

Circuit and System Analysis

EEF 232E

Prof. Dr. Müştak E. Yalçın

Istanbul Technical University
Faculty of Electrical and Electronic Engineering

mustak.yalcin@itu.edu.tr

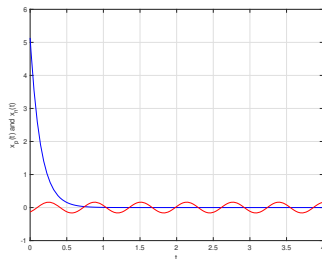
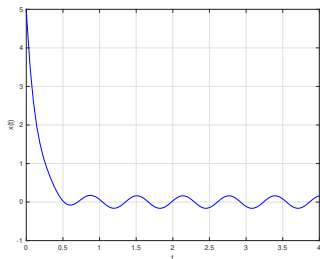
1 Sinusoidal Steady-State Analysis

- Phasor analysis
- Properties of phasors
- Representation of state-space equations
- Transfer function

Analytic Solution of State-space Equation

$$x(t) = \underbrace{\Phi(t)x(0) - \Phi(t)x_p(0)}_{\text{Natural Response}} + \underbrace{x_p(t)}_{\text{Forced response}}$$

Example: $\dot{x} + 7x = 2 \sin 10t$ and $x(0) = 5$



$$x(t) = \underbrace{5e^{-7t}}_{\text{zero-input}} + \underbrace{\frac{20}{149}e^{-7t} + \frac{14}{149}\sin(10t) - \frac{20}{149}\sin(10t + \frac{\pi}{2})}_{\text{zero-state}}$$

Sinusoidal Steady-State Analysis

If a system is asymptotically stable

$$\lim_{t \rightarrow \infty} \Phi(t) = 0$$

Forced response is the complete response!

$$x(t) = \underbrace{\Phi(t)x_0 - \Phi(t)x_p(t_0)}_{=0} + x_p(t)$$

Sinusoidal steady-state behavior

Sinusoidal steady-state behavior of linear time-invariant circuits when the circuits are driven by one or more **sinusoidal** sources at some frequency ω and when, after all "transients" have died down, all currents and voltages are sinusoidal at frequency ω .

Electric Circuits, James W. Nilsson and Susan A. Riedel, Ch.9 and 10

$$x(t) = A_m e^{j(\omega t + \theta)}.$$

where $j = \sqrt{-1}$, A_m ($|X|$) is called the magnitude of $x(t)$ and θ (\angle) is called the phase of $x(t)$.

Rectangular representation of complex $x(t)$ is

$$x(t) = A_m \cos(\omega t + \theta) + jA_m \sin(\omega t + \theta)$$

Real part

$$A_m \cos(\omega t + \theta) = \Re\{x(t)\}$$

Imaginary part

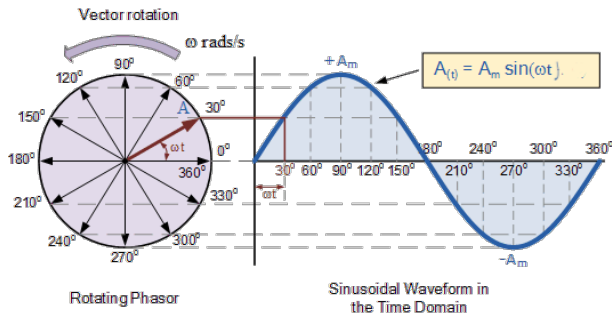
$$A_m \sin(\omega t + \theta) = \Im\{x(t)\}$$

from Euler's identity.

$$\cos(\omega t) = \sin(\omega t + \frac{\pi}{2}) \text{ and } \sin(\omega t) = \cos(\omega t - \frac{\pi}{2})$$

Sinusoidal Steady-State Analysis

$$x(t) = A_m \sin(\omega t) = \Im\{A_m e^{j(\omega t)}\}$$

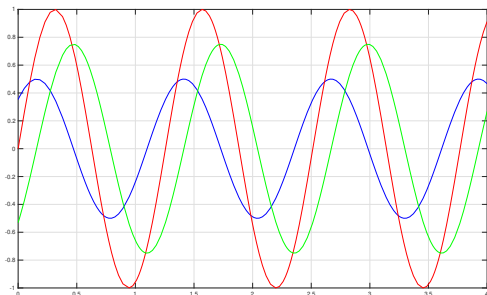


$$x(t) = A_m \sin(\omega t + \theta) = \Im\{A_m e^{j(\omega t + \theta)}\}$$

See: Gif image: <https://en.wikipedia.org/wiki/File:Unfasor.gif>

Sinusoidal Steady-State Analysis

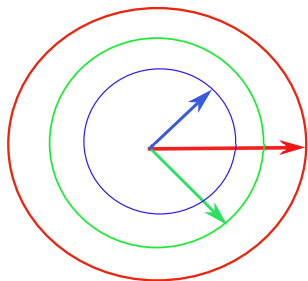
$$\sin(5t), 0.5 \sin\left(5t + \frac{\pi}{4}\right), 0.75 \sin\left(5t - \frac{\pi}{4}\right)$$



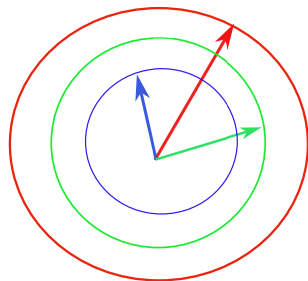
$$\Im\{1e^{j(5t)}\}, \Im\{0.5e^{j(5t+\frac{\pi}{4})}\}, \Im\{0.75e^{j(5t-\frac{\pi}{4})}\}$$

Sinusoidal Steady-State Analysis

$$\Im\{1e^{j(5t)}\}, \Im\{0.5e^{j(5t+\frac{\pi}{4})}\}, \Im\{0.75e^{j(5t-\frac{\pi}{4})}\}$$



after while



We can also use cos function !

$$x(t) = A_m \cos(\omega t + \theta) = \Re\{A_m e^{j(\omega t + \theta)}\}$$

Phasor

The idea is to associate with each sine wave (of voltage or current) a complex number called the phasor.

$x(t)$ is a complex variable and in polar coordinate

$$x(t) = X_m e^{j(\omega t + \theta)}.$$

The quantity (**phasor**)

$$X = X_m e^{j\theta}$$

is a complex number that carries **the amplitude** and **phase angle** of the given sinusoidal function. This complex number is by definition the **phasor** representation of the given sinusoidal function.

Using phasor representation, a complex variable is given

$$x(t) = X e^{j\omega t}$$

Examples: Electric Circuits, James W. Nilsson and Susan A. Riedel, pp. 334

Example

Phasor of the sinusoidal function

$$x(t) = 110\sqrt{2} \cos(\omega t + \frac{\pi}{2})$$

using

$$x(t) = \Re\{\underbrace{110\sqrt{2}e^{j\frac{\pi}{2}}}_{\text{phasor}} e^{j\omega t}\}$$

is obtain

$$X = 110\sqrt{2}e^{j\frac{\pi}{2}}$$

$X_m = 100\sqrt{2}$ (or $|X| = 100\sqrt{2}$), $\theta = \frac{\pi}{2}$ (or $\angle \frac{\pi}{2}$). $|X|_{\text{rms}} = 100$

If you like to use \Im :

$$x(t) = 110\sqrt{2} \sin(\omega t + \pi) = \Im\{\underbrace{110\sqrt{2}e^{j\pi}}_{\text{phasor}} e^{j\omega t}\}$$

then $X = 110\sqrt{2}e^{j\pi}$.

Decide one (\Im or \Re) and obtain phasors, use it for back to t-domain!

Example

Phasor is a complex number therefore remember that:

Lets $Z \in \mathbb{C}$, in rectangular coordinate $Z = \sigma + jw$, in polar coordinate its magnitude $Z_m = \sqrt{\sigma^2 + w^2}$ and its phase $\theta = \arctan(\frac{w}{\sigma})$

$$3 + 4j = 5e^{j0.927} = 5 \cos(0.927) + j5 \sin(0.927)$$

$$5 = \sqrt{3^2 + 4^2}, \quad \arctan \frac{4}{3} = 0.927 \text{radian} = 53.113188^\circ$$

$$1 + j = \sqrt{2}e^{j\frac{\pi}{4}} = \sqrt{2} \cos\left(\frac{\pi}{4}\right) + j\sqrt{2} \sin\left(\frac{\pi}{4}\right)$$

$$\sqrt{2} = \sqrt{1^2 + 1^2} \quad \arctan \frac{1}{1} = \frac{\pi}{4} \text{ radian} = 45^\circ$$

$$5e^{j0.927} + \sqrt{2}e^{j0.785} = ?$$

$$3 + 4j + 1 + j = 4 + 5j = 6.403e^{j0.896}$$

$$(3 + 4j) \times (1 + j) = ?$$

$$5e^{j0.927} \times \sqrt{2}e^{j0.785} = 5\sqrt{2}e^{j1.71}$$

Properties of phasors



$$y(t) = \alpha_1 x_1(t) + \alpha_2 x_2(t)$$

$$Y = \alpha_1 X_1 + \alpha_2 X_2$$

- X is phasor of $x(t)$

$$y(t) = \frac{d^n x(t)}{dt^n}$$

then phasor of $y(t)$

$$Y = (j\omega)^n X.$$



$$\frac{d}{dt} \{X_m e^{\theta j} e^{j\omega t}\} = \left\{ \frac{d}{dt} X_m e^{\theta j} e^{j\omega t} \right\} = \underbrace{\{j\omega A X_m e^{\theta j} e^{j\omega t}\}}_{\text{phasor}}$$

- A are B phasor

- If $\Re\{Ae^{j\omega t}\} = \Re\{Be^{j\omega t}\}$ then $A = B$.
- If $A = B$ then $\Re\{Ae^{j\omega t}\} = \Re\{Be^{j\omega t}\}$.

Phasor & State-space equation

Lets find the sinusoidal particular solution ($Xe^{j\omega t}$) of linear time invariant state equation

$$\dot{x} = Ax + Bu$$

for a sinusoidal input $Ue^{j\omega t}$. Substituting the solution and input

$$j(\omega)X = AX + BU$$

The sinusoidal solution is then

$$X = (j\omega I - A)^{-1}BU$$

The solution is defined for $\det(j\omega I - A) \neq 0$ which means $j\omega \neq \lambda$. Input frequency is equal the natural frequency.

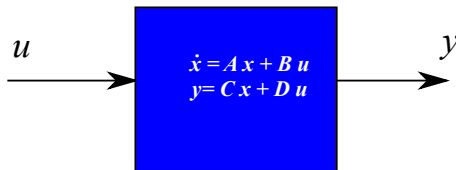
Transfer function

A linear time invariant single input single output system ($u, y \in R$) is defined by

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

what if $u \in R^m, y \in R^l$...



Using phasors, the output of the system

$$Y = \underbrace{(C(j\omega I - A)^{-1}B + D)}_{\text{Transfer function}} U$$

Transfer function

$$H(j\omega) = (C(j\omega I - A)^{-1}B + D)$$

from input U to output Y .

Example

$$\frac{dx}{dt} = \begin{bmatrix} -\sqrt{2} & -1 \\ 1 & 0 \end{bmatrix} x + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u(t); \quad y = [0 \ 1]x$$

Transfer function (which is a function of w !)

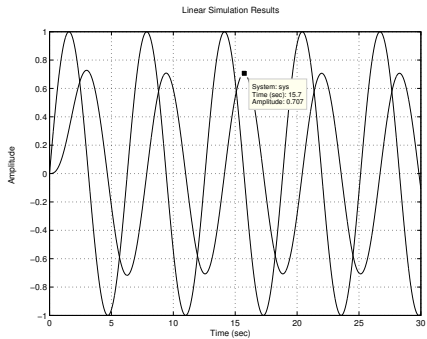
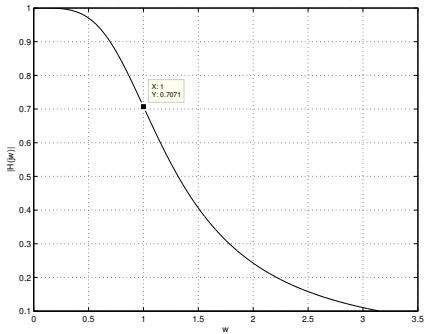
$$H(jw) = \frac{1}{1 - w^2 + j\sqrt{2}w}$$

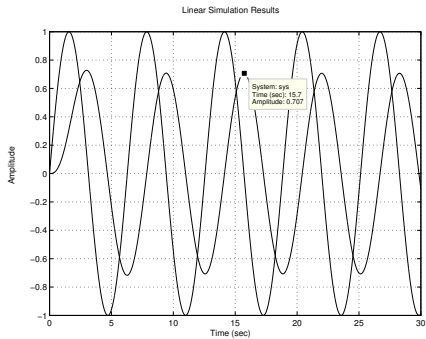
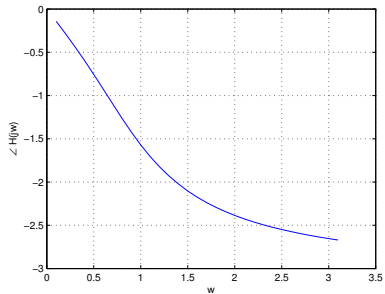
For the input $u(t) = \sin(wt)$ (phasor of input signal $E = 1$) phasor of the output is

$$Y = H(j1)E = \frac{-j}{\sqrt{2}} = \frac{1}{\sqrt{2}} e^{-j\pi/2}$$

Hence output signal is

$$y(t) = \frac{1}{\sqrt{2}} \sin(t - \pi/2)$$





Analytic Solution of State-space Equation

Example: $\dot{x} + 7x = 2 \sin 10t$ and $x(0) = 5$

$$\dot{x} + 7x = 2 \sin 10t$$

, Remember $w = 10$

$$jwX + 7X = 2$$

$$j10X + 7X = 2$$

$$(7 + j10)X = 2$$

$$X = \frac{2}{7 + 10j} = \frac{2}{149}(7 - 10j) = \frac{14}{149} - j\frac{20}{149}$$

$$x(t) = \frac{14}{149} \sin(10t) - \frac{20}{149} \sin(10t + \frac{\pi}{2})$$