

# Transform Learning MRI with Global Wavelet Regularization

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# Outline

- 1 Introduction
  - The Problem
  - The Novel Approach
- 2 Transform Learning MRI
- 3 GTLMRI
  - New Cost
  - GTLMRI: Denoising
  - GTLMRI: Reconstruction
  - GTLMRI: Overall Algorithm
- 4 Simulations and Conclusion

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# Sparse MRI

- Active research area: Use sparsity as a regularizer for ill-conditioned inverse problems.
- Sparse regularization (and compressed sensing (CS)) have been applied to **image reconstruction in Magnetic Resonance Imaging (MRI)** (our problem of interest).
- Pioneering work [Lustig et.al., 2007], **Sparse MRI**: sparsely regularize the MRI reconstruction problem.

$$\min_x \frac{1}{2} \|\mathcal{F}_0 x - y\|_2^2 + \rho_1 \|\Phi x\|_1 + \rho_2 \|x\|_{TV}. \quad (1)$$

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$$\min_{\mathbf{x}} \frac{1}{2} \|\mathcal{F}_U \mathbf{x} - \mathbf{y}\|_2^2 + \rho_1 \|\Phi \mathbf{x}\|_1 + \rho_2 \|\mathbf{x}\|_{\text{TV}}.$$

- $\mathbf{x} \in \mathbb{C}^N$  is the reconstructed MR image in vectorized form.
- $\mathcal{F}_U$  is the undersampled Fourier transform operator: conversion from the vectorized image to the k-space.
- $\mathbf{y} = \mathcal{F}_U \mathbf{x}^* + \boldsymbol{\eta} \in \mathbb{C}^K$  is the observation vector in the k-space.
- $\mathbf{x}^*$  is the true underlying image and  $\boldsymbol{\eta}$  is the additive noise.
- The ratio  $\kappa/N$  quantifies the undersampling.
- $\|\cdot\|_1$  denotes the  $\ell_1$  norm.
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- Exemplar or patch based methods have been very popular for sparsity based image processing.
- Dictionary learning (DL) based synthesis sparsity methods
- Analysis sparsity based analysis operator learning methods
- Novel model for analysis operator learning, called as **sparsifying Transform Learning (TL)** [Ravishankar and Bresler, 2013].
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- TLMRI or DL based algorithms utilize local, patch-scale regularization
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## G-TLMRI

- We introduce a global sparsifying cost into TLMRI, and provide the algorithm.
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- TLMRI cost function can be stated as follows.

$$(P0) \quad \min_{W, \hat{x}, \mathcal{A}, x} \|W\hat{x} - \mathcal{A}\|_F^2 + \lambda Q(W) + \tau \|\mathcal{R}(x) - \hat{x}\|_F^2 \\ + \eta \|\mathcal{F}_0 x - y\|_2^2, \quad \text{s.t.} \quad \|\alpha_j\|_0 \leq s_j \quad \forall j = 1 \dots M. \quad (2)$$

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- $\mathbf{W} \in \mathbb{C}^{n \times n}$  is the learned square transform.
- $\hat{\mathbf{x}} \in \mathbb{C}^{n \times M}$ , and its columns  $\hat{\mathbf{x}}_j \in \mathbb{C}^n$  denote vectorized 2D patches of size  $\sqrt{n} \times \sqrt{n}$ .

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$$(P0) \quad \min_{\mathbf{W}, \hat{\mathbf{x}}, \mathcal{A}, \mathbf{x}} \quad \|\mathbf{W}\hat{\mathbf{x}} - \mathcal{A}\|_F^2 + \lambda Q(\mathbf{W}) + \tau \|\mathcal{R}(\mathbf{x}) - \hat{\mathbf{x}}\|_F^2 \\ + \eta \|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2, \quad \text{s.t.} \quad \|\alpha_j\|_0 \leq \mathbf{s}_j \quad \forall j = 1 \dots M.$$

- $\mathcal{A} \in \mathbb{C}^{n \times M}$  includes the sparse codes.
- $Q(\cdot)$  penalization term for the learned  $\mathbf{W}$ .
- $\mathcal{R}$  image to patch operator.
- Observation fidelity is enforced using the  $\|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2$  term.

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  - The Problem
  - The Novel Approach
- 2 Transform Learning MRI
- 3 GTMRI**
  - New Cost**
  - GTMRI: Denoising
  - GTMRI: Reconstruction
  - GTMRI: Overall Algorithm
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# New Method: GTMRI

- New cost function with global regularizer.

$$\begin{aligned}
 \text{(P1)} \quad \min_{\mathbf{W}, \hat{\mathbf{x}}, \mathcal{A}, \mathbf{x}} \quad & \|\mathbf{W}\hat{\mathbf{x}} - \mathcal{A}\|_F^2 + \lambda Q(\mathbf{W}) + \beta \|\mathcal{A}\|_1 \\
 & + \tau \|\mathcal{R}(\mathbf{x}) - \hat{\mathbf{x}}\|_F^2 + \eta \|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \nu' \|\Phi \mathbf{x}\|_1. \quad (3)
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$$(P2) \min_{\mathbf{W}, \hat{\mathbf{x}}, \mathcal{A}} \|\mathbf{W}\hat{\mathbf{x}} - \mathcal{A}\|_F^2 + \lambda Q(\mathbf{W}) + \beta \|\mathcal{A}\|_1 + \tau \|\mathcal{R}(\mathbf{x}) - \hat{\mathbf{x}}\|_F^2. \quad (4)$$

$$(P3) \min_{\mathbf{x}} \frac{1}{2} \|\mathcal{F}_U \mathbf{x} - \mathbf{y}\|_2^2 + \frac{\tau}{2\eta} \|\mathcal{R}(\mathbf{x}) - \hat{\mathbf{x}}\|_F^2 + \frac{\nu'}{2\eta} \|\Phi \mathbf{x}\|_1. \quad (5)$$

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# GTMRI: Denoising

- We will divide (P2) into two in the following form similar to the TLMRI.

$$(P2.1) \min_{W, \mathcal{A}} \|W\hat{\mathcal{X}} - \mathcal{A}\|_F^2 + \lambda Q(W) + \beta \|\mathcal{A}\|_1.$$

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- (P2.2.2) has a simple least squares solution for fixed  $\mathcal{A}$  given by  $(\mathbf{W}^H\mathbf{W} + \tau\mathbf{I})^{-1}(\mathbf{W}^H\mathcal{A} + \tau\mathcal{R}(\mathbf{x}))$ .

# Outline

- 1 Introduction
  - The Problem
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  - New Cost
  - GTMRI: Denoising
  - GTMRI: Reconstruction**
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# GTMRI: Reconstruction

- The second main step for the solution of (P1) is the reconstruction step, (P3).

$$(P3) \min_{\mathbf{x}} \frac{1}{2} \|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \frac{\tau}{2\eta} \|\mathcal{R}(\mathbf{x}) - \hat{\mathcal{X}}\|_F^2 + \frac{\nu'}{2\eta} \|\Phi \mathbf{x}\|_1.$$

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- Define patch to image operator  $\hat{\mathcal{R}}$ .
- $\hat{\mathcal{R}}(\hat{\mathcal{X}}) = (\sum_j \mathbf{R}_j^T \hat{\mathbf{x}}_j) ./ \mathbf{w}$ .
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$$(P3') \min_{\mathbf{x}} f(\mathbf{x}) + g(\mathbf{x}).$$

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- We have used the forward-backward splitting algorithm.

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- The forward-backward splitting steps:

$$(P3.1) \quad \mathbf{z} = \mathbf{x} - \gamma \nabla g(\mathbf{x}). \quad (7)$$

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- $\nabla g(\mathbf{x}) = \mathcal{F}_v^H (\mathcal{F}_v \mathbf{x} - \mathbf{y}) + \tau'(\mathbf{x} - \hat{\mathcal{R}}(\hat{\lambda}))$ .
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# GTMRI: Overall Algorithm

- *Input:* Observation,  $y = \mathcal{F}_u x^* + \eta$ ; parameters  $\lambda, \beta, \tau, \tau', \nu, \gamma, \mu$ .
- *Goal:* 
$$\min_{W, \hat{x}, \mathcal{A}, x} \|W\hat{x} - \mathcal{A}\|_F^2 + \lambda Q(W) + \beta \|\mathcal{A}\|_1 + \tau \|\mathcal{R}(x) - \hat{x}\|_F^2 + \eta \|\mathcal{F}_u x - y\|_2^2 + \nu \|\Phi x\|_1$$

- Initialize  $x = \mathcal{F}_u^H y$ .

- Main iteration:

    Initialize  $\hat{x} = \mathcal{R}(x)$ .

    Repeat (P2.1)  $N_1$  times.

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    Initialize  $x = \mathcal{R}(\hat{x})$ .

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$$\min_{\mathbf{W}, \hat{\mathcal{X}}, \mathcal{A}, \mathbf{x}} \|\mathbf{W} \hat{\mathcal{X}} - \mathcal{A}\|_F^2 + \lambda Q(\mathbf{W}) + \beta \|\mathcal{A}\|_1$$

$$+ \tau \|\mathcal{R}(\mathbf{x}) - \hat{\mathcal{X}}\|_F^2 + \eta \|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \nu' \|\Phi \mathbf{x}\|_1$$

- Initialize  $\mathbf{x} = \mathcal{F}_u^H \mathbf{y}$ .

- Main iteration:

- Initialize  $\hat{\mathcal{X}} = \mathcal{R}(\mathbf{x})$ . *denoising starts*
- Iterate (P2.1),  $N_1$  times.
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- Initialize  $\mathbf{x} = \hat{\mathcal{R}}(\hat{\mathcal{X}})$ . *reconstruction starts*
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- Output reconstructed MR image  $\mathbf{x}$ .

# GTLMRI: Overall Algorithm

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# Simulations setting

- We compare the reconstruction performance of G-TLMRI algorithm with TLMRI [Ravishankar and Bresler, 2013], DLMRI [Ravishankar and Bresler, 2011] and FCSA [Huang et.al., 2011].
- Simulations for two MR images of size  $(256 \times 256)$ .
- The downsampling ratio for  $\mathcal{F}_U$  is  $\kappa/256^2 = 0.25$  (4 fold downsampling) with a random sampling mask.

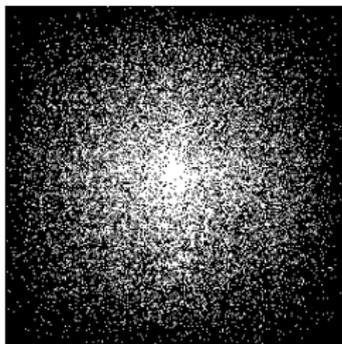
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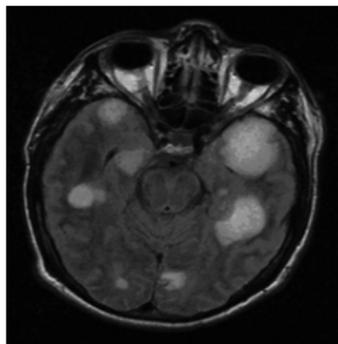
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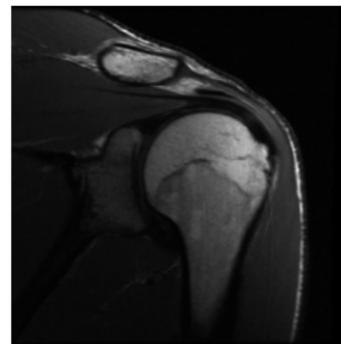
## Simulations: Original images



a)



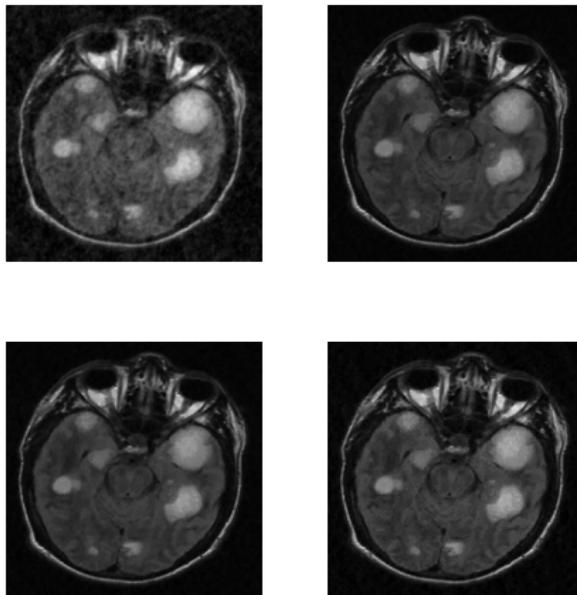
b)



c)

**Figure:** (a) Sampling mask in  $k$ -space with 4-fold undersampling ,  
(b,c) the original MRI test images.

# Simulations: Brain image



**Figure:** Brain image results.

First row: Zero-filling and G-TLMRI. Second row: TLMRI and FCSA.

# Simulations: Brain image

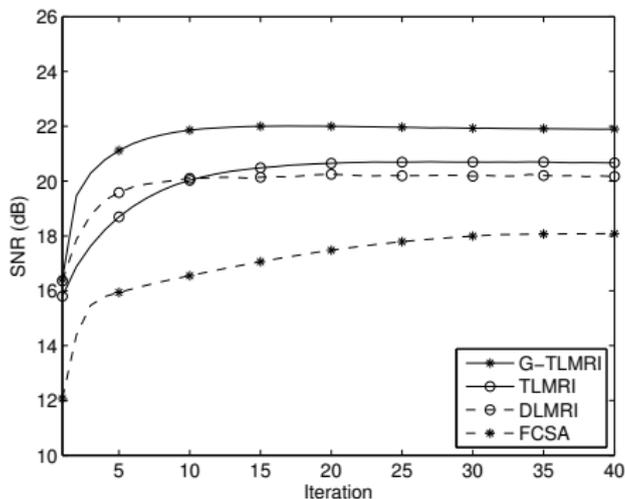


Figure: Brain image results: SNR versus iteration.

# Simulations: Shoulder image

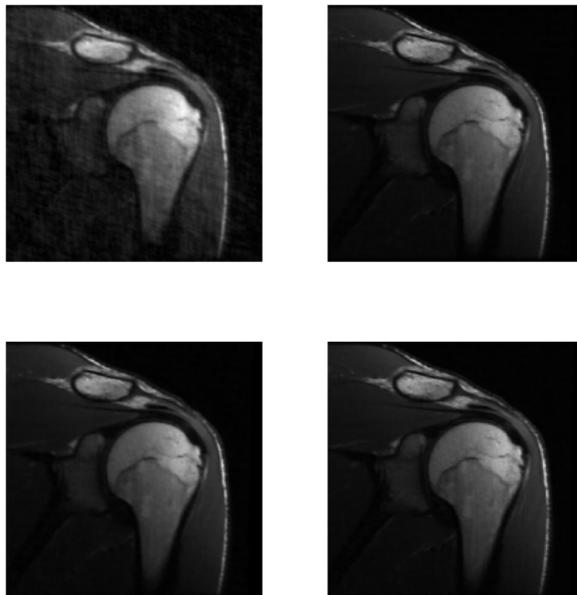


Figure: Shoulder image results.  
First row: Zero-filling and G-TLMRI. Second row: TLMRI and FCSA.

# Simulations: Shoulder image

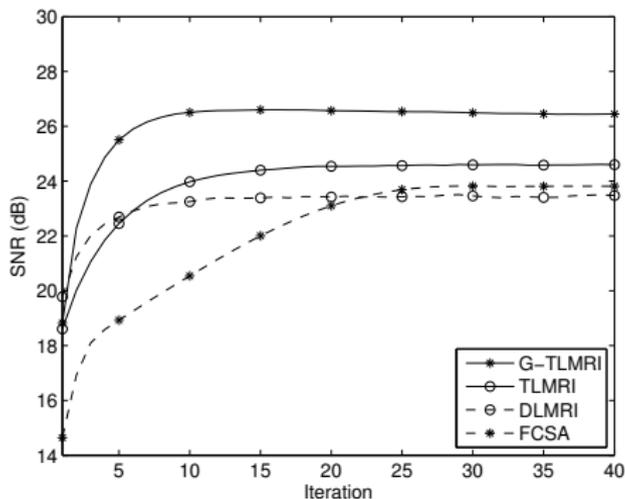


Figure: Shoulder image results: SNR versus iteration.

# Conclusion

- We have presented a new algorithm called as G-TLMRI for MRI reconstruction.
- G-TLMRI algorithm builds upon the patch level sparsification of the TLMRI.
- G-TLMRI introduces a global regularizer into the TLMRI framework.
- Combination of the local and global regularization terms results in reconstruction performance exceeding some competing methods which use these terms alone.

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- Thanks for listening.

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# Sparse MRI

$$\min_{\mathbf{x}} \frac{1}{2} \|\mathcal{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \rho_1 \|\Phi \mathbf{x}\|_1 + \rho_2 \|\mathbf{x}\|_{\text{TV}}.$$

- Several approaches for solving this cost function or its variants.
- In the original Sparse MRI algorithm [Lustig et.al., 2007]: a nonlinear conjugate gradient method
- Operator and variable splitting methods: FCSA, RecPF, TVCMRI ...

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