

Chapter 2

Flows under Pressure in Pipes

If the fluid is flowing full in a pipe under pressure with no openings to the atmosphere, it is called “**pressured flow**”. The typical example of pressured pipe flows is the water distribution system of a city.

2.1. Equation of Motion

Lets take the steady flow ($du/dt=0$) in a pipe with diameter D . (Fig. 2.1). Taking a cylindrical body of liquid with diameter r and with the length Δx in the pipe with the same center, equation of motion can be applied on the flow direction.

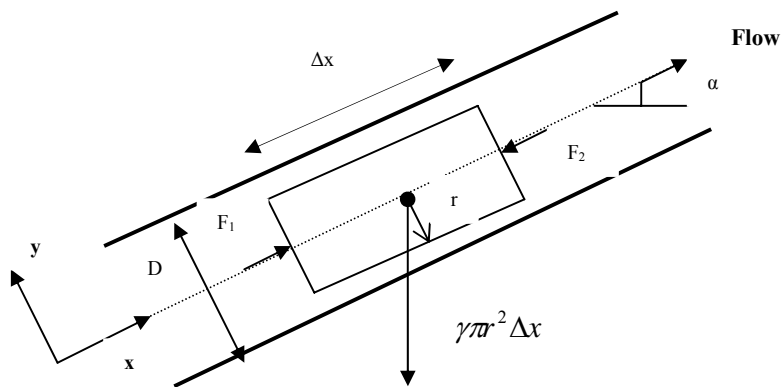


Figure 2.1.

The forces acting on the cylindrical body on the flow direction are,

- Pressure force acting to the bottom surface of the body that causes the motion of the fluid upward is,

$$\rightarrow F_1 = \text{Pressure force} = (p + \Delta p) \pi r^2$$

b) Pressure force to the top surface of the cylindrical body is,

$$\leftarrow F_2 = \text{Pressure force} = p\pi r^2$$

c) The body weight component on the flow direction is,

$$\leftarrow X = \gamma\pi r^2 \Delta x \sin \alpha$$

d) The resultant frictional (shearing) force that acts on the side of the cylindrical surface due to the viscosity of the fluid is,

$$\leftarrow \text{Shearing force} = \tau 2\pi r \Delta x$$

The equation of motion on the flow direction can be written as,

$$(p + \Delta p)\pi r^2 - p\pi r^2 - \gamma\pi r^2 \Delta x \sin \alpha - \tau 2\pi r \Delta x = \text{Mass} \times \text{Acceleration} \quad (2.1)$$

The velocity will not change on the flow direction since the pipe diameter is kept constant and also the flow is a steady flow. The acceleration of the flow body will be zero, Equ. (2.1) will take the form of,

$$\Delta p r^2 - \gamma r^2 \Delta x \sin \alpha - 2\tau r \Delta x = 0$$

$$\tau = \frac{1}{2} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) r \quad (2.2)$$

The frictional stress on the wall of the pipe τ_0 with $r = D/2$,

$$\tau_0 = \frac{1}{2} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \frac{D}{2} \quad (2.3)$$

We get the variation of shearing stress perpendicular the flow direction from Eqs. (2.2) and (2.3) as,

$$\tau = \tau_0 \frac{r}{D/2} \quad (2.4)$$

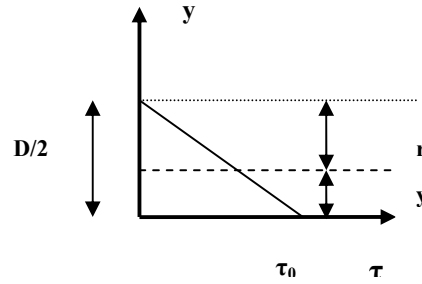


Fig. 2.2

Since $r = D/2 - y$,

$$\tau = \tau_0 \left(1 - \frac{y}{D/2} \right) \quad (2.5)$$

The variation of shearing stress from the wall to the center of the pipe is linear as can be seen from Equ. (2.5).

2.2. Laminar Flow (Hagen-Poiseuille Equation)

Shearing stress in a laminar flow is defined by Newton's Law of Viscosity as,

$$\tau = \mu \frac{du}{dy} \quad (2.6)$$

Where μ = (Dynamic) Viscosity and du/dy is velocity gradient in the normal direction to the flow. Using Eqs. (2.5) and (2.6) together,

$$\tau_0 \left(1 - \frac{y}{D/2}\right) = \mu \frac{du}{dy}$$

$$du = \frac{\tau_0}{\mu} \left(1 - \frac{y}{D/2}\right) dy$$

By taking integral to find the velocity with respect to y,

$$u = \frac{\tau_0}{\mu} \int \left(1 - \frac{y}{D/2}\right) dy$$

$$u = \frac{\tau_0}{\mu} \left(y - \frac{y^2}{D}\right) + \text{cons} \quad (2.7)$$

Since at the wall of the pipe (y=0) there will no velocity (u=0), cons=0. If the specific mass (density) of the fluid is ρ , **Friction Velocity** is defined as,

$$u_* = \sqrt{\frac{\tau_0}{\rho}} \quad (2.8)$$

Kinematic viscosity is defined by,

$$\nu = \frac{\mu}{\rho} \rightarrow \rho = \frac{\mu}{\nu}$$

$$u_*^2 = \frac{\tau_0 \nu}{\mu} \rightarrow \frac{\tau_0}{\mu} = \frac{u_*^2}{\nu}$$

The velocity equation for laminar flows is obtained from Equ. (2.7) as,

$$u = \frac{u_*^2}{\nu} \left(y - \frac{y^2}{D}\right) \quad (2.9)$$

Using the geometric relation of the pipe diameter (D) with the distance from the pipe wall (y) perpendicular to the flow,

$$r = \frac{D}{2} - y \rightarrow y = \frac{D}{2} - r$$

$$u = \frac{u_*^2}{\nu} \left[\frac{D}{2} - y - \frac{1}{D} \left(\frac{D}{2} - r \right)^2 \right]$$

$$u = \frac{u_*^2}{\nu D} \left(\frac{D^2}{4} - r^2 \right) \quad (2.10)$$

Equ. (2.10) shows that velocity distribution in a laminar flow is to be a parabolic curve.

The mean velocity of the flow is,

$$V = \frac{Q}{A} = \frac{\int_A u dA}{A}$$

Placing velocity equation (Equ. 2.10) gives us the mean velocity for laminar flows as,

$$V = \frac{Du_*^2}{8\nu} \quad (2.11)$$

Since

$$u_*^2 = \frac{\tau_0}{\rho}$$

And according to the Equ. (2.3),

$$\tau_0 = \frac{1}{2} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \frac{D}{2}$$

$$u_*^2 = \frac{1}{2\rho} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \frac{D}{2}$$

Placing this to the mean velocity Equation (2.11),

$$V = \frac{D^2}{32\mu} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \quad (2.11)$$

We find the mean velocity equation for laminar flows. This equation shows that velocity increases as the pressure drop along the flow increases. The discharge of the flow is,

$$Q = AV = \frac{\pi D^2}{4} V$$

$$Q = \frac{\pi D^4}{128\mu} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \quad (2.12)$$

If the pipe is horizontal,

$$Q = \frac{\pi D^4}{128\mu} \frac{\Delta p}{\Delta x} \quad (2.13)$$

This is known as **Hagen-Poiseuille Equation**.

2.3. Turbulent Flow

The flow in a pipe is **Laminar** in low velocities and **Turbulent** in high velocities. Since the velocity on the wall of the pipe flow should be zero, there is a thin layer with laminar flow on the wall of the pipe. This layer is called **Viscous Sub Layer** and the rest part in that cross-section is known as **Center Zone**. (Fig. 2.3)

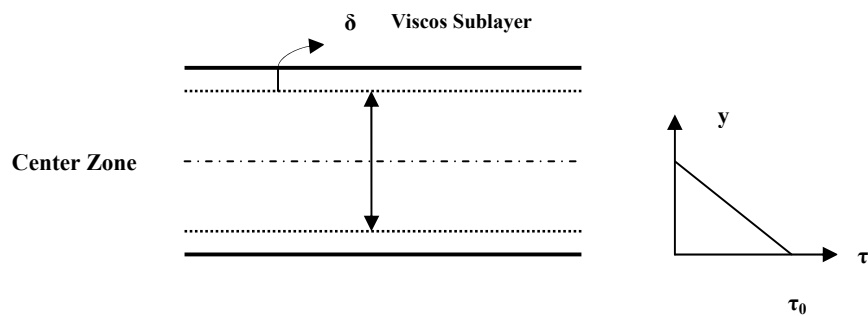


Fig. 2.3.

2.3.1. Viscous Sub Layer

Since this layer is thin enough to take the shearing stress as, $\tau \approx \tau_0$ and since the flow is laminar,

$$\tau = \mu \frac{du}{dy} = \tau_0 = \rho u_*^2$$

$$du = \frac{\rho}{\mu} u_*^2 dy$$

By taking the integral,

$$u = \frac{\rho}{\mu} u_*^2 \int dy$$

$$u = \frac{\rho}{\mu} u_*^2 y + cons$$

Since for $y=0 \rightarrow u = 0$, the integration constant will be equal to zero. Substituting $v=\mu/\rho$ gives,

$$u = \frac{u_*^2}{\nu} y \quad (2.14)$$

The variation of velocity with y is linear in the viscous sub layer. The thickness of the sub layer (δ) has been obtained by laboratory experiments and this empirical equation has been given,

$$\delta = 11.6 \frac{\nu}{u_*} \quad (2.15)$$

Example 2.1. The friction velocity $u_* = 1$ cm/sec has been found in a pipe flow with diameter $D = 10$ cm and discharge $Q = 2$ lt/sec. If the kinematic viscosity of the liquid is $\nu = 10^{-2}$ cm²/sec, calculate the viscous sub layer thickness.

$$\begin{aligned} \delta &= 11.6 \frac{\nu}{u_*} \\ \delta &= 11.6 \frac{10^{-2}}{1} \\ \delta &= 0.12 \text{ cm} = 1.2 \text{ mm} \end{aligned}$$

2.3.2 Smooth Pipes

The flow will be turbulent in the center zone and the shearing stress is,

$$\tau = \mu \frac{du}{dy} + (-\rho \bar{u}'v') \quad (2.16)$$

The first term of Equ. (2.16) is the result of viscous effect and the second term is the result of turbulence effect. In turbulent flow the numerical value of **Reynolds Stress** ($-\rho \bar{u}'v'$) is generally several times greater than that of ($\mu du/dy$). Therefore, the viscosity term ($\mu du/dy$) may be neglected in case of turbulent flow.

Shearing stress caused by turbulence effect in Equ. (2.16) can be written in the similar form as the viscous affect shearing stress as,

$$\tau = -\rho \bar{u}'v' = \mu_T \frac{du}{dy} \quad (2.17)$$

Here μ_T is known as **turbulence viscosity** and defined by,

$$\mu_T = \rho l^2 \left| \frac{du}{dy} \right| \quad (2.18)$$

Here l is the **mixing length**. It has found by laboratory experiments that $l = 0.4y$ for $\tau \approx \tau_0$ zone and this 0.4 coefficient is known as **Von Karman Coefficient**. Substituting this value to the Equ. (2.18),

$$\begin{aligned} \mu_T &= 0.16\rho y^2 \left| \frac{du}{dy} \right| \\ \tau_0 &= \mu_T \frac{du}{dy} = 0.16\rho y^2 \left(\frac{du}{dy} \right)^2 \\ \frac{\tau_0}{\rho} &= u_*^2 = 0.16\rho y^2 \left(\frac{du}{dy} \right)^2 \\ u_* &= 0.4y \frac{du}{dy} \\ \frac{dy}{y} &= 0.4 \frac{du}{u_*} \\ du &= 2.5u_* \frac{dy}{y} \end{aligned}$$

Taking the integral of the last equation,

$$\begin{aligned} u &= 2.5u_* \int \frac{dy}{y} \\ u &= 2.5u_* \ln y + \text{cons} \end{aligned} \quad (2.19)$$

The velocity on the surface of the viscous sub layer is calculated by using Eqs. (2.14) and (2.15),

$$u = \frac{u_*^2}{\nu} y$$

$$y = \delta \rightarrow \delta = 11.6 \frac{\nu}{u_*}$$

$$u = 11.6u_*$$

Substituting this to the Equ. (2.19) will give us the integration constant as,

$$cons = u - 2.5u_* Lny$$

$$cons = 11.6u_* - 2.5u_* Ln\left(11.6 \frac{\nu}{u_*}\right)$$

$$cons = 11.6u_* - 2.5u_* \left(Ln11.6 + Ln \frac{\nu}{u_*} \right)$$

$$cons = 5.5u_* - 2.5u_* Ln \frac{\nu}{u_*}$$

Substituting the constant to the Equ. (2.19),

$$u = 2.5u_* Lny + 5.5u_* - 2.5u_* Ln \frac{\nu}{u_*}$$

$$u = 2.5u_* Ln \frac{yu_*}{\nu} + 5.5u_* \quad (2.20)$$

$$\frac{u}{u_*} = 2.5 Ln \frac{yu_*}{\nu} + 5.5$$

Equ. (2.20) is the velocity equation in turbulent flow in a cross section with respect to y from the wall of the pipe and valid for the pipes with **smooth wall**.

The **mean velocity** at a cross-section is found by the integration of Equ. (2.20) for are A ,

$$V = \frac{Q}{A} = \frac{\int u dA}{A}$$

$$V = \left(2.5Ln \frac{u_* D}{2\nu} + 1.75 \right) u_* \quad (2.21)$$

$$\frac{V}{u_*} = 2.5Ln \frac{Du_*}{\nu} + 1.75$$

2.3.3. Definition of Smoothness and Roughness

The uniform roughness size on the wall of the pipe can be e as roughness depth. Most of the commercial pipes have roughness. The above derived equations are for smooth pipes. The definition of smoothness and roughness basically depends upon the size of the roughness relative to the thickness of the viscous sub layer. If the roughnesses are submerged in the viscous sub layer so the pipe is a smooth one, and resistance and head loss are entirely unaffected by roughness up to this size.

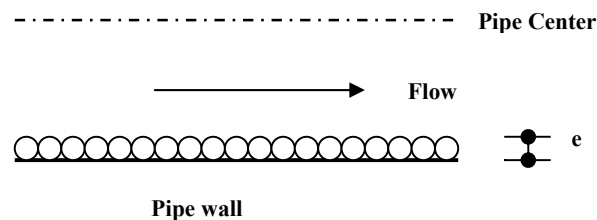


Fig. 2.4

Since the viscous sub layer thickness (δ) is given by, $\delta = 11.6 \frac{\nu}{u_*}$ pipe roughness size e is compared with δ to define if the pipe will be examined as smooth or rough pipe.

$$\text{a) } e < \delta = 11.6 \frac{\nu}{u_*}$$

The roughness of the pipe e will be submerged in viscous sub layer. The flow in the center zone of the pipe can be treated as smooth flow which is given Chap. 2.3.2.

$$\text{b) } e > 70 \frac{\nu}{u_*}$$

The height of the roughness e is higher than viscous sub layer. The flow in the center zone will be affected by the roughness of the pipe. This flow is named as **Wholly Rough Flow**.

$$\text{c) } 11.6 \frac{\nu}{u_*} < e < 70 \frac{\nu}{u_*}$$

This flow is named as **Transition Flow**.

2.3.4. Wholly Rough Pipes

Pipe friction in rough pipes will be governed primarily by the size and pattern of the roughness. The velocity equation in a cross section will be the same as Equ. (2.19).

$$u = 2.5u_* \ln y + \text{cons} \quad (2.19)$$

Since there will be no sub layer left because of the roughness of the pipe, the integration constant needs to be found out. It has been found by laboratory experiments that,

$$u = 0 \rightarrow y = \frac{e}{30}$$

The integration is calculated as,

$$0 = 2.5u_*Ln \frac{e}{30} + const$$

$$const = -2.5u_*Ln \frac{e}{30}$$

$$u = 2.5u_*Lny - 2.5u_*Ln \frac{e}{30}$$

The velocity distribution at a cross section for wholly rough pipes is,

$$u = 2.5u_*Ln \frac{30y}{e} \quad (2.22)$$

$$\frac{u}{u_*} = 2.5Ln \frac{30y}{e}$$

The mean velocity at that cross section is,

$$V = u_* \left(2.5Ln \frac{D}{2e} + 4.73 \right) \quad (2.23)$$

$$\frac{V}{u_*} = 2.5Ln \frac{D}{2e} + 4.73$$

2.4. Head (Energy) Loss in Pipe Flows

The Bernoulli equation for the fluid motion along the flow direction between points (1) and (2) is,

$$z_1 + \frac{p + \Delta p}{\gamma} + \frac{V_1^2}{2g} = z_2 + \frac{p}{\gamma} + \frac{V_2^2}{2g} + h_L \quad (2.24)$$

If the pipe is constant along the flow, $V_1 = V_2$,

$$h_L = \frac{\Delta p}{\gamma} - (z_2 - z_1) \quad (2.25)$$

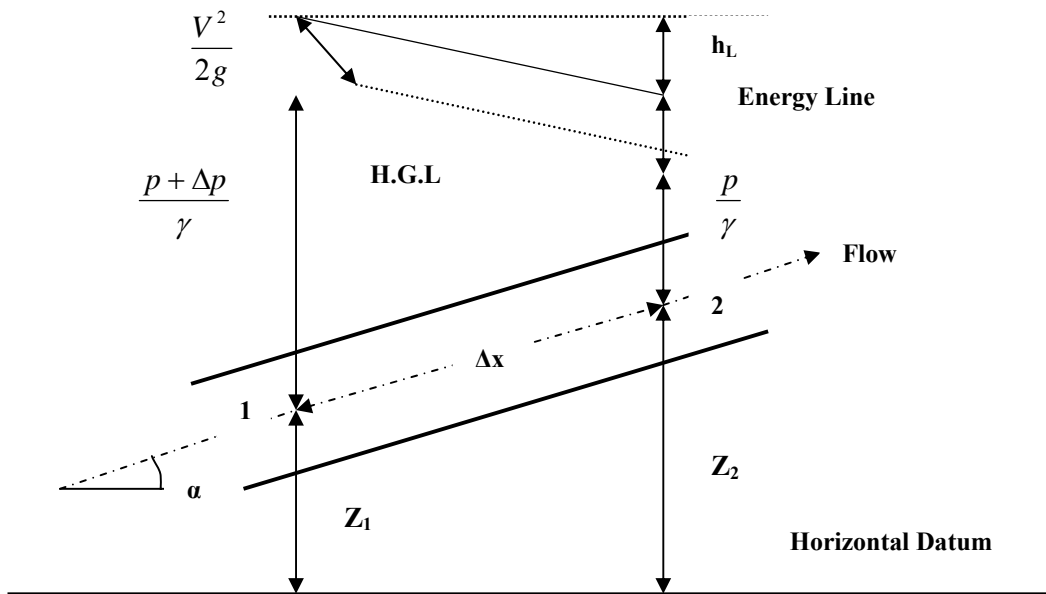


Figure 2.5

If we define **energy line (hydraulic) slope J** as energy loss for unit weight of fluid for unit length,

$$J = \frac{h_L}{\Delta x} \quad (2.26)$$

Where Δx is the length of the pipe between points (1) and (2), and using Eqs. (2.25) and (2.26) gives,

$$J = \frac{\Delta p}{\gamma \Delta x} - \frac{z_2 - z_1}{\Delta x} \quad (2.27)$$

$$J = \frac{\Delta p}{\gamma \Delta x} - \sin \alpha$$

Using Equ. (2.3),

$$\begin{aligned}\tau_0 &= \frac{1}{2} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \frac{D}{2} \\ \tau_0 &= \frac{\gamma D}{4} \left(\frac{\Delta p}{\gamma \Delta x} - \sin \alpha \right) \quad (2.28) \\ \tau_0 &= \frac{\gamma D}{4} J\end{aligned}$$

Using the friction velocity Equ. (2.8),

$$\begin{aligned}u_* &= \sqrt{\frac{\tau_0}{\rho}} \\ \tau_0 &= \rho u_*^2 \\ \rho u_*^2 &= \frac{\gamma D}{4} J = \frac{\rho g D}{4} J \\ J &= \frac{4u_*^2}{gD} \quad (2.29)\end{aligned}$$

Energy line slope equation has been derived for pipe flows with respect to friction velocity u_* . Mean velocity of the cross section is used in practical applications instead of frictional velocity. The overall summary of equational relations was given in Table. (2.1) between frictional velocity u_* and the mean velocity V of the cross section.

Table 2.1. Mathematical Relations between u_* and V

Laminar Flow ($Re < 2000$)	$V = \frac{Du_*^2}{8\nu}$	
Turbulent Flow ($Re > 2000$)	Smooth Flow $e < 11.6 \frac{\nu}{u_*}$	$V = u_* \left(2.5 \ln \frac{Du_*}{2\nu} + 1.75 \right)$
	Wholly Rough Flow $e > 70 \frac{\nu}{u_*}$	$V = u_* \left(2.5 \ln \frac{D}{2e} + 4.73 \right)$

After calculating the mean velocity V of the cross-section and finding the type of flow, frictional velocity u_* is found out from the equations given in Table (2.1). The energy line (hydraulic) slope J of the flow is calculated by Equ. (2.29). **Darcy-Weisbach** equation is used in practical applications which is based on the mean velocity V to calculate the hydraulic slope J .

$$J = \frac{f V^2}{D 2g} \quad (2.30)$$

Where f is named as the **friction coefficient** or **Darcy-Weisbach coefficient**. Friction coefficient f is calculated from table (2.2) depending upon the type of flow where

$$Re = \frac{\rho V D}{\mu} = \frac{V D}{\nu}$$

Table 2.2. Friction Coefficient Equations

Laminar Flow ($Re < 2000$)		$f = \frac{64}{Re}$
Turbulent Flow ($Re > 2000$)	Smooth Flow $\left(e < 11.6 \frac{\nu}{u_*} \right)$	$\sqrt{\frac{8}{f}} = 2.5 \ln \left(Re \sqrt{\frac{f}{32}} \right) + 1.75$
	Wholly Rough Flow $\left(e > 70 \frac{\nu}{u_*} \right)$	$\sqrt{\frac{8}{f}} = 2.5 \ln \left(\frac{D}{2e} \right) + 4.73$
	Transition Flow $\left(11.6 \frac{\nu}{u_*} < e < 70 \frac{\nu}{u_*} \right)$	$\sqrt{\frac{8}{f}} = 2.5 \ln \left(\frac{D}{2e} \right) + 4.73 - 2.5 \ln \left[1 + \frac{9.2}{Re \sqrt{\frac{f}{32}}} \right]$

The physical explanation of the equations in Table (2.2) gives us the following results.

- a) For laminar flows ($Re < 2000$), friction factor f depends only to the Reynolds number of the flow. $f = f(Re)$
- b) For turbulent flows ($Re > 2000$),
 1. For smooth flows, friction factor f is a function of Reynolds number of the flow. $f = f(Re)$

2. For transition flows, f depends on Reynolds number (Re) of the flow and **relative roughness** of the pipe (e/D), $f = f(Re, e/D)$
3. For wholly rough flows, f is a function of the relative roughness (e/D)
 $f = f(e/D)$

Friction coefficient f is calculated from the equations given in Table (2.2). In case of turbulent flow, the calculation of f will always be done by trial and error method. A diagram has been prepared to overcome this difficulty. It is prepared by **Nikuradse** and shows the functional relations between f and Re , e/D as curves. (Figure 2.6)

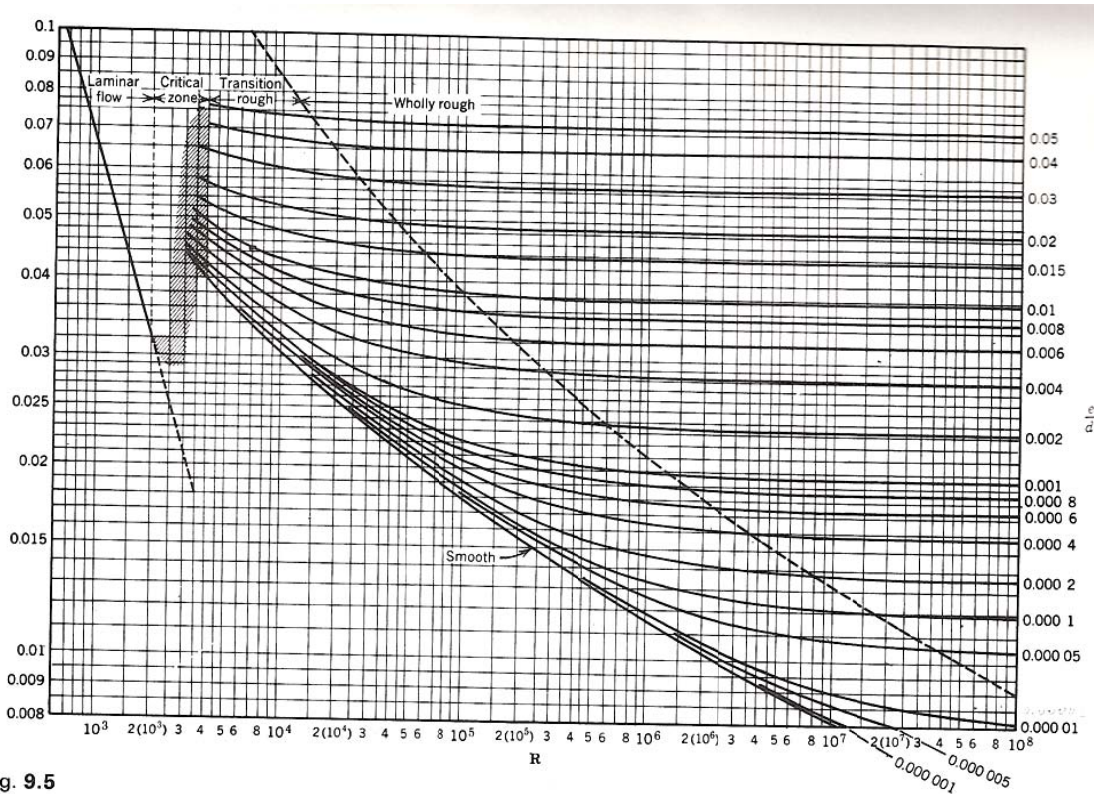


Fig. 9.5

Figure 2.6

Summary

- a) Energy loss for unit length of pipe is calculated by Darcy-Weisbach equation,

$$J = \frac{f V^2}{D 2g}$$

For a pipe with length L , the energy loss will be,

$$h_L = JL \quad (2.31)$$

- b) The friction coefficient f will either be calculated from the equations given in Table (2.2) or from the **Nikuradse diagram**. (Figure 2.6)

2.5. Head Loss for Non-Circular Pipes

Pipes are generally circular. But a general equation can be derived if the cross-section of the pipe is not circular. Let's write equation of motion for a non-circular prismatic pipe with an angle of α to the horizontal datum in a steady flow. Fig. (2.7).

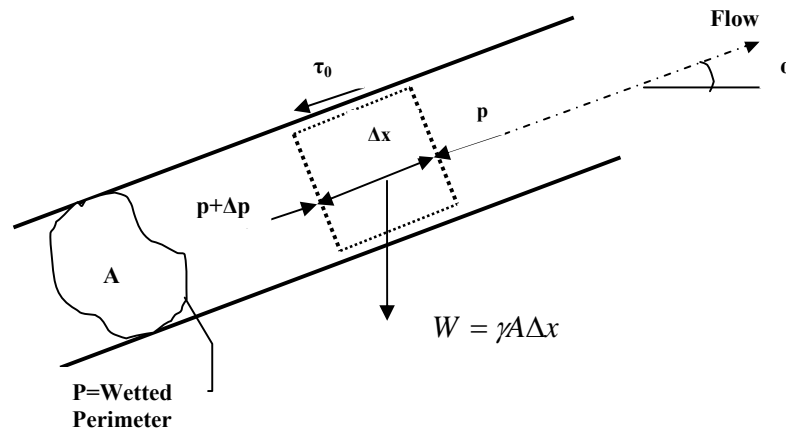


Figure 2.7

$$(p + \Delta p)A - pA - \tau_0 P \Delta x - \gamma A \Delta x \sin \alpha = \text{Mass} \times \text{acceleration}$$

Where P is the **wetted perimeter** and since the flow is steady, the acceleration of the flow will be zero. The above equation is then,

$$\begin{aligned} \Delta p A - \tau_0 P \Delta x - \gamma A \Delta x \sin \alpha &= 0 \\ \tau_0 &= \frac{A}{P} \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right) \end{aligned} \quad (2.32)$$

Where,

$$R = \frac{A}{P} = \text{Hydraulic Radius} \quad (2.33)$$

Hydraulic radius is the ratio of wetted area to the wetted perimeter. Substituting this to the Equ. (2.32),

$$\tau_0 = R \left(\frac{\Delta p}{\Delta x} - \gamma \sin \alpha \right)$$
$$\tau_0 = \gamma R \left(\frac{\Delta p}{\gamma \Delta x} - \sin \alpha \right)$$

Since by Equ. (2.27),

$$J = \frac{\Delta p}{\gamma \Delta x} - \sin \alpha$$

Shearing stress on the wall of the non-circular pipe,

$$\tau_0 = \gamma R J \quad (2.34)$$

For circular pipes,

$$R = \frac{A}{P} = \frac{\pi D^2 / 4}{\pi D} = \frac{D}{4} \quad (2.35)$$
$$D = 4R$$

This result is substituted ($D=4R$) to the all equations derived for the circular pipes to obtain the equations for non-circular pipes. Table (2.3) is prepared for the equations as,

Table 2.3.

Circular Pipes	Non-Circular pipes
$\tau_0 = \gamma \frac{D}{4} J$ $J = \frac{f}{D} \times \frac{V^2}{2g}$ $f = f(\text{Re}, D/e)$ $\text{Re} = \frac{VD}{\nu}$	$\tau_0 = \gamma R J$ $J = \frac{f}{4R} \times \frac{V^2}{2g}$ $f = f(\text{Re}, 4R/e)$ $\text{Re} = \frac{V4R}{\nu}$

2.6. Hydraulic and Energy Grade Lines

The terms of energy equation have a dimension of length [L]; thus we can attach a useful relationship to them.

$$\frac{p_1}{\gamma} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{\gamma} + \frac{V_2^2}{2g} + z_2 + h_L \quad (2.36)$$

If we were to tap a piezometer tube into the pipe, the liquid in the pipe would rise in the tube to a height p/γ (**pressure head**), hence that is the reason for the name

hydraulic grade line (HGL). The total head $\left(\frac{p}{\gamma} + \frac{V^2}{2g} + z\right)$ in the system is greater

than $\left(\frac{p}{\gamma} + z\right)$ by an amount $\frac{V^2}{2g}$ (**velocity head**), thus the **energy (grade) line (EGL)**

is above the **HGL** with a distance $\frac{V^2}{2g}$.

Some hints for drawing hydraulic grade lines and energy lines are as follows.

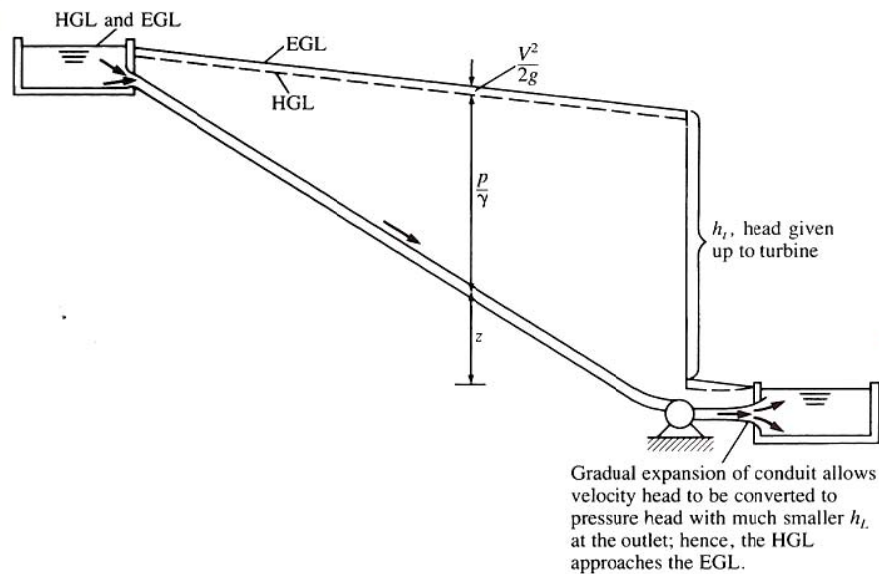


Figure 2.8

1. By definition, the EGL is positioned above the HGL an amount equal to the velocity head. Thus if the velocity is zero, as in lake or reservoir, the HGL and EGL will coincide with the liquid surface. (Figure 2.8)
2. Head loss for flow in a pipe or channel always means the EGL will slope downward in the direction of flow. The only exception to this rule occurs when a pump supplies energy (and pressure) to the flow. Then an abrupt rise in the EGL occurs from the upstream side to the downstream side of the pump.
3. If energy is abruptly taken out of the flow by, for example, a turbine, the EGL and HGL will drop abruptly as in Fig....
4. In a pipe or channel where the pressure is zero, the HGL is coincident with the water in the system because $p/\gamma = 0$ at these points. This fact can be used to locate the HGL at certain points in the physical system, such as at the outlet end of a pipe, where the liquid charges into the atmosphere, or at the upstream end, where the pressure is zero in the reservoir. (Fig.2.8)
5. For steady flow in a pipe that has uniform physical characteristics (diameter, roughness, shape, and so on) along its length, the head loss per unit of length will be constant; thus the slope ($\Delta h_L/\Delta L$) of the EGL and HGL will be constant and parallel along the length of pipe.
6. If a flow passage changes diameter, such as in a nozzle or a change in pipe size, the velocity there in will also change; hence the distance between the EGL and HGL will change. Moreover, the slope on the EGL will change because the head per unit length will be larger in the conduit with the larger velocity.
7. If the HGL falls below the pipe, p/γ is negative, thereby indicating sub-atmospheric pressure (Fig.2.8).

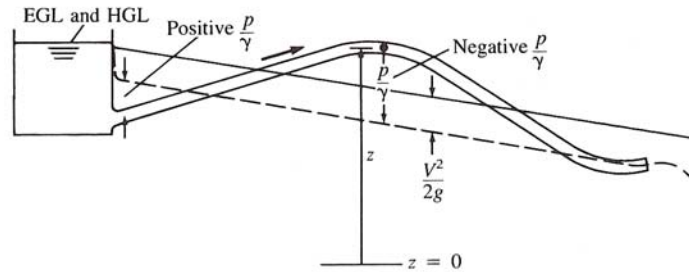


Figure 2.9

If the pressure head of water is less than the vapor pressure head of the water (-97 kPa or -950 cm water head at standard atmospheric pressure), cavitation will occur. Generally, cavitation in conduits is undesirable. It increases the head loss and cause structural damage to the pipe from excessive vibration and pitting of pipe walls. If the pressure at a section in the pipe decreases to the vapor pressure and stays that low, a large vapor cavity can form leaving a gap of water vapor with columns of water on either side of cavity. As the cavity grows in size, the columns of water move away from each other. Often these of columns of water rejoin later, and when they do, a very high dynamic pressure (water hammer) can be generated, possibly rupturing the pipe. Furthermore, if the pipe is thin walled, such as thin-walled steel pipe, sub-atmospheric pressure can cause the pipe wall to collapse. Therefore, the design engineer should be extremely cautious about negative pressure heads in the pipe.

