frac{L \cdot 10^6}{60 \cdot n}$$

operating hours

Lubrication

- Use grease when
 - The temperature is not over 200°F. (93°C)
 - The speed is low.
 - Unusual protection is required from the entrance of foreign matter.
 - Simple bearing enclosures are desired.
 - Operation for long periods without attention is desired.
- Use oil when
 - Speeds are high
 - Temperatures are high
 - Oiltight seals are readily employed.
 - Bearing type is not suitable for grease lubrication.
 - The bearing is lubricated from a central supply which is also used for other machine parts.

Mounting

- One bearing at each end of a shaft.
 - The inner rings are backed up against the shaft shoulders and are held in position by round nuts threaded onto the shaft.

Bearing Load-Life Trade-Off at Constant Reliability

$$C_{10} \cdot L_{10}^{1/a} = F \cdot L^{1/a}$$

$$C_{10} \cdot (L_R \cdot n_R \cdot 60)^{1/a} = F_D \cdot (L_D \cdot n_D \cdot 60)^{1/a}$$

catalog rating \uparrow C_{10}
 rating life in hours \uparrow L_R
 rating speed, rpm \uparrow n_R
 desired radial load \uparrow F_D
 desired life, hours \uparrow L_D
 desired speed, rpm \uparrow n_D

Load-Life-Reliability Trade-Off

$$C_{10} = F_D \cdot \left[\frac{x_D}{x_0 + (\theta - x_0) (\ln 1/R_D)^{1/b}} \right]^{1/a}$$

characteristic parameter corresponding to the 63.2121 percentile value of the variate

Variable Loading

$$F_{eq} = \left[\frac{\sum n_i t_i F_i^a}{\sum n_i t_i} \right]^{1/a}$$

speed \uparrow F_i
 duration of speed (i) \uparrow $n_i t_i$

Adequacy Assessment for Selected Rolling-Contact Bearings

$$R = \exp \left(- \left\{ \frac{\left[x_D - x_0 \left(\frac{C_{10}}{f_A \cdot F_D} \right)^a \right]^b}{(\theta - x_0) \left(\frac{C_{10}}{f_A \cdot F_D} \right)^a} \right\} \right)$$

C_{10} : basic load rating

- The inner races are backed up against the shaft shoulders as before but no retaining devices are required.
 - Two or more bearings at one end of shaft
 - face-to-face
 - back-to-back
 - tandem arrangement
 - The inner ring usually takes circumferential load
 - The outer ring usually takes point load
- the direction of load changes over time
- the direction of load doesn't change over time

The mounting rule

- The ring taking circumferential load is mounted tightly.
- The ring taking point load is mounted less tightly.

Typical sealing methods

- Felt seals may be used with grease lubrication when the speeds are low.
- The commercial seal is an assembly consisting of the rubbing element, spring backing, which are retained in a sheet-metal jacket.
- The labyrinth seal is especially effective for high-speed installations and maybe used with either oil or grease.

Lubrication and Journal Bearings

DCR 501E-400

Types of Lubrication

- Hydrodynamic: Relative motion of surfaces
- Hydrostatic: Requires a pressure
- Elastohydrodynamic: Lubricant introduced in rolling contact.
- Boundary: Thin film
- Solid-film: Extreme temperatures. Graphite, molybdenum, composite bearing materials.

Viscosity

$$\tau = \frac{F}{A} = \mu \frac{du}{dy}$$

absolute (dynamic viscosity) μ
rate of shear (velocity gradient) $\frac{du}{dy}$

If $\frac{du}{dy}$ is constant, then $\frac{du}{dy} = \frac{U}{h} \Rightarrow \tau = \frac{F}{A} = \mu \frac{U}{h}$

Unit of viscosity Pa.s (pascal-second)

ASME cgs units dyn.s/cm² (P) (poise), cP (centipoise)

$$\mu (\text{Pa.s}) = (10)^{-3} Z (\text{cP})$$

kinematic viscosity $Z_k = \left(0.22t - \frac{180}{t} \right)$
cSt (centistoke) number of seconds Saybolt

$$\nu (\text{m}^2/\text{s}) = 10^{-6} Z_k (\text{cSt})$$

$$\nu = \left(0.22t - \frac{180}{t} \right) (10^{-6})$$

$$\mu = \rho \cdot \nu$$

Petroff's Equation

$$\tau = \mu \frac{U}{h} = \frac{2\pi r \rho N}{c}$$

$$T = (\tau A) \cdot (r) = \left(\frac{2\pi r \rho N}{c} \right) \cdot (2\pi r l) \cdot (r) = \frac{4\pi^2 r^3 L \rho N}{c}$$

$$T = f \cdot W \cdot r = \frac{4\pi^2 r^3 L \rho N}{c} \Rightarrow f = 2\pi^2 \frac{\rho N}{P} \frac{r}{c} \quad \uparrow P = \frac{W}{2rL}$$

$$S = \left(\frac{r}{c}\right)^2 \left(\frac{\mu N_j}{P}\right)$$

Journal radius (mm) → r
 absolute viscosity (Pa.s) → μ
 significant speed (r/s) → N_j
 bearing characteristic number (Sommerfeld number) → S
 radial clearance (mm) → c
 load per unit of projected bearing area (MPa) → P

Temperature rise

$$\dot{m} = l.c.f. \cdot \frac{U}{2} = l.c.f. \cdot \pi \cdot r \cdot N_j$$

heat loss rate by convection and radiation → \dot{Q}_{loss}
 journal angular speed → N_j
 $\dot{Q}_{loss} = U_o A_o (T_b - T_\infty) = U_o A_o (\bar{T}_f - T_\infty) / 2$
 overall combined coefficient → U_o
 bearing housing lateral surface area → A_o
 ambient temperature → T_∞
 bearing metal surface temperature → T_b
 average film temperature → $\bar{T}_f = T_s + \Delta T / 2$
 Not: bushing and housing metal temperature is midway between the \bar{T}_f and T_∞

$$\dot{Q}_{gen} = \dot{m} \cdot C_p \cdot \Delta T = l.c.f. \cdot \pi \cdot r \cdot N_j \cdot C_p \cdot \Delta T$$

heat generation rate by viscous friction

$$\dot{Q}_{gen} = 2\pi T N_j = 2\pi f W r N_j = 2\pi \frac{f r}{c} \frac{c}{r} r W N_j$$

$$= 4\pi^3 \left(\frac{r}{c}\right)^2 \frac{\mu N_j^2 (2rL)}{W} \frac{c}{r} r W N_j$$

$$\bar{T}_f = T_\infty + 16\pi^3 \frac{\mu \cdot N_j^2 \cdot L \cdot r^3}{U_o \cdot A_o \cdot c}$$

$$\Delta T = \frac{\dot{Q}_{gen}}{\dot{m} \cdot C_p} = \frac{U_o \cdot A_o (\bar{T}_f - T_\infty) / 2}{l.c.f. \cdot \pi \cdot r \cdot N_j \cdot C_p}$$

temperature rise

Stable Lubrication

$$\frac{\mu \cdot N_j}{P} \gg 0.362 (10^{-6})$$

Thick Film Lubrication and Hydrodynamic Theory UCK361E-40

Assumptions

- 1) The curvature could be neglected
- 2) The lubricant obeys Newton's viscous effect, $\tau = \mu \frac{du}{dy}$
- 3) The forces due to inertia of the lubricant are neglected
- 4) The lubricant is assumed to be incompressible
- 5) The viscosity is assumed to be constant throughout the film
- 6) The pressure does not vary in the axial direction
- 7) There is not lubricant flow in the z direction
- 8) The film pressure constant in the y direction
- 9) The velocity depends only on the coordinates x and y

$$\frac{dp}{dx} = \mu \frac{\partial^2 u}{\partial y^2} \Rightarrow u = \frac{1}{2\mu} \frac{dp}{dx} (y^2 - hy) - \frac{U}{h} y$$

$$Q = \int_0^h u dy$$

volume of lubricant flowing in the x-direction

$$\frac{dQ}{dx} = 0 \Rightarrow \frac{r}{c} f = \phi \left[\left(\frac{r}{c} \right)^2 \frac{\mu N}{P} \right]$$

↑
incompressible lubricant

Design Considerations

- 1) The viscosity μ
- 2) The load per unit of projected bearing area, P
- 3) The speed N
- 4) The bearing dimensions r, c, β , and L

Performance factors \Rightarrow 1) The coefficient of friction, f

2) The temperature rise ΔT 3) The flow of oil, Q

4) The minimum film thickness h_0

$$h_0 \geq 0.005 + 0.00004 \cdot D \text{ mm}$$

journal diameter

$$T_{\max} \leq 120^\circ\text{C} \quad \frac{\mu_d}{\partial h_0} \geq 2$$

starting load

$$\frac{W_{st}}{LD} \leq 2 \text{ MPa} \quad \frac{\partial h_0}{\partial c} > 0$$

The relations of the variables are given in Figures 12-11 --- 12-19.

The design plane is the rc plane (Fig. 12-27).

Pressure-Fed Bearings

The lubricant is supplied to the bearing under pressure. rc plane (Fig. 12-34)

Loads and Materials

Table 12-5 unit loads for several applications

Table 12-6 some characteristic of bearing alloys

- satisfactory compressive and fatigue strength
- soft, have a low melting point and a low modulus of elasticity
- to permit the material to wear or break in
- resistance to wear
- resistance to corrosion, low cost

Bearing Types

Solid bushing, lined bushing, two-piece bushings, thrust bearings, boundary-lubricated bearings (some bearings are boundary lubricated at all times, some only at starting, stopping, overloading, lubricant deficiency)